

CS 318 Principles of Operating Systems

Fall 2019

Lecture 8: Deadlock

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Administrivia

- **Lab 1 deadline extended to **Sunday noon** (Sept 29th 11:59am)**
 - Accommodate the fact the lecture is a bit behind
 - Don't expect that future lab ddls would be extended
 - Try to finish the coding before the weekend
- **If you decide to use late hours, please send an email following the instruction *before* the deadline.**

Deadlock

- **Synchronization is a live gun**
 - We can easily shoot ourselves in the foot
 - Incorrect use of synchronization can block all processes
 - You have likely been intuitively avoiding this situation already
- **If one process tries to access a resource that a second process holds, and vice-versa, they can never make progress**
- **We call this situation **deadlock**, and we'll look at:**
 - Definition and conditions necessary for deadlock
 - Representation of deadlock conditions
 - Approaches to dealing with deadlock

Deadlock Definition

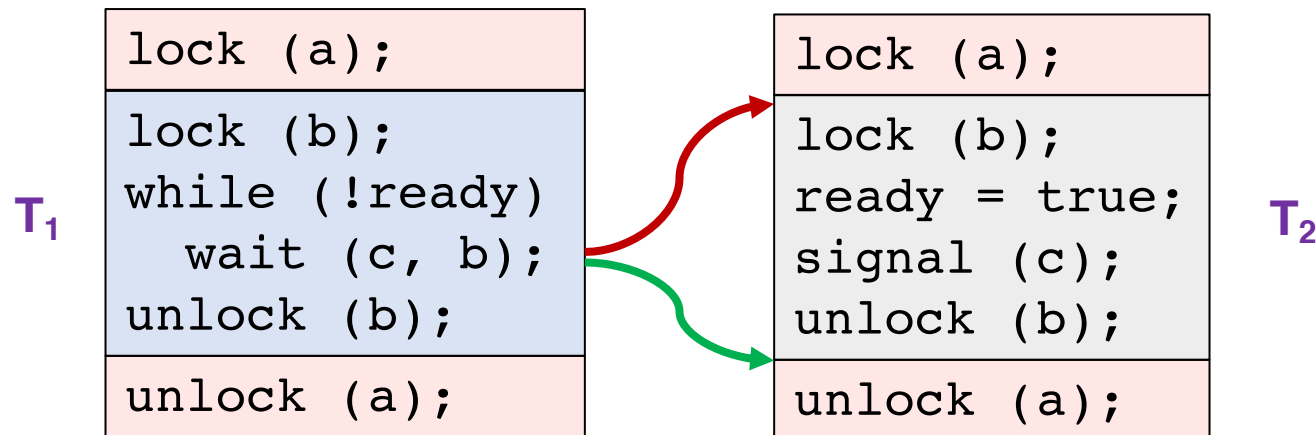
- **Deadlock is a problem that can arise:**
 - When processes compete for access to limited resources
 - When processes are incorrectly synchronized
- **Definition:**
 - Deadlock exists among a set of processes if every process is waiting for an event that can be caused only by another process in the set.

Deadlock Example

```
mutex_t m1, m2;
void p1(void *ignored) {
    lock(m1);
    → lock(m2);
    /* critical section */
    unlock(m2);
    unlock(m1);
}
void p2(void *ignored) {
    → lock(m2);
    lock(m1);
    /* critical section */
    unlock(m1);
    unlock(m2);
}
```

Deadlock Example

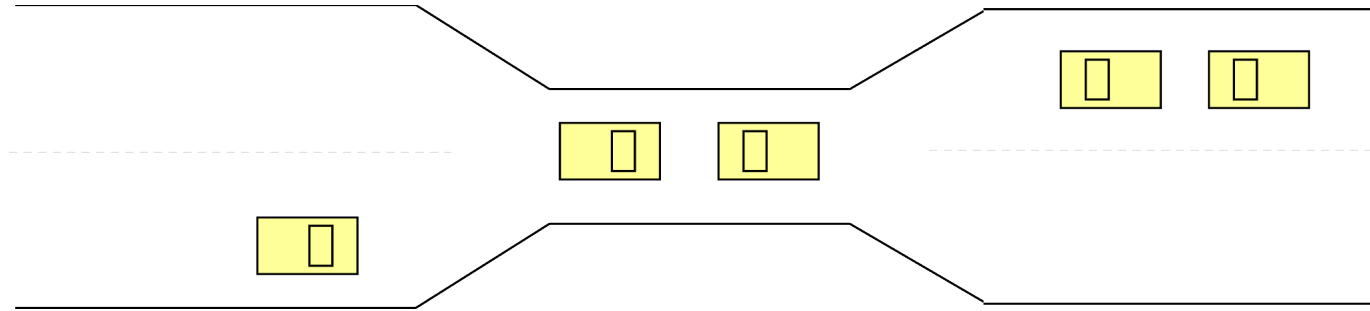
- **Can you have deadlock w/o mutexes?**
- **Same problem with condition variables**
 - Suppose resource 1 managed by c_1 , resource 2 by c_2
 - A has 1, waits on c_2 , B has 2, waits on c_1
- **Or have combined mutex/condition variable deadlock:**



