

EECS 591

DISTRIBUTED SYSTEMS

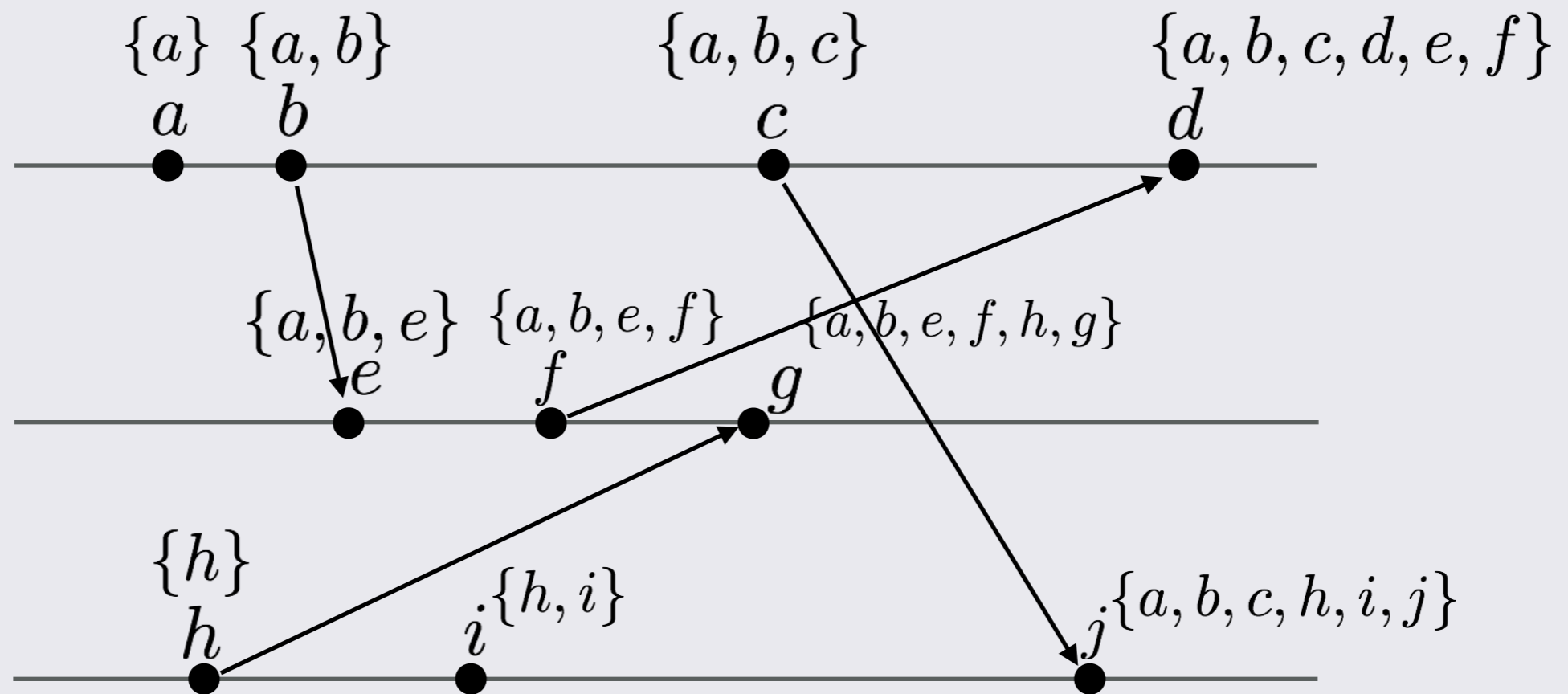
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Fall 2021



