CS 318 Principles of Operating Systems

Fall 2019

Lecture 4: Scheduling

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Administrivia

• Lab 0

- Due today
- Submit in Blackboard

Lab 1 released

- Due in two weeks
- Lab overview session next week
- If you still don't have a group, let us know soon
- GitHub classroom invitation link on Piazza post

Recap: Processes

The process is the OS abstraction for execution

- own view of machine

Process components

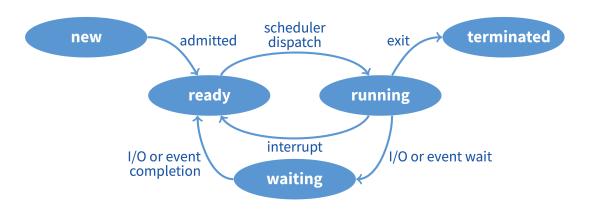
- address space, program counter, registers, open files, etc.
- kernel data structure: Process Control Block (PCB)

Process states and APIs

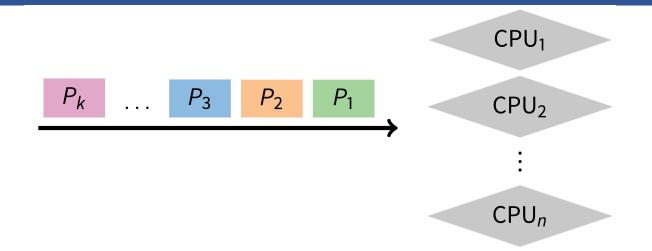
- state graph and queues
- process creation, deletion, waiting

Multiple processes

- overlapping I/O and CPU activities
- context switch



Scheduling Overview



• The scheduling problem:

- Have *K* jobs ready to run
- Have $N \ge 1$ CPUs

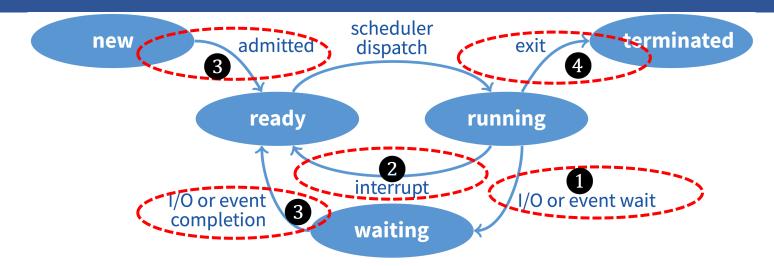
• Policy: which jobs should we assign to which CPU(s), for how long?

- we'll refer to schedulable entities as jobs could be processes, threads, people, etc.
- Mechanism: context switch, process state queues

Scheduling Overview

- 1. Goals of scheduling
- 2. Textbook scheduling
- **3.** Priority scheduling
- 4. Advanced scheduling topics

When Do We Schedule CPU?



Scheduling decisions may take place when a process:

Switches from running to waiting state
Switches from running to ready state
Switches from new/waiting to ready
Exits

Non-preemptive schedules use ① & ④ only

• Preemptive schedulers run at all four points

Scheduling Goals

Scheduling works at two levels in an operating system

- To determine the multiprogramming level # of jobs loaded into memory
 - Moving jobs to/from memory is often called swapping
- To decide what job to run next to guarantee "good service"
 - Good service could be one of many different criteria

Known as long-term and short-term scheduling decisions

- Long-term scheduling happens relatively infrequently
 - Significant overhead in swapping a process out to disk
- Short-term scheduling happens relatively frequently
 - · Want to minimize the overhead of scheduling
 - Fast context switches, fast queue manipulation

Scheduling "Non-goal": Starvation

- Starvation is when a process is prevented from making progress because some other process has the resource it requires
 - Resource could be the CPU, or a lock (recall readers/writers)

Starvation usually a side effect of the sched. algorithm

- A high priority process always prevents a low priority process from running
- One thread always beats another when acquiring a lock

Starvation can be a side effect of synchronization

- Constant supply of readers always blocks out writers

Scheduling Criteria

• Why do we care?

- How do we measure the effectiveness of a scheduling algorithm?