Deadlock Example

- **Can you have deadlock w/o mutexes?**
- **Same problem with condition variables**
 - Suppose resource 1 managed by c_1 , resource 2 by c_2
 - A has 1, waits on c_2 , B has 2, waits on c_1
- **Or have combined mutex/condition variable deadlock:**
 - `lock (a); lock (b); while (!ready) wait (c, b); unlock (b); unlock (a);`
 - `lock (a); lock (b); ready = true; signal (c); unlock (b); unlock (a);`
- **One lesson: dangerous to hold locks when crossing abstraction barriers!**
 - i.e., lock (a) then call function that uses condition variable

Deadlocks w/o Computers



- **Real issue is *resources* & how required**
- **E.g., bridge only allows traffic in one direction**
 - Each section of a bridge can be viewed as a resource.
 - If a deadlock occurs, it can be resolved if one car backs up (preempt resources and rollback).
 - Several cars may have to be backed up if a deadlock occurs.
 - Starvation is possible.

Conditions for Deadlock

1. **Mutual exclusion** – At least one resource must be held in a non-sharable mode
 2. **Hold and wait** – There must be one process holding one resource and waiting for another resource
 3. **No preemption** – Resources cannot be preempted (critical sections cannot be aborted externally)
 4. **Circular wait** – There must exist a set of processes $[P_1, P_2, P_3, \dots, P_n]$ such that P_1 is waiting for P_2 , P_2 for P_3 , etc.
- **All of 1–4 necessary for deadlock to occur**
 - **Two approaches to dealing with deadlock:**
 - Pro-active: prevention
 - Reactive: detection + corrective action

Prevent by Eliminating One Condition

1. Mutual exclusion

- Buy more resources, split into pieces, or virtualize to make "infinite" copies
- Threads: threads have copy of registers = no lock

2. Hold and wait

- Wait on all resources at once (must know in advance)

3. No preemption

- Physical memory: virtualized with VM, can take physical page away and give to another process!

4. Circular wait

- Single lock for entire system: (problems?)
- Partial ordering of resources (next)

Resource Allocation Graph

- **View system as graph**
 - Processes and Resources are nodes
 - Resource Requests and Assignments are edges