PREVIOUSLY ON
DISTRIBUTED SYSTEMS

IMPLEMENTING STRONG CLOCKS

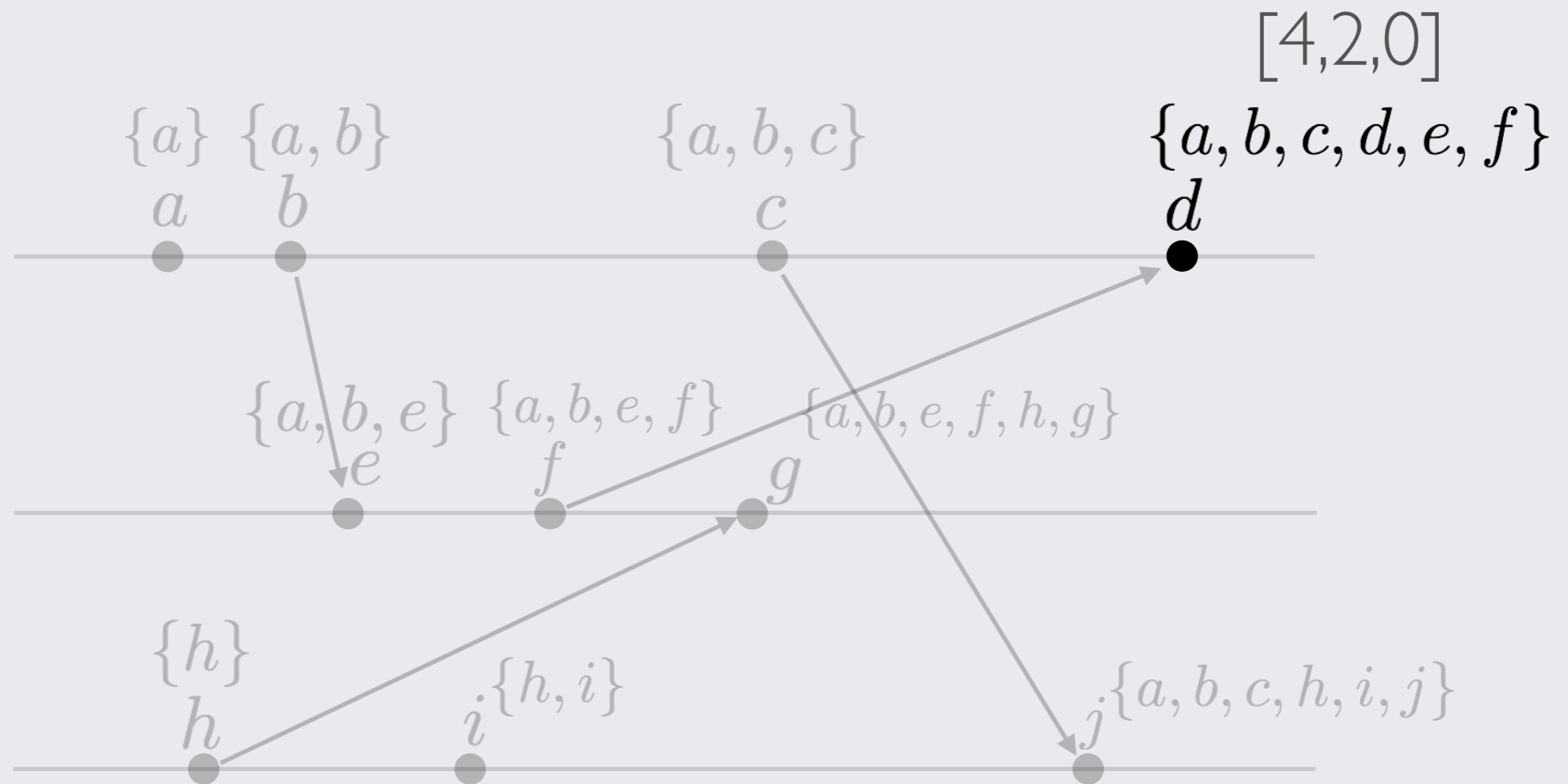
(the hard way)



Strong clock condition: $p \rightarrow q \Leftrightarrow \theta(p) \subset \theta(q)$

IMPLEMENTING STRONG CLOCKS

(the hard way)



Strong clock condition: $p \rightarrow q \Leftrightarrow \theta(p) \subset \theta(q)$

VECTOR CLOCKS

Each process keeps a vector of natural numbers **VC**, one for each process

Update rules

If e_i is a local or send event at process i :

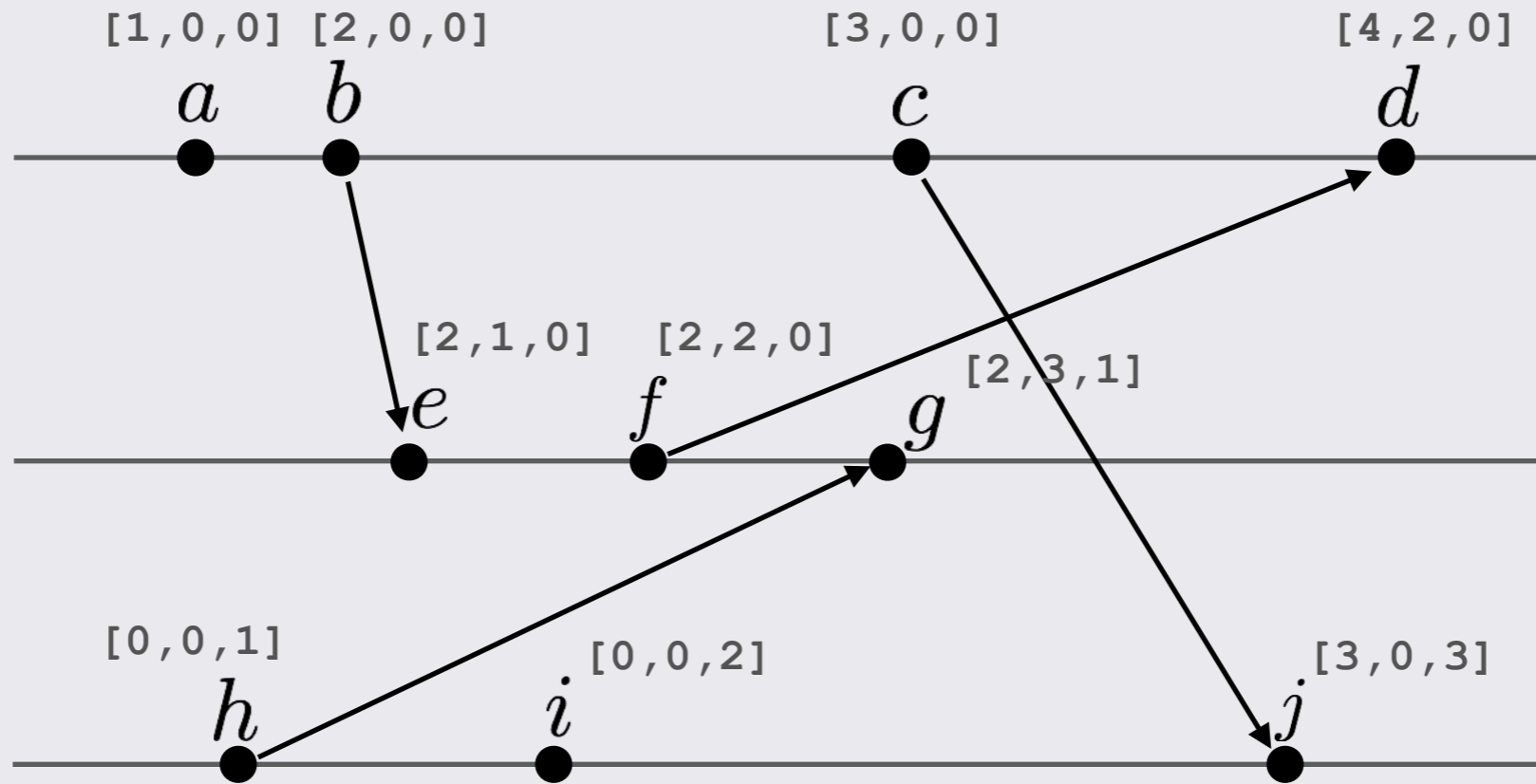
$$VC(e_i)[i] := VC[i] + 1 \quad (\text{Update the "local" counter})$$

