

CS 318 Principles of Operating Systems

Fall 2020

Lecture 8: Deadlock

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Administrivia

- Lab 1 deadline is this **Sunday noon** (Sept 27th 11:59**am**)
- If you decide to use late hours, please send an email to the staff mailing list following the format *before* the deadline.
- Reminder about cheating

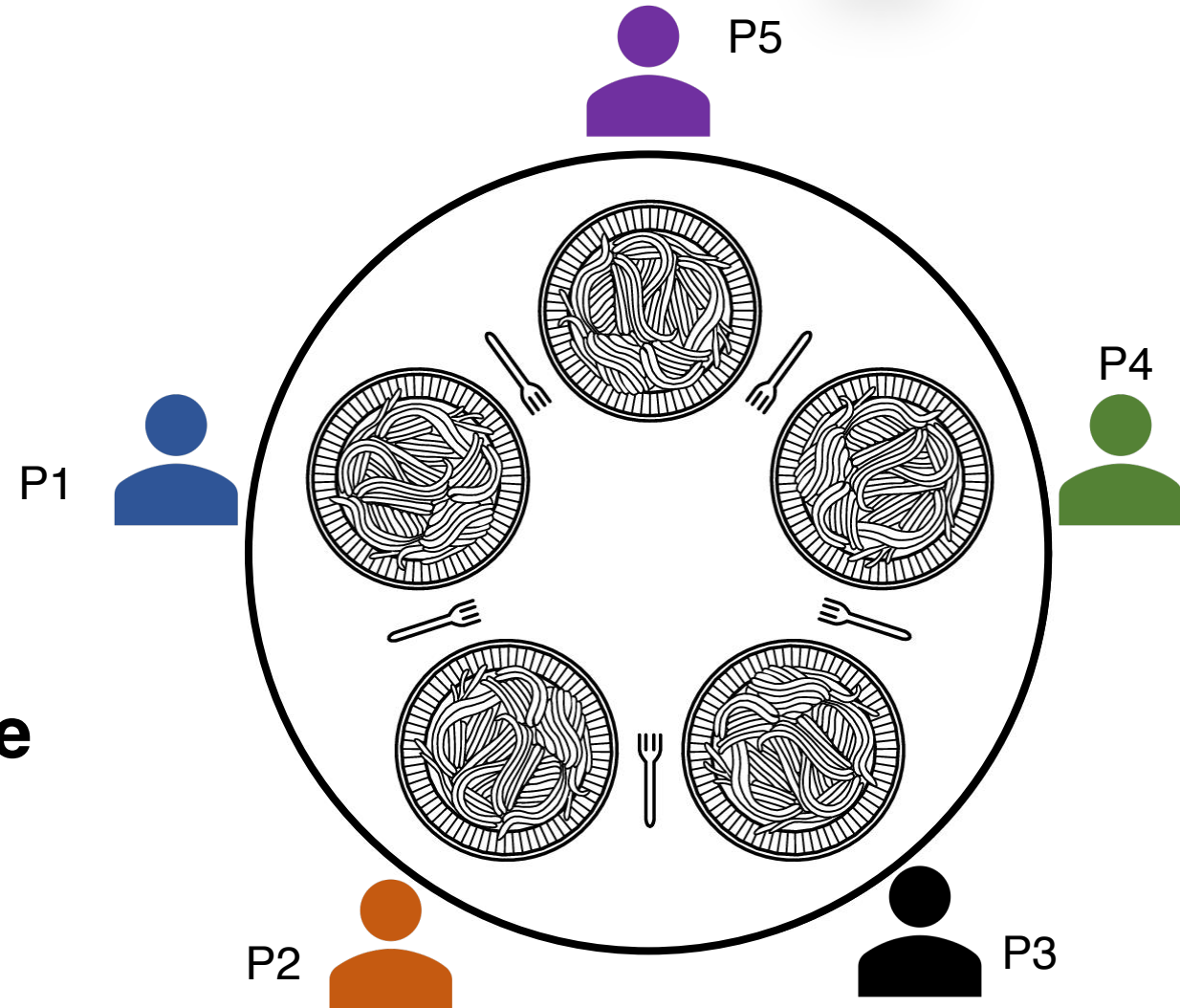
Deadlock

- **Synchronization is a live gun**
 - We can easily shoot ourselves in the foot
 - Incorrect use of synchronization can block all processes
 - You have likely been intuitively avoiding this situation already
- **If one process tries to access a resource that a second process holds, and vice-versa, they can never make progress**
- **We call this situation **deadlock**, and we'll look at:**
 - Definition and conditions necessary for deadlock
 - Representation of deadlock conditions
 - Approaches to dealing with deadlock

Dining Philosophers Problem



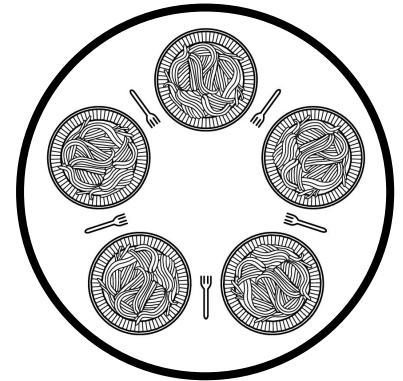
- **Philosophers spend their lives alternating thinking and eating**
- **Don't interact with neighbors, occasionally eat**
 - Need 2 forks to eat
 - Release both when done
- **Can only pick up 1 fork at a time**



Philosophers in Code (1)

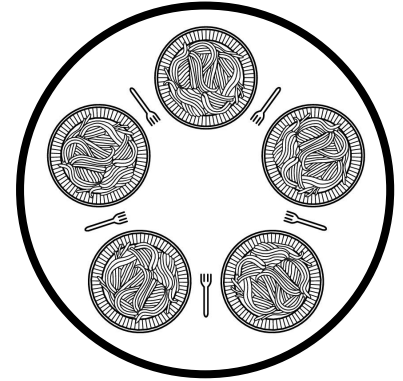
```
#define N 5                                /* number of philosophers */

void philosopher(int i) /* i: philosopher id, 0 to 4 */
{
    while (true) {
        think();                          /* philosopher is thinking */
        take_fork(i);                      /* take left fork */
        take_fork((i + 1) % N);           /* take right fork */
        eat();                             /* yum-yum, spaghetti */
        put_fork(i);                       /* put left fork back on the table */