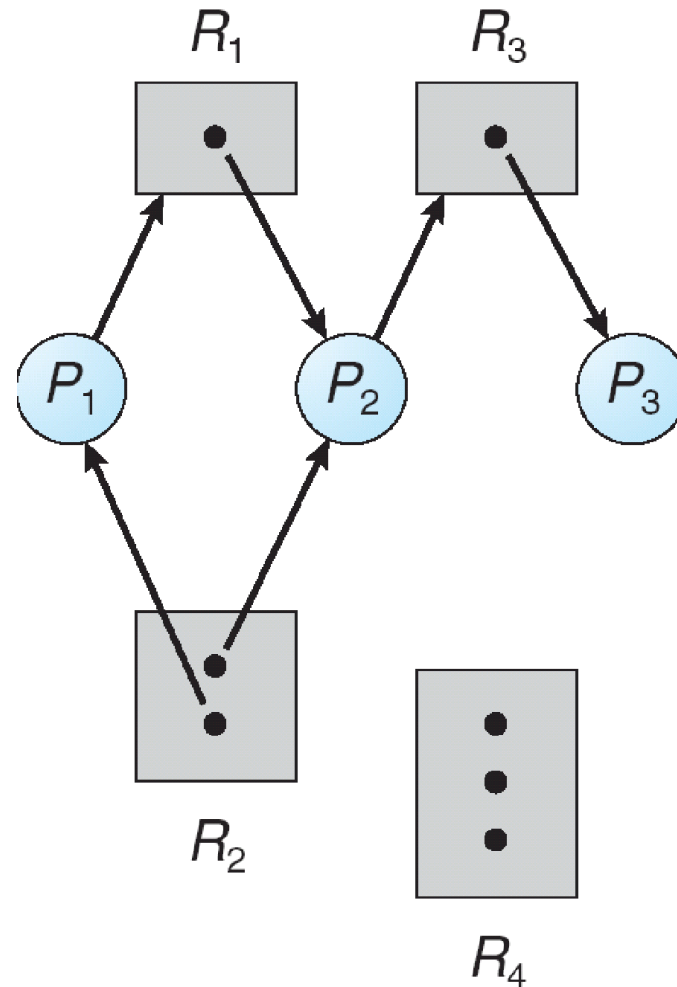
• **Process:** 

• **Resource with 4 instances:** 

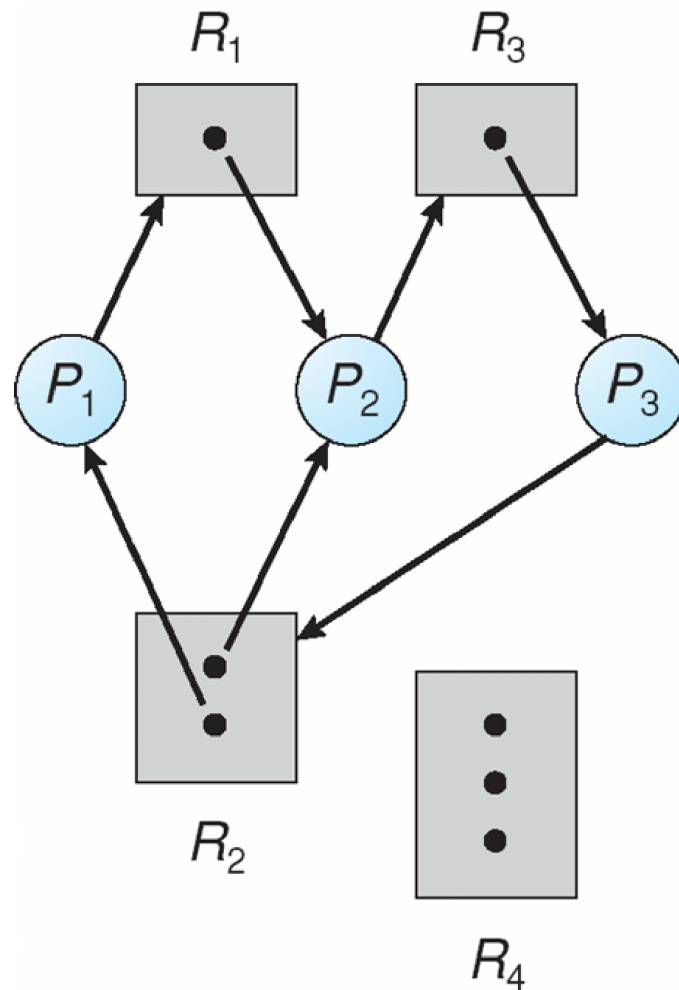
• P_i requesting R_j : 

• P_i holding instance of R_j : 