If e_i is a receive event of message m :

$$VC(e_i) := \max\{VC, VC(m)\} \quad (\text{First "max" with the incoming VC...})$$

$$VC(e_i)[i] := VC[i] + 1 \quad (\text{...then update the "local" counter})$$

VECTOR CLOCKS



$VC(e_i)[j]$ = number of events executed by process j that causally precede e_i

COMPARING VECTOR CLOCKS

Equality

$$V = V' \equiv \forall k : 1 \leq k \leq n : V[k] = V'[k]$$

(i.e. all elements are the same)

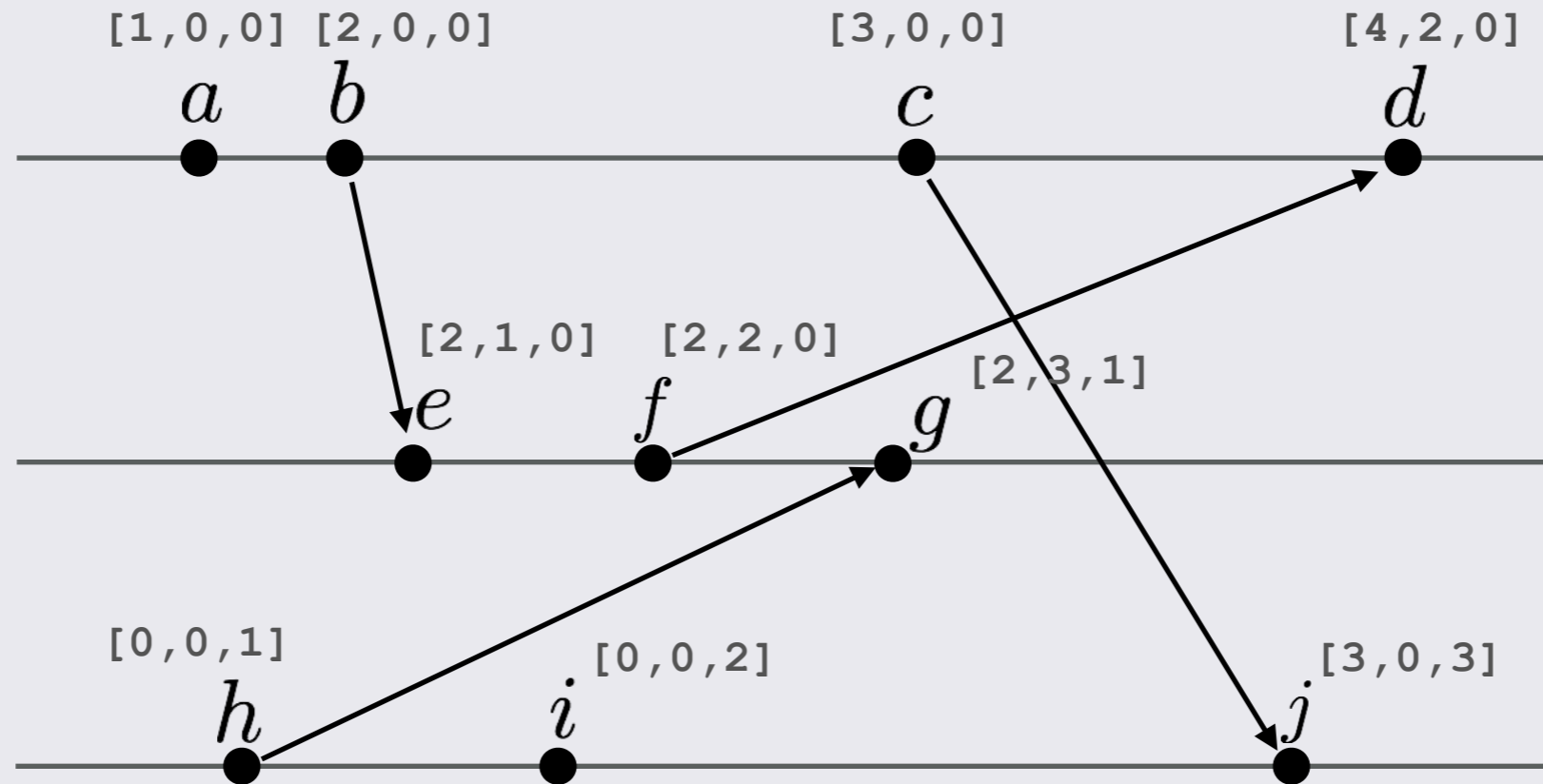
Inequality

$$V < V' \equiv (V \neq V') \wedge (\forall k : 1 \leq k \leq n : V[k] \leq V'[k])$$

