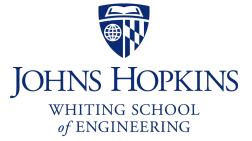
# CS 318 Principles of Operating Systems

### Fall 2019

### **Midterm Review**

Prof. Ryan Huang



## Midterm

- October 22<sup>th</sup> Tuesday 1:30-2:45 pm at classroom
- Covers material before virtual memory
- Based upon lecture material, homeworks, and project
  - Make sure you do the homeworks to practice
- One 8.5"x11" double-sided sheet of notes
- Obligatory: do not cheat
  - Do not copy from your neighbors
  - No one involved will be happy, particularly the teaching staff

# Arch Support for OSes

#### Types of architecture support

- Manipulating privileged machine state
- Generating and handling events

# **Privileged Instructions**

### What are privileged instructions?

- Who gets to execute them?
- How does the CPU know whether they can be executed?
- Difference between user and kernel mode
- Why do they need to be privileged?
- What do they manipulate?
  - Protected control registers
  - Memory management
  - I/O devices



Events		Unexpected	Deliberate
	Exceptions (sync)	fault	syscall trap
	Interrupts (async)	interrupt	software interrupt

- What are faults, and how are they handled?
- What are system calls, and how are they handled?
- What are interrupts, and how are they handled?
  - How do I/O devices use interrupts?
- What is the difference between exceptions and interrupts?



- What is a process?
- What resource does it virtualize?
- What is the difference between a process and a program?
- What is contained in a process?

## **Process Data Structures**

### Process Control Blocks (PCBs)

- What information does it contain?
- How is it used in a context switch?

#### State queues

- What are process states?
- What is the process state graph?
- When does a process change state?
- How does the OS use queues to keep track of processes?

# **Process Manipulation**

- What does CreateProcess on NT do?
- What does fork() on Unix do?
  - What does it mean for it to "return twice"?
- What does exec() on Unix do?
  - How is it different from fork?
- How are fork and exec used to implement shells?
- Why fork()?



#### • What is a thread?

- What is the difference between a thread and a process?
- How are they related?
- Why are threads useful?
- What is the difference between user-level and kernel-level

#### threads?

- What are the advantages/disadvantages of one over another?

# **Thread Implementation**

#### How are threads managed by the run-time system?

- Thread control blocks, thread queues
- How is this different from process management?

#### What operations do threads support?

- create, yield, sleep, etc.
- What does thread yield do?

#### What is a context switch?

What is the difference between non-preemptive scheduling and

#### preemptive thread scheduling?

- Voluntary and involuntary context switches

# Synchronization

#### Why do we need synchronization?

- Coordinate access to shared data structures
- Coordinate thread/process execution

### What can happen to shared data structures if synchronization is not

#### used?

- Race condition
- Corruption
- Bank account example

#### When are resources shared?

- Global variables, static objects
- Heap objects

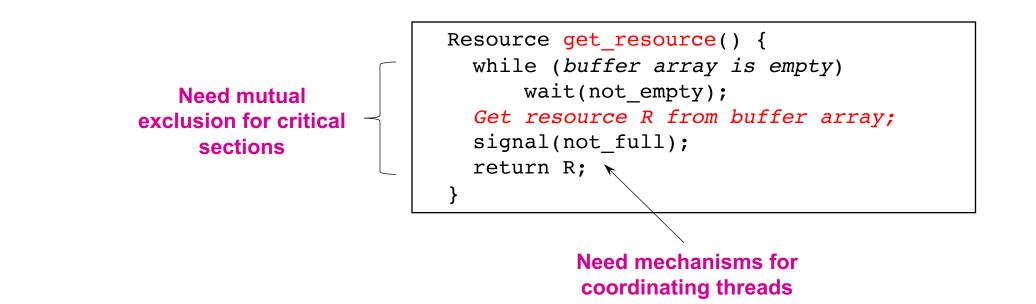
# **Concurrent Programs**

```
Monitor bounded_buffer {
   Resource buffer[N];
   // Variables for indexing buffer
   // monitor invariant involves these vars
   Condition not_full; // space in buffer
   Condition not_empty; // value in buffer
   void put_resource (Resource R) {
     while (buffer array is full)
        wait(not_full);
     Add R to buffer array;
     signal(not_empty);
   }
```

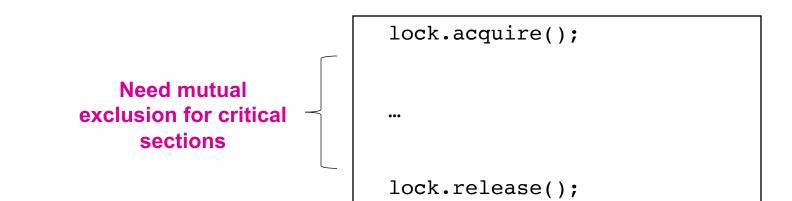
```
Resource get_resource() {
   while (buffer array is empty)
        wait(not_empty);
   Get resource R from buffer array;
   signal(not_full);
   return R;
  }
} // end monitor
```

• Our goal is to write concurrent programs...

