



EECS 487: Interactive Computer Graphics

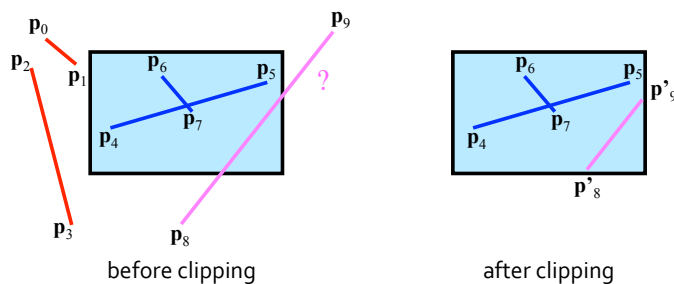
Lecture 5:

- Finish up line rasterization
- Line clipping

Clipping Line Segments

How to clip?

- preprocessing to exclude/include trivial cases
 - accept/reject bitmask test: Cohen-Sutherland
- clip the intersecting cases:
 - parametric line trimming: Cyrus-Beck



Clipping

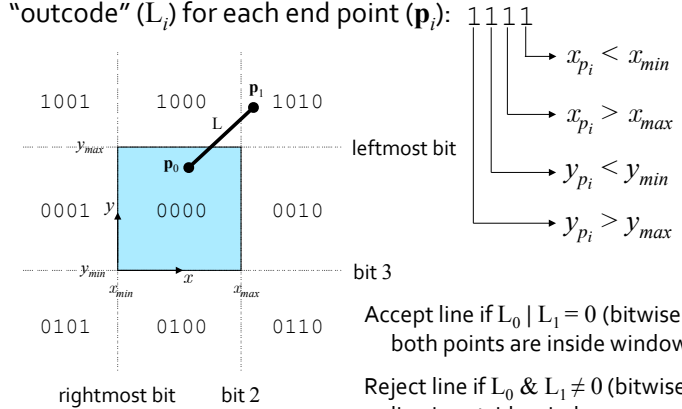
Clip against viewing window/viewport

Why clip?

- avoids rasterizing outside window
 - speeds up rasterization
 - prevents memory errors
 - avoids divide by 0 and overflows
- in 3D, clip against view volume
 - polygons that are too close can obscure view
 - those too far shouldn't be visible and could mess up depth buffer

Cohen-Sutherland

Trivial Accept/Reject test: compute a 4-bit "outcode" (L_i) for each end point (p_i):



- Accept line if $L_0 \mid L_1 = 0$ (bitwise or) both points are inside window
- Reject line if $L_0 \& L_1 \neq 0$ (bitwise and) line is outside window
- Else **may** need clipping

Line Clipping Examples

1111

- $x_{p_i} < x_{min}$
- $x_{p_i} > x_{max}$
- $y_{p_i} < y_{min}$
- $y_{p_i} > y_{max}$

Accept if $L_0 \mid L_1 = 0$
 Reject if $L_0 \& L_1 \neq 0$

A is Rejected

F needs clipping

E is Accepted

H needs clipping?
I needs clipping?

$A_0 = 1001$
 $A_1 = 1000$
 $A_0 \mid A_1 = 1001$
 $A_0 \& A_1 = 1000$

$F_0 = 0000$
 $F_1 = 0100$
 $F_0 \mid F_1 = 0100$
 $F_0 \& F_1 = 0000$

$E_0 = 0000$
 $E_1 = 0000$
 $E_0 \mid E_1 = 0000$

$H_0 = 0100$
 $H_1 = 0010$
 $H_0 \mid H_1 = 0110$
 $H_0 \& H_1 = 0000$

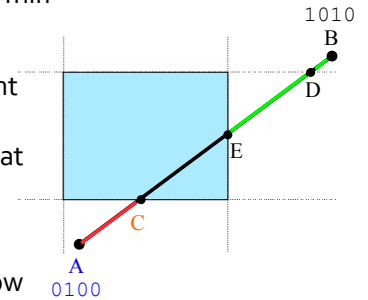
Line Clipping Cohen-Sutherland

Each '1' in the outcode indicates the line intersecting an edge, e.g., 0100 means intersection with y-min

Starting from the **left most outside point** (A in example), going left to right (e.g.,) on the outcode, compute the **intersection** with the window edge that cuts the line into two segments

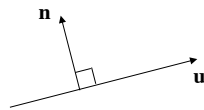
Test the outcodes of each segment, clip the **segment(s) outside** the window

Recurse until all segments are checked



Normal Vectors

What is the **normal vector** of a line?
A vector perpendicular to the line



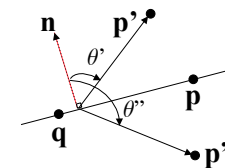
What is a **unit normal**?
Normal vector of magnitude one: $\mathbf{n}/\|\mathbf{n}\|$