Scheduling Criteria

Throughput – # of processes that complete per unit time

- (# jobs/time)
- Higher is better

Turnaround time – time for each process to complete

- $(T_{finish} T_{start})$
- Lower is better

Response time – time from request to *first* response

- $(T_{response} T_{request})$ i.e., , time between *waiting* \rightarrow *ready* transition and *ready* \rightarrow *running*
 - e.g., key press to echo, not launch to exit
- Lower is better

Above criteria are affected by secondary criteria

- *CPU utilization* %CPU fraction of time CPU doing productive work
- Waiting time Avg(T_{wait}) time each process waits in the ready queue

What Criterial Should We Use?

Batch systems

- Strive for job throughput, turnaround time (supercomputers)

Interactive systems

- Strive to minimize response time for interactive jobs (PC)
 - Utilization and throughput are often traded off for better response time

Usually optimize average measure

- Sometimes also optimize for min/max or variance
 - e.g., minimize the maximum response time
 - e.g., users prefer predictable response time over faster but highly variable response time

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Example: FCFS Scheduling

• Run jobs in order that they arrive

- Called "First-come first-served" (FCFS)
- E.g., Say P_1 needs 24 sec, while P_2 and P_3 need 3.
- Say P₂, P₃ arrived immediately after P₁, get:



- Throughput: 3 jobs / 30 sec = 0.1 jobs/sec
- Turnaround Time: $P_1 : 24, P_2 : 27, P_3 : 30$
 - Average TT: (24 + 27 + 30) / 3 = 27
- Waiting Time: P₁ : 0, P₂ : 24, P₃ : 27
 - Average WT: (0 + 24 + 27) / 3 = 17
- Can we do better?

FCFS Continued

• Suppose we scheduled P₂, P₃, then P₁

- Would get:

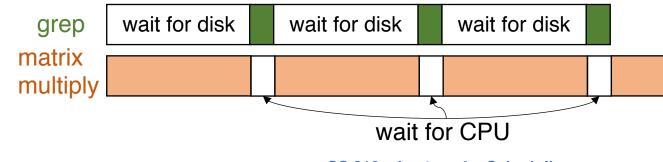


- Throughput: 3 jobs / 30 sec = 0.1 jobs/sec
- Turnaround Time: $P_1 : 30, P_2 : 3, P_3 : 6$
 - Average TT: (30 + 3 + 6) / 3 = 13 much less than 27
- Lesson: scheduling algorithm can reduce TT
 - Minimizing waiting time can improve RT and TT
- Can a scheduling algorithm improve throughput?
 - Yes, if jobs require both computation and I/O

View CPU and I/O devices the same

CPU is one of several devices needed by users' jobs

- CPU runs compute jobs, Disk drive runs disk jobs, etc.
- With network, part of job may run on remote CPU
- Scheduling 1-CPU system with n I/O devices like scheduling asymmetric (n+1)-CPU multiprocessor
 - Result: all I/O devices + CPU busy \rightarrow (n + 1)-fold throughput gain!
- Example: disk-bound grep + CPU-bound matrix_multiply
 - Overlap them just right, throughput will be almost doubled



Bursts of Computation & I/O

Jobs contain I/O and computation

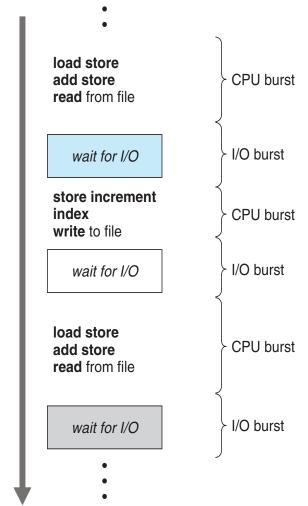
- Bursts of computation
- Then must wait for I/O

Goal: maximize throughput

- maximize both CPU and I/O device utilization

• How?