        put_fork((i + 1) % N);           /* put right fork back on the table */
    }
}
```



Philosophers in Code (2)

```
semaphore forks[N]; /* semaphores for each fork,  
                    each initialized to 1 (omitted) */  
  
void take_fork(int i)  
{  
    forks[i].P();    /* wait for ith fork's semaphore */  
}  
  
void put_fork(int i)  
{  
    forks[i].V();    /* signal ith fork's semaphore */  
}
```



- **What is a problem with this algorithm?**

How to Avoid Deadlock Here?

- **Multiple solutions exist**
- **Simple one: allow at most 4 philosophers to sit simultaneously at the table**
- **Another solution: define a partial order for resources (forks)**
 - Number the forks
 - Philosopher must always pick up lower-numbered fork first and then higher-numbered fork
 - **What happens if four philosophers all pick up their lower-numbered fork?**
 - Disadvantage
 - Not always practical, when the complete list of all resources is not known in advance
- **Third solution: all or none each time**

2nd Attempt to Dining Philosopher Problem

```
#define N 5                                /* number of philosophers */
#define LEFT (i+N-1) % N                   /* i's left neighbor */
#define RIGHT (i+1) % N                    /* i's right neighbor */
enum State {THINKING, HUNGRY, EATING}; /* a philosopher's status */
enum State states[N]; /* keep track of each philosopher's status */
semaphore mutex = 1; /* mutual exclusion for critical section */
semaphore phis[N]; /* semaphore for each philosopher, init to 0 */

void philosopher(int i) /* i: philosopher id, 0 to N-1 */
{
    while (true) {
        think(); /* philosopher is thinking */
        take_forks(i); /* take both forks */
        eat(); /* yum-yum, spaghetti */
        put_forks(i); /* put both forks */
    }
}
```