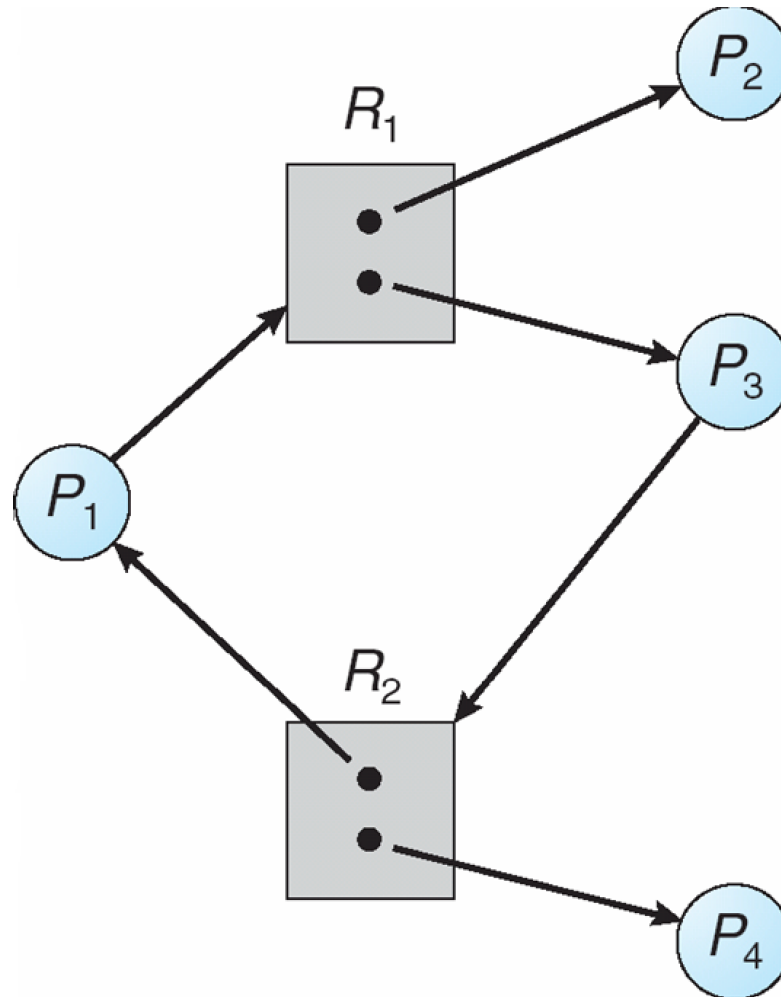
Example Resource Allocation Graph



Resource Allocation Graph with Deadlock



Is This Deadlock?



Cycles and Deadlock

- **If graph has no cycles \Rightarrow no deadlock**
- **If graph contains a cycle**
 - Definitely deadlock if only one instance per resource ([waits-for graph \(WFG\)](#))
 - Otherwise, [maybe](#) deadlock, maybe not
- **Prevent deadlock with partial order on resources**
 - e.g., always acquire mutex m_1 before m_2
 - Usually design locking discipline for application this way

Dealing With Deadlock

- **There are four approaches for dealing with deadlock:**
 - **Ignore it** – how lucky do you feel?
 - **Prevention** – make it impossible for deadlock to happen
 - **Avoidance** – control allocation of resources
 - **Detection and Recovery** – look for a cycle in dependencies

Deadlock Avoidance

- **Avoidance**

- Provide information in advance about what resources will be needed by processes to guarantee that deadlock will not happen
- System only grants resource requests if it knows that the process can obtain all resources it needs in future requests
- Avoids circularities (wait dependencies)

- **Tough**

- Hard to determine all resources needed in advance
- Good theoretical problem, not as practical to use

Banker's Algorithm

- **The Banker's Algorithm is the classic approach to deadlock avoidance for resources with multiple units**
 - 1. Assign a **credit limit** to each customer (process)**
 - Maximum credit claim must be stated in advance
 - 2. Reject any request that leads to a **dangerous state****
 - A dangerous state is one where a sudden request by any customer for the full credit limit could lead to deadlock
 - A recursive reduction procedure recognizes dangerous states
 - 3. In practice, the system must keep resource usage well below capacity to maintain a **resource surplus****
 - Rarely used in practice due to low resource utilization

Detection and Recovery

- **Detection and recovery**
 - If we don't have deadlock prevention or avoidance, then deadlock may occur
 - In this case, we need to detect deadlock and recover from it
- **To do this, we need two algorithms**
 - One to determine whether a deadlock has occurred
 - Another to recover from the deadlock
- **Possible, but expensive (time consuming)**
 - Implemented in VMS
 - Run detection algorithm when resource request times out

Deadlock Detection

- **Detection**
 - Traverse the resource graph looking for cycles
 - If a cycle is found, preempt resource (force a process to release)
- **Expensive**
 - Many processes and resources to traverse
- **Only invoke detection algorithm depending on**
 - How often or likely deadlock is
 - How many processes are likely to be affected when it occurs

Deadlock Recovery

Once a deadlock is detected, we have two options...

1. Abort processes

- Abort all deadlocked processes
 - Processes need to start over again
- Abort one process at a time until cycle is eliminated
 - System needs to rerun detection after each abort

2. Preempt resources (force their release)

- Need to select process and resource to preempt
- Need to rollback process to previous state
- Need to prevent starvation

Deadlock Summary

- **Deadlock occurs when processes are waiting on each other and cannot make progress**
 - Cycles in Resource Allocation Graph (RAG)
- **Deadlock requires four conditions**
 - Mutual exclusion, hold and wait, no resource preemption, circular wait
- **Four approaches to dealing with deadlock:**
 - **Ignore it** – Living life on the edge
 - **Prevention** – Make one of the four conditions impossible
 - **Avoidance** – Banker's Algorithm (control allocation)
 - **Detection and Recovery** – Look for a cycle, preempt or abort

Next time...

- **Read Chapter 15, 16, 18**