Overlap computation from one job with I/O from other jobs



FCFS Convoy Effect

CPU-bound jobs will hold CPU until exit or I/O

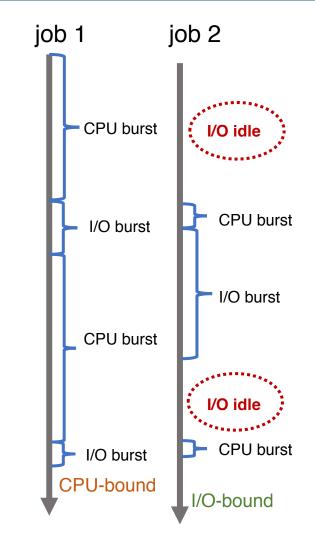
- But I/O burst for CPU-bound job is small
- Long periods where no I/O requests issued, and CPU held
- Result: poor I/O device utilization

Example: one CPU-bound job, many I/O bound

- 1. CPU-bound job runs (I/O devices idle)
- 2. Eventually, CPU-bound job blocks on I/O
- 3. I/O-bound jobs run, but each quickly blocks on I/O
- 4. CPU-bound job unblocks, runs again
- 5. All I/O requests complete, but CPU-bound job still hogs CPU
- 6. I/O devices sit idle since I/O-bound jobs can't issue next requests

Simple hack: run process whose I/O completed

- What is a potential problem?
 - I/O-bound jobs can starve CPU-bound one



FCFS Convoy Effect

The Convoy Effect, visualized

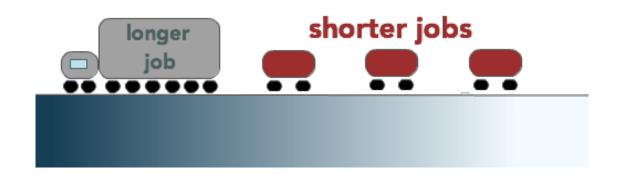


image source: http://web.cs.ucla.edu/classes/fall14/cs111/scribe/7a/convoy_effect.png

CS 318 – Lecture 4 – Scheduling

FCFS Convoy Effect



Shortest Job First (SJF)

Shortest Job First (SJF)

- Choose the job with the smallest expected CPU burst
 - Person with smallest number of items to buy
- Provably optimal minimum average *waiting* time (AWT)



Shortest Job First (SJF)

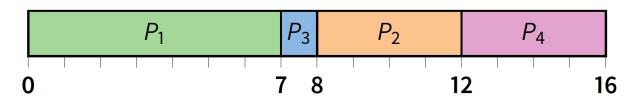
Two schemes

- Non-preemptive once CPU given to the process it cannot be preempted until completes its CPU burst
- Preemptive if a new process arrives with CPU burst length less than remaining time of current executing process, preempt current process
 - Known as the *Shortest-Remaining-Time-First* or *SRTF*

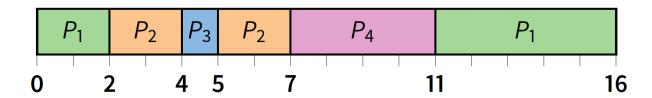
Examples

Arrival Time	Burst Time
0	7
2	4
4	1
5	4
	0

Non-preemptive



Preemptive



What is the AWT?

SJF Limitations

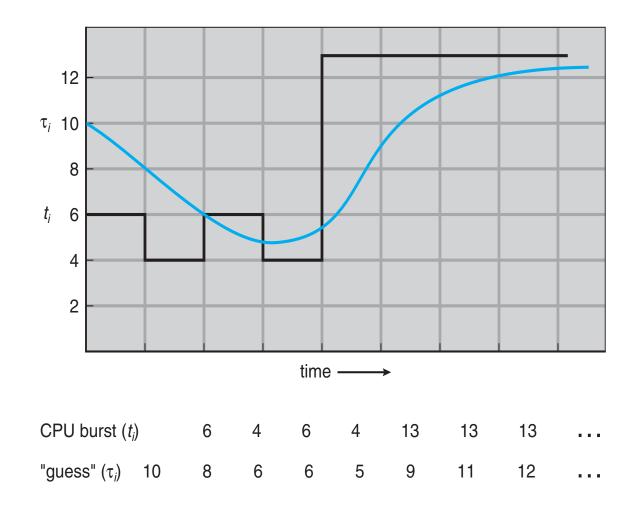
Doesn't always minimize average TT

- Only minimizes waiting time
- Example where turnaround time might be suboptimal?
- Can potentially lead to unfairness or starvation
- Impossible to know size of CPU burst ahead of time
 - Like choosing person in line without looking inside basket/cart

How can you make a reasonable guess?