2nd Attempt to Dining Philosopher Problem

```
void take_forks(int i) /* i: philosopher id, 0 to N-1 */
{
    mutex.P();          /* enter critical section */
    states[i] = HUNGRY; /* indicate philosopher is hungry */
    test(i);            /* try to acquire two forks */
    mutex.V();          /* exit critical section */
    phis[i].P();        /* block if forks not acquired */
}
void put_forks(int i) /* i: philosopher id, 0 to N-1 */
{
    mutex.P();          /* enter critical section */
    states[i] = THINKING; /* indicate i finished eating */
    test(LEFT);         /* see if left neighbor can eat now */
    test(RIGHT);        /* see if right neighbor can eat now */
    mutex.V();          /* exit critical section */
}
```

```
void test(int i) /* i: philosopher id,
                 0 to N-1 */
{
    if (states[i] == HUNGRY &&
        states[LEFT] != EATING &&
        states[RIGHT] != EATING) {
        states[i] = EATING; /* philosopher i
                             can eat now */
        phis[i].V(); /* signal i to proceed */
    }
}
```

Notes for the 2nd Attempt Solution

- **What is the purpose of `states` array?**
 - ...given that already have the semaphore array?
 - A semaphore doesn't have operations for checking its value!
- **What if we don't use the `mutex` semaphore?**
- **Why the semaphore array is for each philosopher?**
 - Our first attempt uses semaphore array for each fork
- **What if we put `phis[i].P()`; inside the critical section?**
- **What if we don't call the two `test` in `put_forks`?**

Deadlock Definition

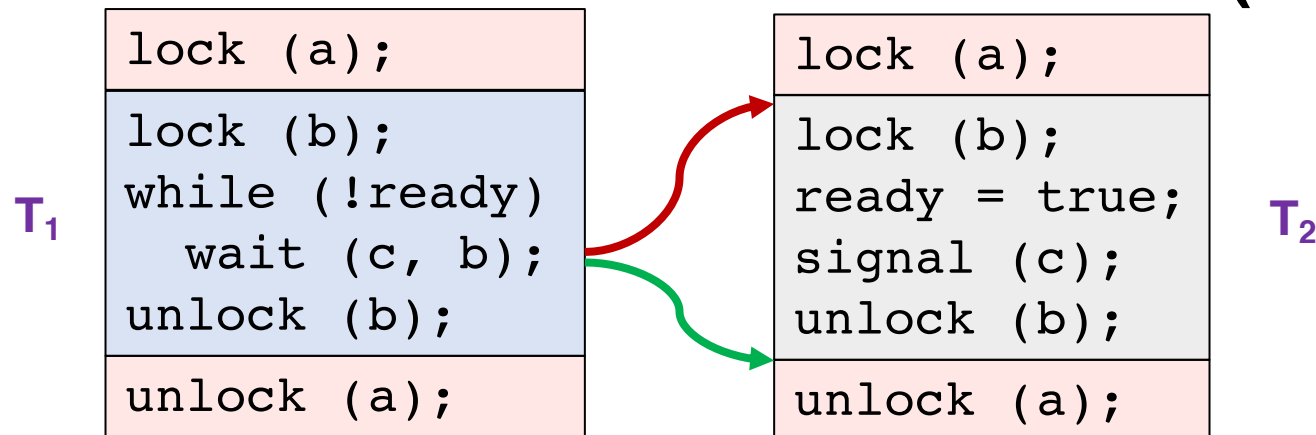
- **Deadlock is a problem that can arise:**
 - When processes compete for access to limited resources
 - When processes are incorrectly synchronized
- **Definition:**
 - Deadlock exists among a set of processes if every process is waiting for an event that can be caused only by another process in the set.