Examples: $[2,0,0] < [2,0,1] < [3,0,1] < [4,1,1]$

Strong clock condition: $p \rightarrow q \Leftrightarrow VC(p) < VC(q)$

COMPARING VECTOR CLOCKS



Strong clock condition: $p \rightarrow q \Leftrightarrow VC(p) < VC(q)$

CAUSAL DELIVERY

A “monitor” process wants to record all messages
(e.g. deadlock detection, system snapshot, etc)

- Processes send copies of their messages to the monitor
- Only increment the local component of **VC** for send events

CAUSAL DELIVERY RULES

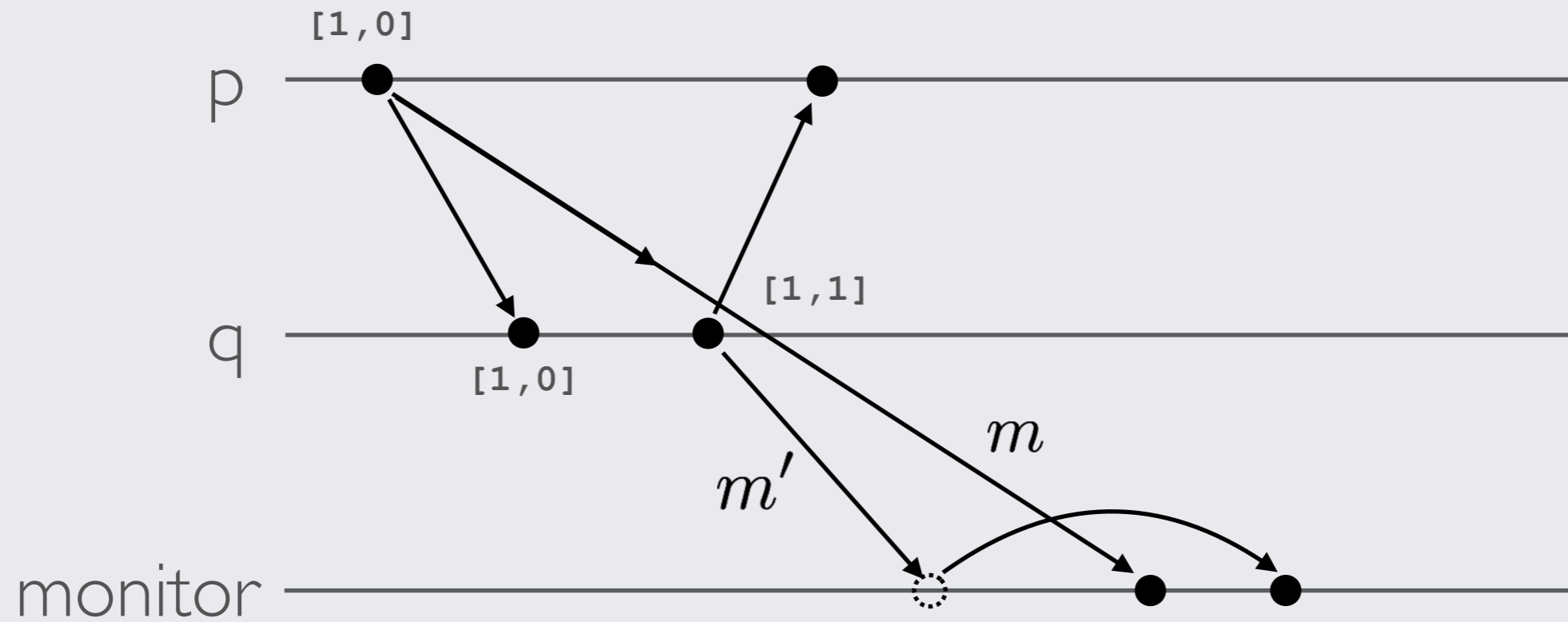
Monitor keeps an array D , where $D[i]$ is the number of messages delivered from process i

Monitor delivers message m from process j when:

$$D[j] = VC(m)[j] - 1$$

$$D[k] \geq VC(m)[k], \forall k \neq j$$

CAUSAL DELIVERY



D	$(0, 0)$	$(1, 0)$	$(1, 1)$
$D[j] = VC(m)[j] - 1$	✓	✓	✓
$D[k] \geq VC(m)[k], \forall k \neq j$	✗	✓	✓

ADMINISTRIVIA

- Remember to send me your picture if you haven't already

Clock synchronization



What time is it?

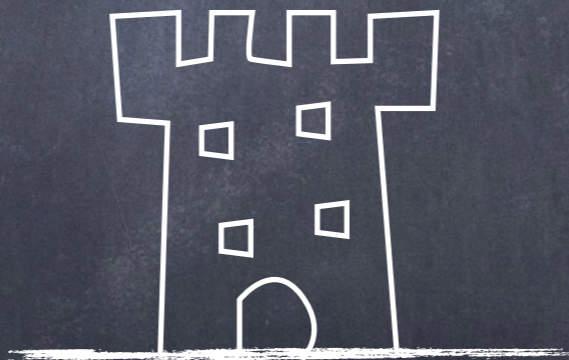
Roman generals v2.0

Attack at midnight!