- Estimate CPU burst length based on past
- E.g., exponentially weighted average
 - t_n actual length of process's n^{th} CPU burst
 - τ_{n+1} estimated length of proc's $(n+1)^{st}$ CPU burst
 - Choose parameter α where $0 < \alpha \leq 1$, e.g., $\alpha = 0.5$
 - Let $\tau_{n+1} = \alpha t_n + (1 \alpha) \tau_n$

Exp. Weighted Average Example



Round Robin (RR)



Solution to fairness and starvation

- Each job is given a time slice called a quantum
- Preempt job after duration of quantum
- When preempted, move to back of FIFO queue

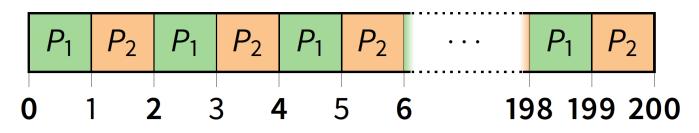
• Advantages:

- Fair allocation of CPU across jobs
- Low average waiting time when job lengths vary
- Good for responsiveness if small number of jobs

Disadvantages?

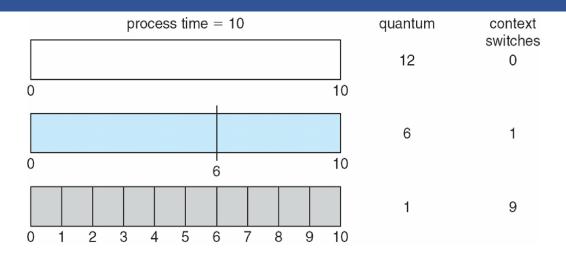
RR Disadvantages

- Context switches are frequent and need to be very fast
- Varying sized jobs are good ...what about same-sized jobs?
- Assume 2 jobs of time=100 each:



- Even if context switches were free...
 - What would average turnaround time be with RR?
 - How does that compare to FCFS?

Time Quantum



• How to pick quantum?

- Want much larger than context switch cost
- Majority of bursts should be less than quantum
- But not so large system reverts to FCFS

• Typical values: 1–100 msec

Scheduling Overview

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Priority Scheduling

Priority Scheduling

- Associate a numeric priority with each process
 - E.g., smaller number means higher priority (Unix/BSD)
 - Or smaller number means lower priority (Pintos)
- Give CPU to the process with highest priority
 - Airline check-in for first class passengers
 - Can be done preemptively or non-preemptively
- Can implement SJF, priority = 1/(expected CPU burst)

Problem: starvation – low priority jobs can wait indefinitely

Solution?

- "Age" processes
 - Increase priority as a function of waiting time
 - Decrease priority as a function of CPU consumption

Combining Algorithms

Different types of jobs have different preferences

- Interactive, CPU-bound, batch, system, etc.
- Hard to use one size to fit all

Combining scheduling algorithms to optimize for multiple objectives

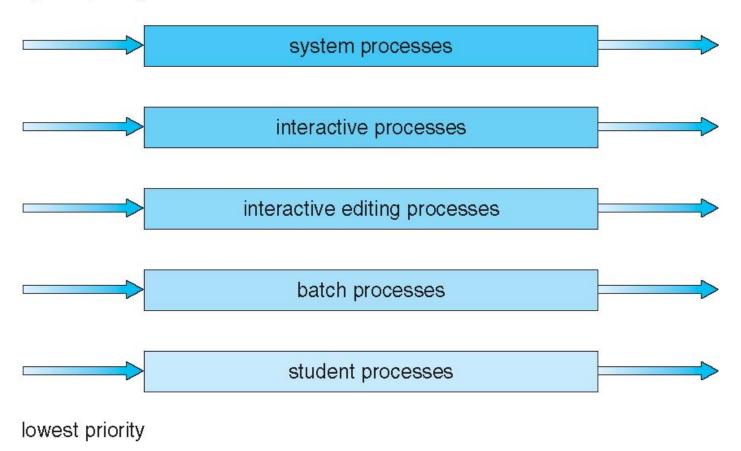
- Have multiple queues
- Use a different algorithm for each queue
- Move processes among queues

• Example: Multiple-level feedback queues (MLFQ)

- Multiple queues representing different job types
- Queues have priorities
 - Job in higher-priority queue can preempt jobs lower-priority queue
- Jobs on same queue use the same scheduling algorithm, typically RR