Deadlock Example

```
mutex_t m1, m2;
void p1(void *ignored) {
    lock(m1);
    → lock(m2);
    /* critical section */
    unlock(m2);
    unlock(m1);
}
void p2(void *ignored) {
    lock(m2);
    → lock(m1);
    /* critical section */
    unlock(m1);
    unlock(m2);
}
```

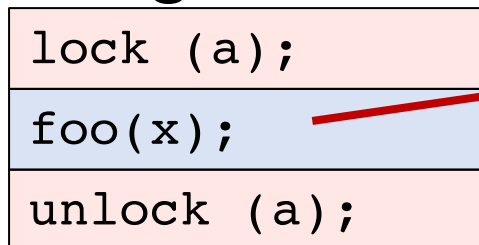
Deadlock Example

- **Can you have deadlock w/o mutexes?**
- **Same problem with condition variables**
 - Suppose resource 1 managed by c_1 , resource 2 by c_2
 - A has 1, waits on c_2 , B has 2, waits on c_1
- **Or w/ combined mutex/condition variable (tricky)**



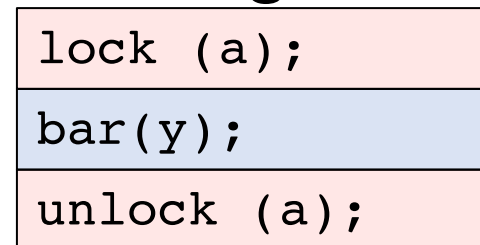
Deadlock Example

- **Can you have deadlock w/o mutexes?**
- **Same problem with condition variables**
 - Suppose resource 1 managed by c_1 , resource 2 by c_2
 - A has 1, waits on c_2 , B has 2, waits on c_1
- **Or with combined mutex/condition variable (tricky)**
 - `lock (a); lock (b); while (!ready) wait (c, b); unlock (b); unlock (a);`
 - `lock (a); lock (b); ready = true; signal (c); unlock (b); unlock (a);`
- **Lesson: dangerous to hold locks when crossing boundaries!**

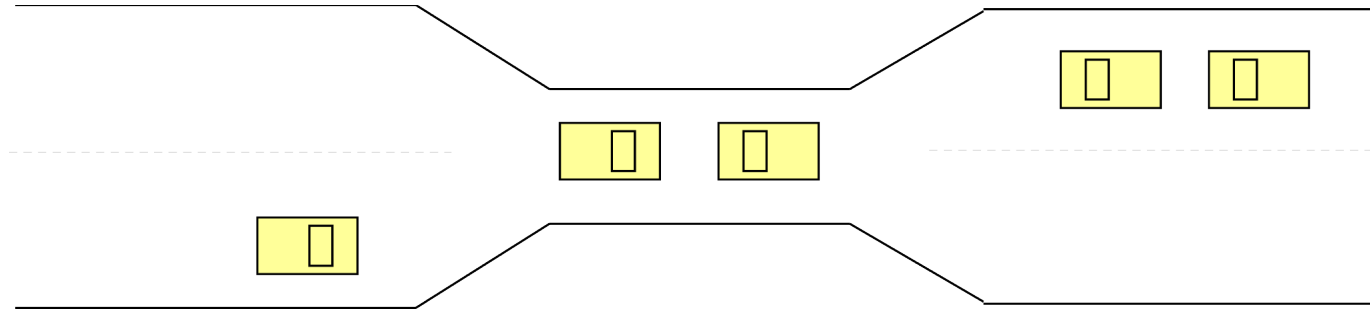


internally uses
condition variables

CS 318 – Lecture 8 – Deadlock



Deadlocks w/o Computers



- **Real issue is *resources* & how required**
- **E.g., bridge only allows traffic in one direction**
 - Each section of a bridge can be viewed as a resource.
 - If a deadlock occurs, it can be resolved if one car backs up (preempt resources and rollback).
 - Several cars may have to be backed up if a deadlock occurs.
 - Starvation is possible.