Chaaaaaarge!



12:00am



zzzzzz



11:30pm

Clock drift

- Bound on drift: ρ

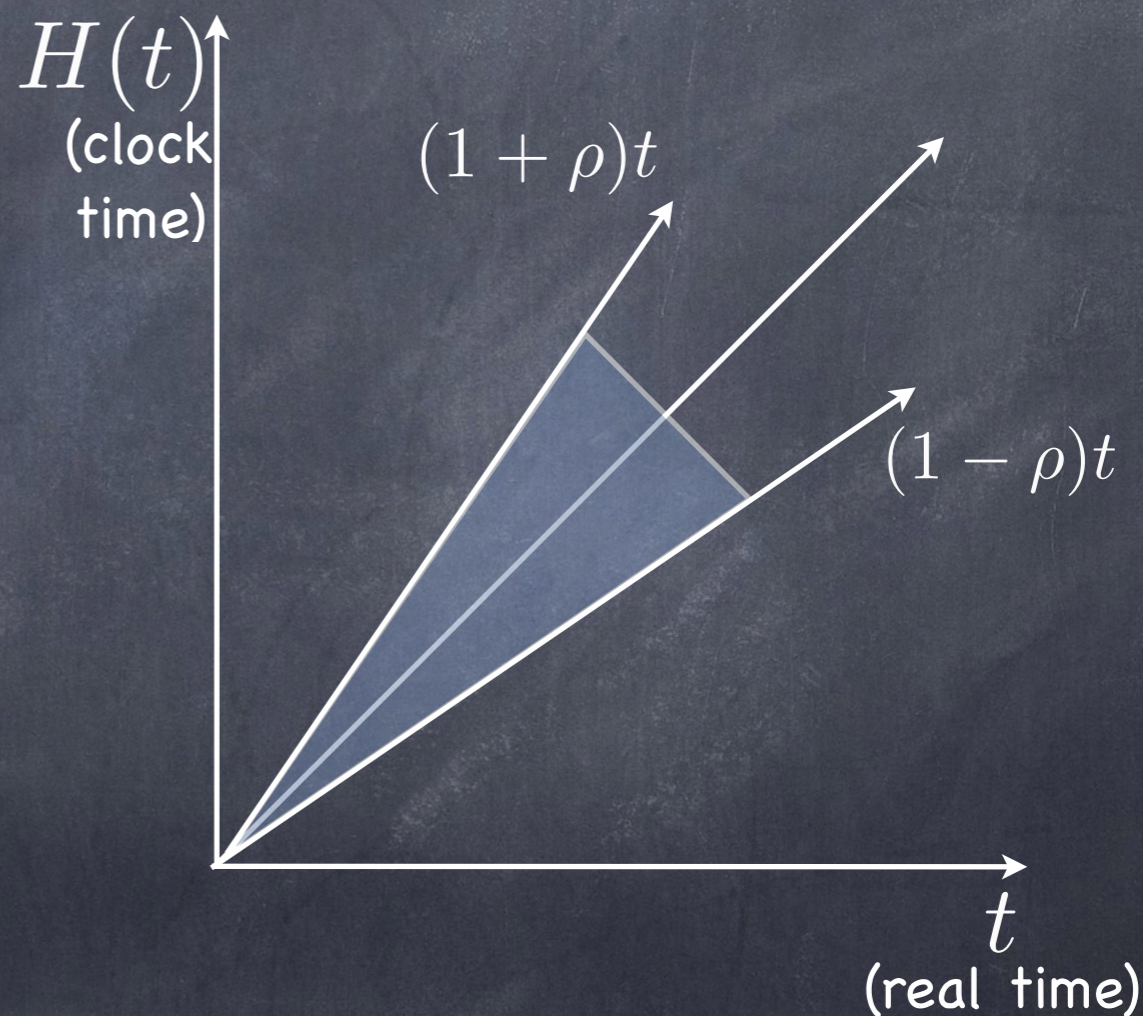
$$(1 - \rho)(t - t') \leq H(t) - H(t') \leq (1 + \rho)(t - t')$$

- ρ is typically small (10^{-6})

- $\rho^2 \approx 0$

- $\frac{1}{1 - \rho} = 1 + \rho$

- $\frac{1}{1 + \rho} = 1 - \rho$



External vs internal synchronization

External Clock Synchronization:

keeps clock within some maximum deviation from an external time source.

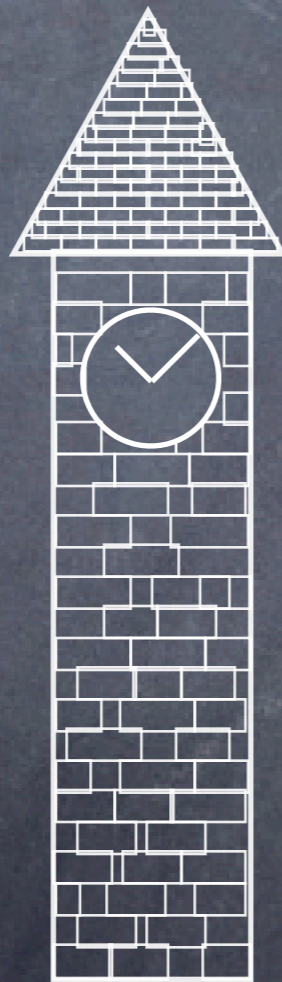
- exchange of info about timing events of different systems
- can take actions at **real-time** deadlines

Internal Clock Synchronization:

keeps clocks within some maximum deviation from each other.