Multilevel Queue Scheduling

highest priority





Goal #1: Optimize job turnaround time for "batch" jobs

- Shorter jobs run first
- Why not SJF?
- Goal #2: Minimize response time for "interactive" jobs

Challenge:

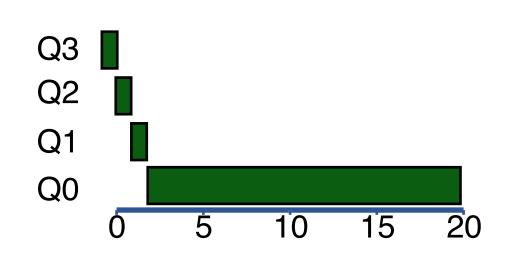
- No a *priori knowledge* of what type a job is, what the next burst is, etc.

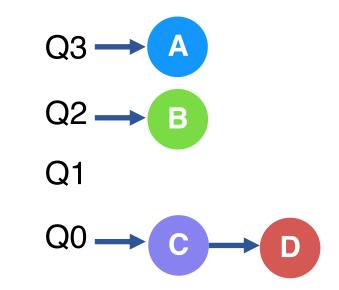
• Idea:

- Change a process's priority based on how it behaves in the past ("feedback")

Attempt

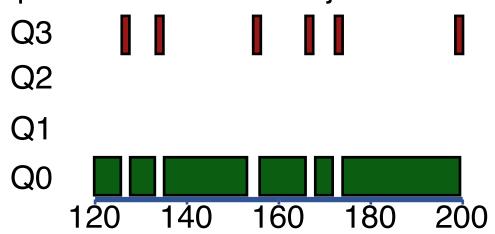
- Rule A: Processes start at top priority
- Rule B: If job uses whole slice, demote process
 - i.e., longer time slices at lower priorities
- Example 1: A long-running "batch" job





Attempt

- Rule A: Processes start at top priority
- Rule B: If job uses whole slice, demote process
 - i.e., longer time slices at lower priorities
- Example 1: A long-running "batch" job
- Example 2: An "interactive" job



Attempt

- Rule A: Processes start at top priority
- Rule B: If job uses whole slice, demote process
- Example 1: A long-running "batch" job
- Example 2: An "interactive" job
- Problems:
 - unforgiving + starvation
 - gaming the system
 - E.g., performing I/O right before time-slice ends

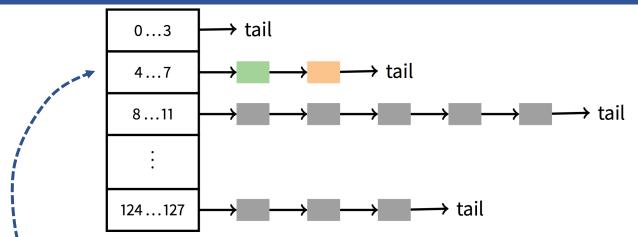
Attempt

- Rule A: Processes start at top priority
- Rule B: If job uses whole slice, demote process
- Example 1: A long-running "batch" job
- Example 2: An "interactive" job
- Problems:
 - unforgiving + starvation
 - gaming the system

Fixing the problems

- Periodically boost priority for jobs that haven't been scheduled
- Account for job's total run time at priority level (instead of just this time slice)

MLFQ in BSD



Every runnable process on one of 32 run queues

- Kernel runs process on highest-priority non-empty queue
 - Round-robins among processes on same queue
- Process priorities dynamically computed
 - Processes moved between queues to reflect priority changes
- Idea: Favor interactive jobs that use less CPU

Process Priority

p_nice – user-settable weighting factor

• p_estcpu – per-process estimated CPU usage

- Incremented whenever timer interrupt found process running
- Decayed every second while process runnable

$$p_estcpu \leftarrow \left(\frac{2 * load}{2 * load + 1}\right) * p_estcpu + p_nice$$

- Load is sampled average of length of run queue plus short-term sleep queue over last minute

• Run queue determined by p_usrpri/4

$$p_usrpri \leftarrow 50 + \left(\frac{p_estcpu}{4}\right) + 2 * p_nice$$

Sleeping Process Increases Priority

• p_estcpu not updated while asleep

- Instead p_slptime keeps count of sleep time

When process becomes runnable

 $p_estcpu \leftarrow \left(\frac{2 * load}{2 * load + 1}\right)^{p_slptime} * p_estcpu$