## **Concurrent Programs**

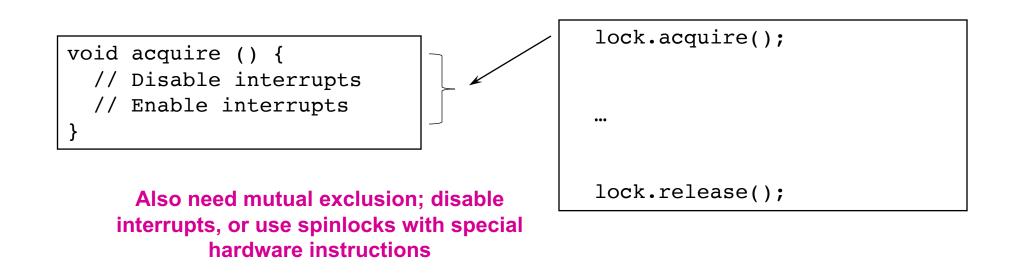


## **Mutual Exclusion**



Interrupts enabled, other threads can run (just not in this critical section)

## Mutual Exclusion



# Mutual Exclusion

#### What is mutual exclusion?

### What is a critical section?

- What guarantees do critical sections provide?
- What are the requirements of critical sections?
  - Mutual exclusion (safety)
  - Progress (liveness)
  - Bounded waiting (no starvation: liveness)
  - Performance

### How does mutual exclusion relate to critical sections?

### What are the mechanisms for building critical sections?

- Locks, semaphores, monitors, condition variables

### Locks

- What does Acquire do?
- What does Release do?
- What does it mean for Acquire/Release to be atomic?
- How can locks be implemented?
  - Spinlocks
  - Disable/enable interrupts
  - Blocking

#### How does test-and-set work?

- What kind of lock does it implement?

### What are the limitations of using spinlocks, interrupts?

- Inefficient, interrupts turned off too long

## Semaphores

#### • What is a semaphore?

- What does Wait/P/Decrement do?
- What does Signal/V/Increment do?
- How does a semaphore differ from a lock?
- What is the difference between a binary semaphore and a counting semaphore?
- When do threads block on semaphores?
- When are they woken up again?
- Using semaphores to solve synchronization problems
  - Readers/Writers problem
  - Bounded Buffers problem

# Monitors

#### What is a monitor?

- Shared data
- Procedures
- Synchronization

#### In what way does a monitor provide mutual exclusion?

- To what extent is it provided?
- How does a monitor differ from a semaphore?
- How does a monitor differ from a lock?
- What kind of support do monitors require?
  - Language, run-time support

# **Condition Variables**

### What is a condition variable used for?

- Coordinating the execution of threads
- Not mutual exclusion

### Operations

- What are the semantics of Wait?
- What are the semantics of Signal?
- What are the semantics of Broadcast?

### How are condition variables different from semaphores?

# Implementing Monitors

### What does the implementation of a monitor look like?

- Shared data
- Procedures
- A lock for mutual exclusion to procedures (w/ a queue)
- Queues for the condition variables

### • What is the difference between Hoare and Mesa monitors?

- Semantics of signal (whether the woken up waiter gets to run immediately or not)
- What are their tradeoffs?
- What does Java provide?

# Locks and Condition Vars

- Condition variables are also used without monitors in conjunction with locks
- A monitor ≈ a module whose state includes a C/V and a lock
- Why must cond\_wait both release mutex\_t & sleep?

# Scheduling

### What kinds of scheduling is there?

- Long-term scheduling
- Short-term scheduling

### Components

- Scheduler (dispatcher)

#### When does scheduling happen?

- Job changes state (e.g., waiting to running)
- Interrupt, exception
- Job creation, termination

# Scheduling Goals

#### Goals

- Maximize CPU utilization
- Maximize job throughput
- Minimize turnaround time
- Minimize waiting time
- Minimize response time
- What is the goal of a batch system?
- What is the goal of an interactive system?

### Starvation

### Starvation

- Indefinite denial of a resource (CPU, lock)

#### Causes

- Side effect of scheduling
- Side effect of synchronization

#### Operating systems try to prevent starvation

# Scheduling Algorithms

What are the properties, advantages and disadvantages of the

### following scheduling algorithms?

- First Come First Serve (FCFS)/First In First Out (FIFO)
- Shortest Job First (SJF)
  - Preemptive: Shortest-Remaining-Time-First (SRTF)
- Priority
- Round Robin
- Multilevel feedback queues

### • What scheduling algorithm does Unix use? Why?



 Deadlock happens when processes are waiting on each other and cannot make progress

#### What are the conditions for deadlock?

- Mutual exclusion
- Hold and wait
- No preemption
- Circular wait

#### How to visualize, represent abstractly?

- Resource allocation graph (RAG)
- Waits for graph (WFG)

# **Deadlock Approaches**

### • Dealing with deadlock

- Ignore it
- Prevent it (prevent one of the four conditions)
- Avoid it (have tight control over resource allocation)
- Detect and recover from it

### What is the Banker's algorithm?

- Which of the four approaches above does it implement?

## **Race Conditions**

```
int x = 0;
int i, j;
void AddToX() {
  for (i = 0; i < 100; i++) x++;
}
void SubFromX() {
  for (j = 0; j < 100; j++) x--;
}
```

#### What is the range of possible values for x? Why?

# Synchronization

```
Class Event {

...

void Signal () {

...

}

void Wait () {

...

}

}
```

- Event synchronization (e.g., Win32)
- Event::Wait blocks if and only if Event is unsignaled
- Event::Signal makes Event signaled, wakes up blocked threads
- Once signaled, an Event remains signaled until deleted
- Use locks and condition variables



• Use synchronization primitives (locks, semaphores, monitor, condition variables, etc.) to solve synchronization problems