- can measure **duration** of distributed activities that start on one process and terminate on another
- can totally order events that occur in a distributed system

Probabilistic Clock Synchronization (Cristian)

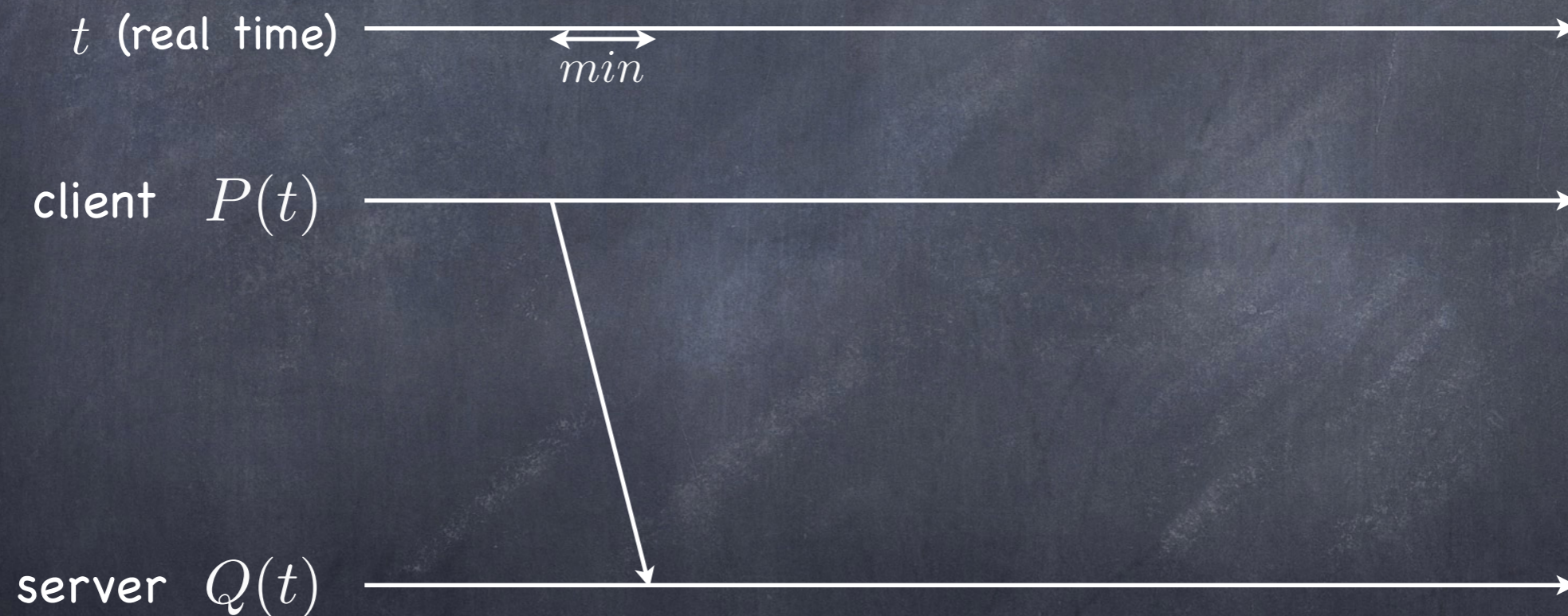


- Client-server architecture
- Server can be connected to external time source
- Clients read server's clock and adjust their own

How accurately can a client read the server's clock?