Conditions for Deadlock

1. **Mutual exclusion** – At least one resource must be held in a non-sharable mode
 2. **Hold and wait** – There must be one process holding one resource and waiting for another resource
 3. **No preemption** – Resources cannot be preempted (critical sections cannot be aborted externally)
 4. **Circular wait** – There must exist a set of processes $[P_1, P_2, P_3, \dots, P_n]$ such that P_1 is waiting for P_2 , P_2 for P_3 , etc.
- **All of 1–4 necessary for deadlock to occur**
 - **Two approaches to dealing with deadlock:**
 - Pro-active: prevention
 - Reactive: detection + corrective action

Prevent by Eliminating One Condition

1. Mutual exclusion

- Buy more resources, split into pieces, or virtualize to make "infinite" copies
- Threads: threads have copy of registers = no lock

2. Hold and wait

- Wait on all resources at once (must know in advance)

3. No preemption

- Physical memory: virtualized with VM, can take physical page away and give to another process!

4. Circular wait

- Single lock for entire system: (problems?)
- Partial ordering of resources (next)

Resource Allocation Graph

- **View system as graph**
 - Processes and Resources are nodes
 - Resource Requests and Assignments are edges

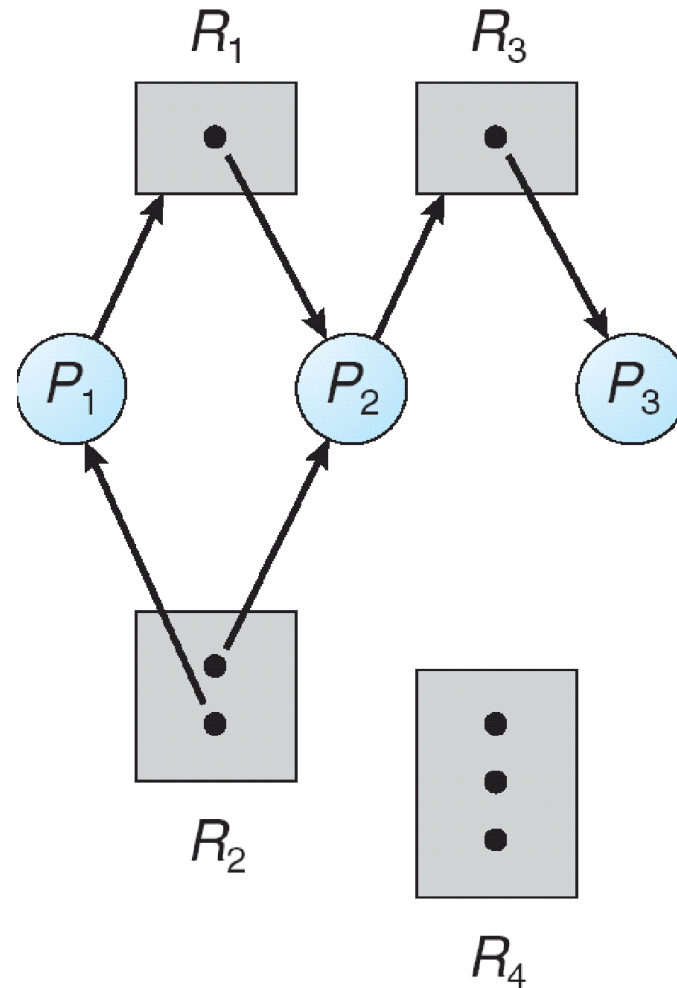
• **Process:** 

• **Resource with 4 instances:** 

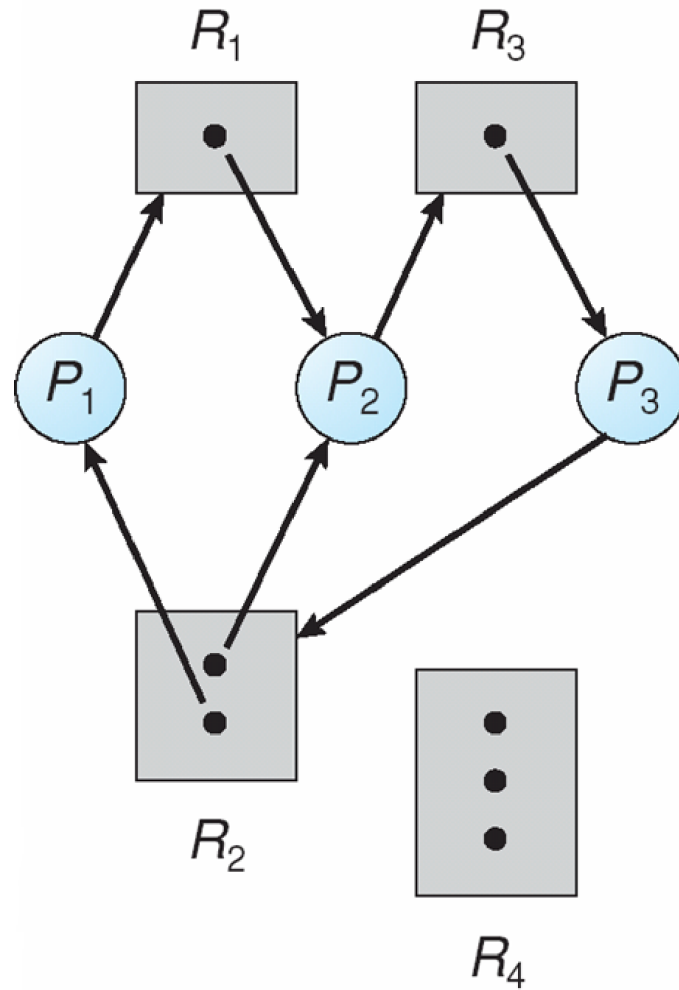
• P_i requesting R_j : 

• P_i holding instance of R_j : 