- Approximates decay ignoring nice and past loads

• Description based on "The Design and Implementation of the 4.4BSD Operating System"

Pintos Notes

Same basic idea for second half of Lab 1

- But 64 priorities, not 128
- Higher numbers mean higher priority
- Okay to have only one run queue if you prefer (less efficient, but we won't deduct points for it)

Have to negate priority equation:

$$priority = 63 - \left(\frac{recent_cpu}{4}\right) - 2 * nice$$

Priority Inversion

• Two tasks: *H* at high priority, *L* at low priority

- L acquires lock 1 for exclusive use of a shared resource R
- If *H* tries to acquire 1, blocked until *L* release resource R
- M enters system at medium priority, preempts L
 - L unable to release R in time
 - *H* unable to run, despite having higher priority than *M*

• A famous example: Mars PathFinder failure in 1997

 low-priority data gathering task and a medium-priority communications task prevented the critical bus management task from running

Priority Donation

- Say higher number = higher priority (like Pintos)
- Example 1: *L* (prio 2), *M* (prio 4), *H* (prio 8)
 - L holds lock 1
 - *M* waits on 1, *L*'s priority raised to $L_1 = \max(M; L) = 4$
 - Then H waits on 1, L's priority raised to $max(H; L_1) = 8$

• Example 2: Same *L*,*M*,*H* as above

- L holds lock 1, M holds lock 1_2
- *M* waits on 1, *L*'s priority now $L_1 = 4$ (as before)
- Then *H* waits on 1₂. *M*'s priority goes to $M_1 = \max(H; M) = 8$, and *L*'s priority raised to $\max(M_1; L_1) = 8$

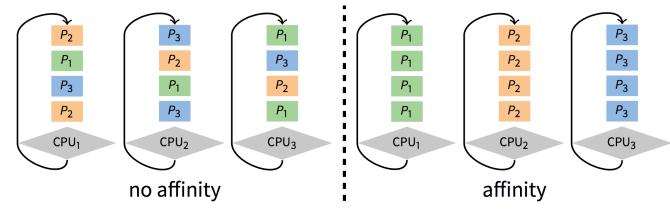
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Multiprocessor Scheduling Issues

Must decide on more than which processes to run

- Must decide on which CPU to run which process
- Moving between CPUs has costs
 - More cache misses, depending on arch. more TLB misses too
- Affinity scheduling—try to keep process/thread on same CPU



- But also prevent load imbalances
- Do cost-benefit analysis when deciding to migrate...affinity can also be harmful, particularly when tail latency is critical

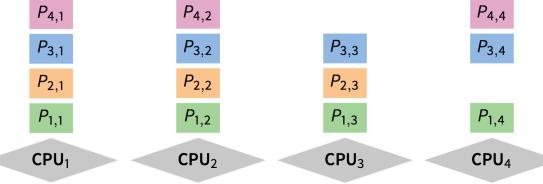
Multiprocessor Scheduling (cont)

Want related processes/threads scheduled together

- Good if threads access same resources (e.g., cached files)
- Even more important if threads communicate often, otherwise must context switch to communicate

Gang scheduling—schedule all CPUs synchronously

- With synchronized quanta, easier to schedule related processes/threads together



Real-time Scheduling

• Two categories:

- Soft real time miss deadline and CD will sound funny
- Hard real time miss deadline and plane will crash

System must handle periodic and aperiodic events

- E.g., processes A, B, C must be scheduled every 100, 200, 500 msec, require 50, 30, 100 msec respectively
- Schedulable if $\sum \frac{cpu}{period} \le 1$

Variety of scheduling strategies

- E.g., first deadline first (works if schedulable, otherwise fails spectacularly)

Scheduling Summary

Scheduling algorithm determines which process runs, quantum, priority...

Many potential goals of scheduling algorithms

- Utilization, throughput, wait time, response time, etc.

Various algorithms to meet these goals

- FCFS/FIFO, SJF, RR, Priority

Can combine algorithms

- Multiple-level feedback queues

Advanced topics

- affinity scheduling, gang scheduling, real-time scheduling

Next Time

• Read Chapter 26, 27