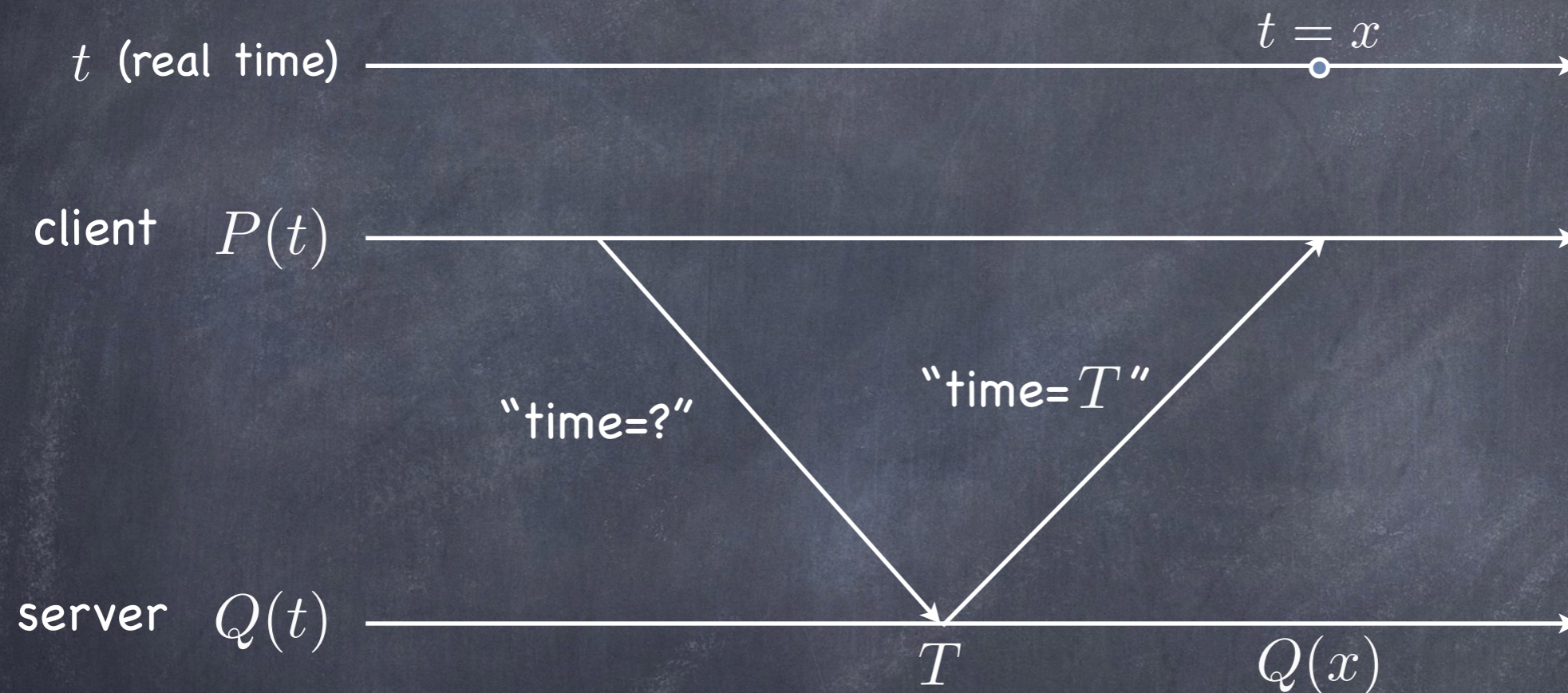
Setup and assumptions

Goal: Synchronize the client's clock with the server



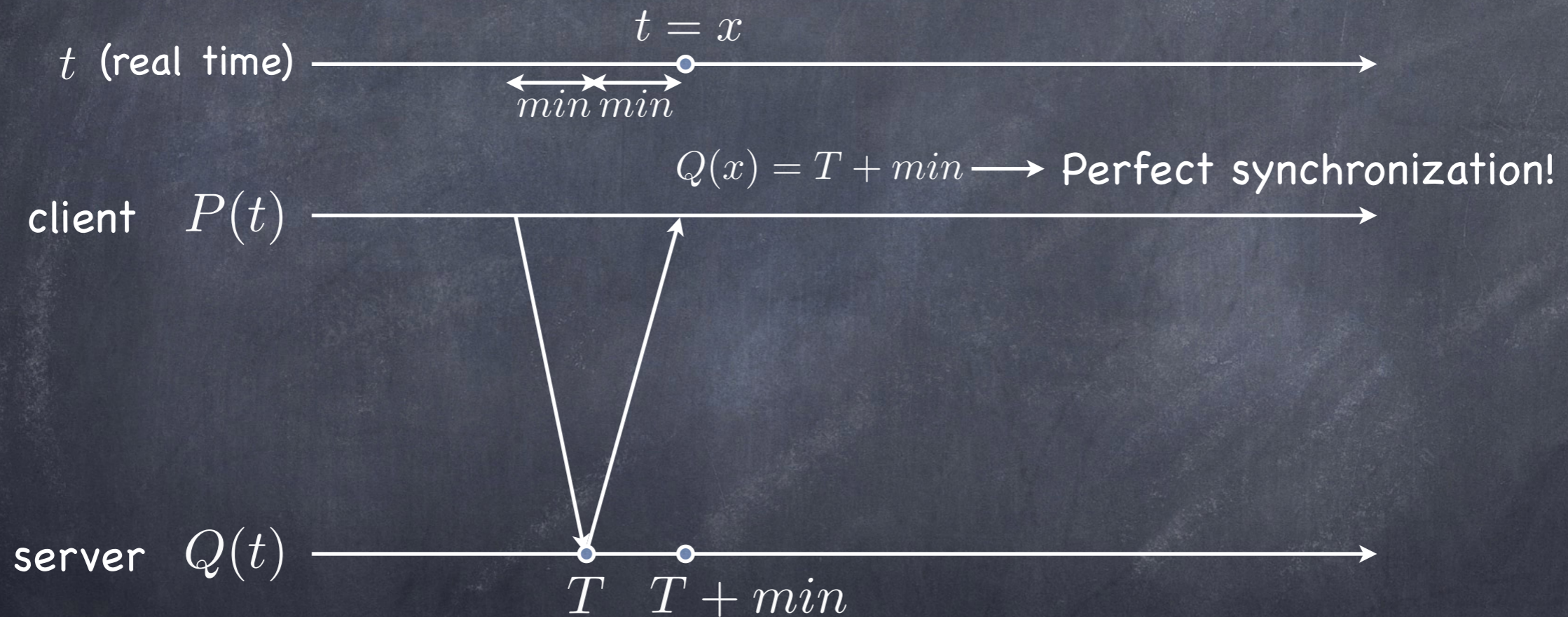
Assume that minimum delay is known
Assume that clock drifts are known (ρ for both)