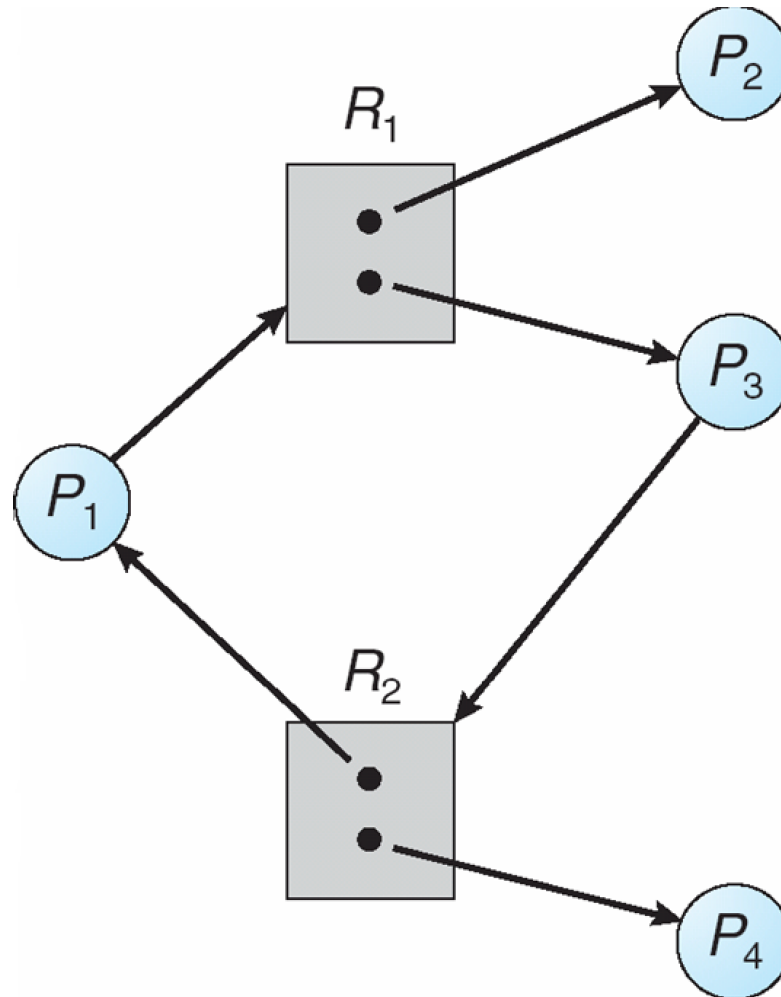
Example Resource Allocation Graph



Resource Allocation Graph with Deadlock



Is This Deadlock?



Cycles and Deadlock

- **If graph has no cycles \Rightarrow no deadlock**
- **If graph contains a cycle**
 - Definitely deadlock if only one instance per resource ([waits-for graph \(WFG\)](#))
 - Otherwise, [maybe](#) deadlock, maybe not
- **Prevent deadlock with partial order on resources**
 - e.g., always acquire mutex m_1 before m_2
 - Usually design locking discipline for application this way

Dealing With Deadlock

- **There are four approaches for dealing with deadlock:**
 - **Ignore it** – how lucky do you feel?
 - **Prevention** – make it impossible for deadlock to happen
 - **Avoidance** – control allocation of resources
 - **Detection and Recovery** – look for a cycle in dependencies

Deadlock Avoidance

- **Avoidance**

- Provide information in advance about what resources will be needed by processes to guarantee that deadlock will not happen
- System only grants resource requests if it knows that the process can obtain all resources it needs in future requests
- Avoids circularities (wait dependencies)

- **Tough**

- Hard to determine all resources needed in advance
- Good theoretical problem, not as practical to use

Banker's Algorithm

- **The Banker's Algorithm is the classic approach to deadlock avoidance for resources with multiple units**
 - 1. Assign a **credit limit** to each customer (process)**
 - Maximum credit claim must be stated in advance
 - 2. Reject any request that leads to a **dangerous state****
 - A dangerous state is one where a sudden request by any customer for the full credit limit could lead to deadlock
 - A recursive reduction procedure recognizes dangerous states
 - 3. In practice, the system must keep resource usage well below capacity to maintain a **resource surplus****