Normal vectors are important to many graphics calculations

Implicit Line Eqn. Using Vectors

Let \mathbf{n} be a normal vector of the line and \mathbf{q} a point on the line

- the point \mathbf{p} is on the line iff $f(\mathbf{p}) = \mathbf{n} \cdot (\mathbf{p} - \mathbf{q}) = 0$
- the point \mathbf{p}' is above the line iff $f(\mathbf{p}') > 0$ ($\theta' < 90^\circ$)
- the point \mathbf{p}'' is below the line iff $f(\mathbf{p}'') < 0$ ($\theta'' > 90^\circ$)
- if $f(\mathbf{p}) \neq 0$, \mathbf{p} 's projection onto \mathbf{n} has a non-zero length



θ measured in the direction of travel

Cyrus-Beck Line Clipping

Compute the intersection between line \mathbf{u} and edge i

Let:

- \mathbf{u} the vector from \mathbf{p}_0 to \mathbf{p}_1 : $\mathbf{u} = (\mathbf{p}_1 - \mathbf{p}_0)$
- \mathbf{n}_i be the normal of edge i , pointing away from the clipping window
- \mathbf{p}_{e_i} an arbitrary point on edge i

then:

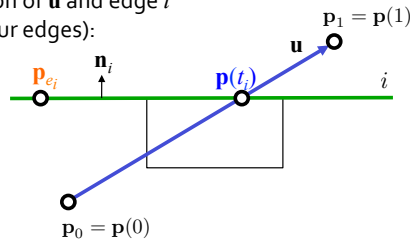
- if $\mathbf{n}_i \cdot \mathbf{u} = 0$ the line is parallel to the edge i
- otherwise, let $\mathbf{p}(t_i)$ be the intersection of \mathbf{u} and edge i
- solve for t_i (repeat for each of the four edges):

$$\mathbf{n}_i \cdot [\mathbf{p}(t_i) - \mathbf{p}_{e_i}] = 0$$

$$\mathbf{n}_i \cdot [\mathbf{p}_0 + t_i(\mathbf{p}_1 - \mathbf{p}_0) - \mathbf{p}_{e_i}] = 0$$

$$\mathbf{n}_i \cdot [\mathbf{p}_0 - \mathbf{p}_{e_i}] + \mathbf{n}_i \cdot t_i \mathbf{u} = 0$$

$$t_i = \frac{\mathbf{n}_i \cdot [\mathbf{p}_0 - \mathbf{p}_{e_i}]}{-\mathbf{n}_i \cdot \mathbf{u}} = \frac{\mathbf{n}_i \cdot [\mathbf{p}_{e_i} - \mathbf{p}_0]}{\mathbf{n}_i \cdot \mathbf{u}}$$



Foley et al.94

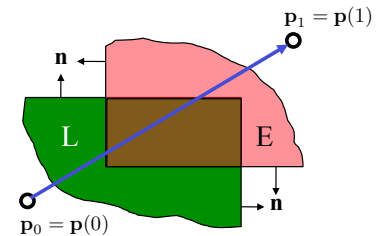
Cyrus-Beck Line Clipping

Let two sides of the clipping window define a region **E**(nter) that the line enters and never leaves

Let the other two sides define a region **L**(eave) that the line starts in and eventually leaves

(Algorithm determines **E** and **L** automatically!)

The dot products of the line and the normal (\mathbf{n}) of the boundary edges determine the parameters (the t 's) at the intersection points



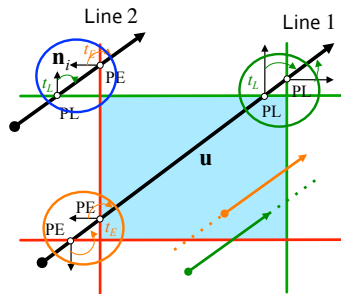
Cyrus-Beck Line Clipping

Now classify each intersection point as Potentially Entering (PE) or Potentially Leaving (PL) at edge i :

- if $\mathbf{n}_i \cdot \mathbf{u} < 0$, intersection is PE (why?)
- if $\mathbf{n}_i \cdot \mathbf{u} > 0$, intersection is PL (why?)

Let t_L be the MIN of the t_i 's that are PL and t_E the MAX of the t_i 's that are PE

- if $t_L < t_E$, the line is outside the clipping window (Line 2)
- otherwise (t_E, t_L) are the clipped line's bounding points
- in case actual line segment starts or ends inside window, $t_E < 0$ or $t_L > 1$ respectively, we let $\max(0, t_E)$ and $\min(1, t_L)$ be the clipped line's bounding points



Foley et al.94

Cyrus-Beck Line Clipping

Whereas Cohen-Sutherland is limited to upright rectangle, Cyrus-Beck works well with arbitrary convex polygon as clipping area