 - Rarely used in practice due to low resource utilization

Detection and Recovery

- **Detection and recovery**
 - If we don't have deadlock prevention or avoidance, then deadlock may occur
 - In this case, we need to detect deadlock and recover from it
- **To do this, we need two algorithms**
 - One to determine whether a deadlock has occurred
 - Another to recover from the deadlock
- **Possible, but expensive (time consuming)**
 - Implemented in VMS
 - Run detection algorithm when resource request times out

Deadlock Detection

- **Detection**
 - Traverse the resource graph looking for cycles
 - If a cycle is found, preempt resource (force a process to release)
- **Expensive**
 - Many processes and resources to traverse
- **Only invoke detection algorithm depending on**
 - How often or likely deadlock is
 - How many processes are likely to be affected when it occurs

Deadlock Recovery

Once a deadlock is detected, we have two options...

1. Abort processes

- Abort all deadlocked processes
 - Processes need to start over again
- Abort one process at a time until cycle is eliminated
 - System needs to rerun detection after each abort

2. Preempt resources (force their release)

- Need to select process and resource to preempt
- Need to rollback process to previous state
- Need to prevent starvation

Deadlock Summary

- **Deadlock occurs when processes are waiting on each other and cannot make progress**
 - Cycles in Resource Allocation Graph (RAG)
- **Deadlock requires four conditions**
 - Mutual exclusion, hold and wait, no resource preemption, circular wait
- **Four approaches to dealing with deadlock:**
 - **Ignore it** – Living life on the edge
 - **Prevention** – Make one of the four conditions impossible
 - **Avoidance** – Banker's Algorithm (control allocation)
 - **Detection and Recovery** – Look for a cycle, preempt or abort

Next time...

- **Read Chapter 15, 16, 18**