The protocol



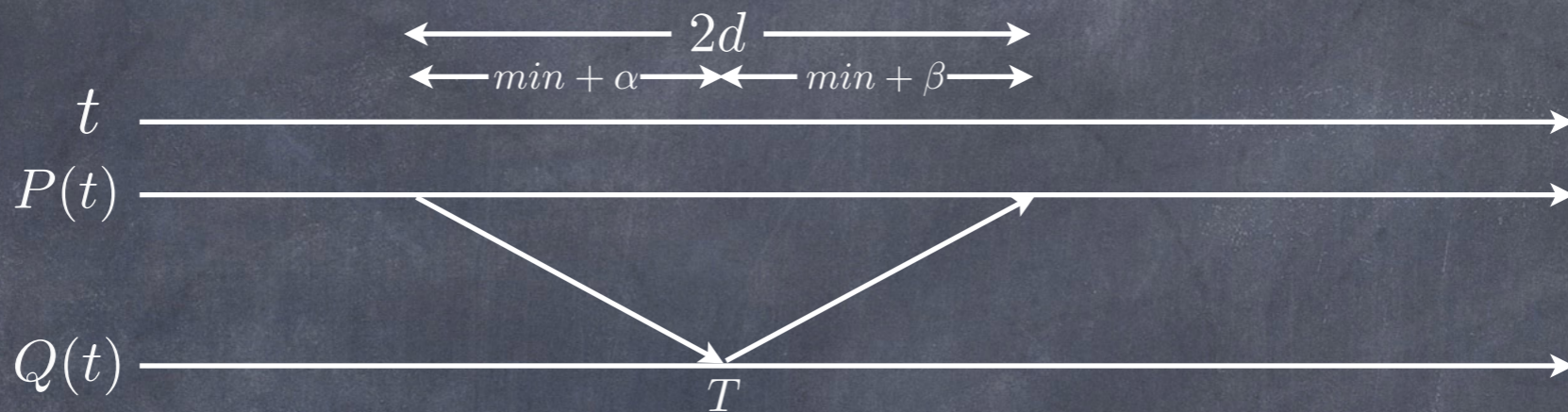
Question: what is $Q(x)$?

Ideal scenario

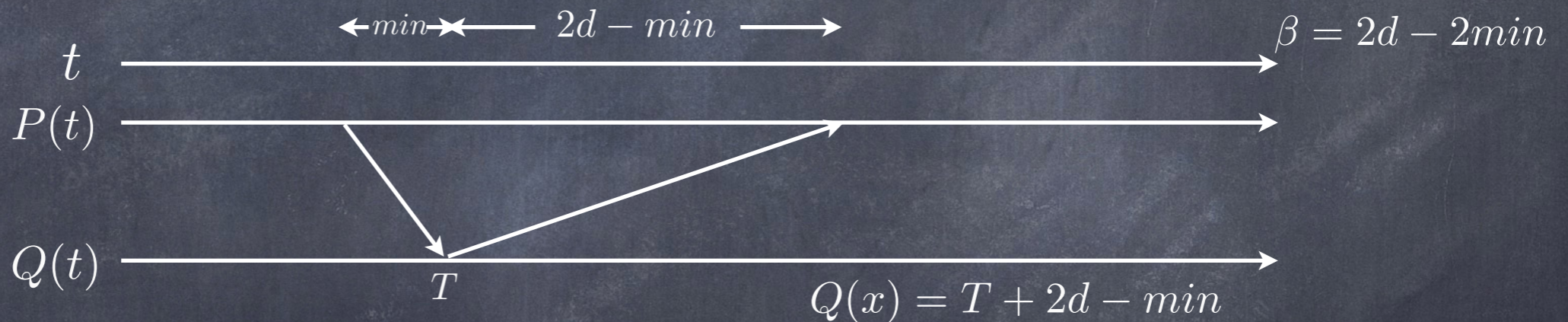


Assume no clock drift

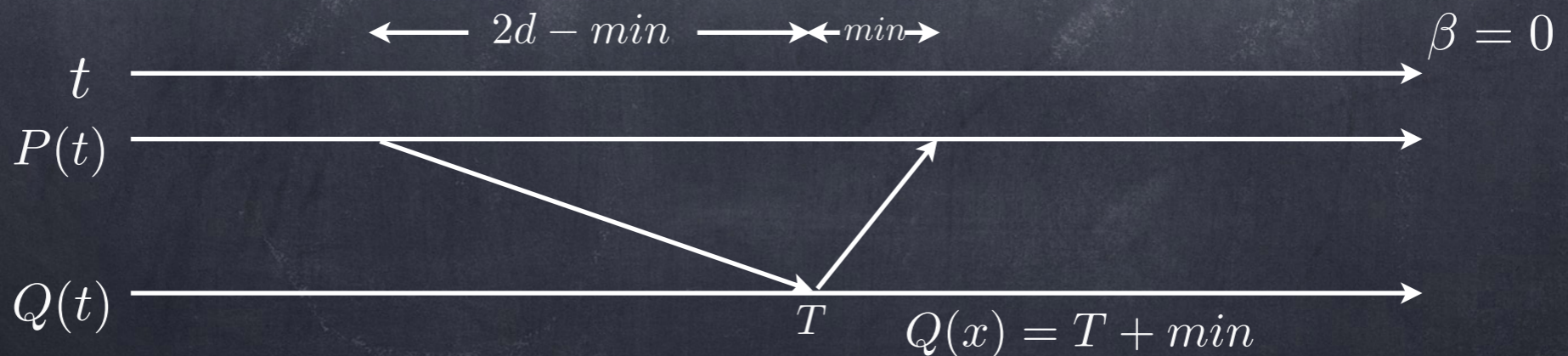
Problem #1: message delay



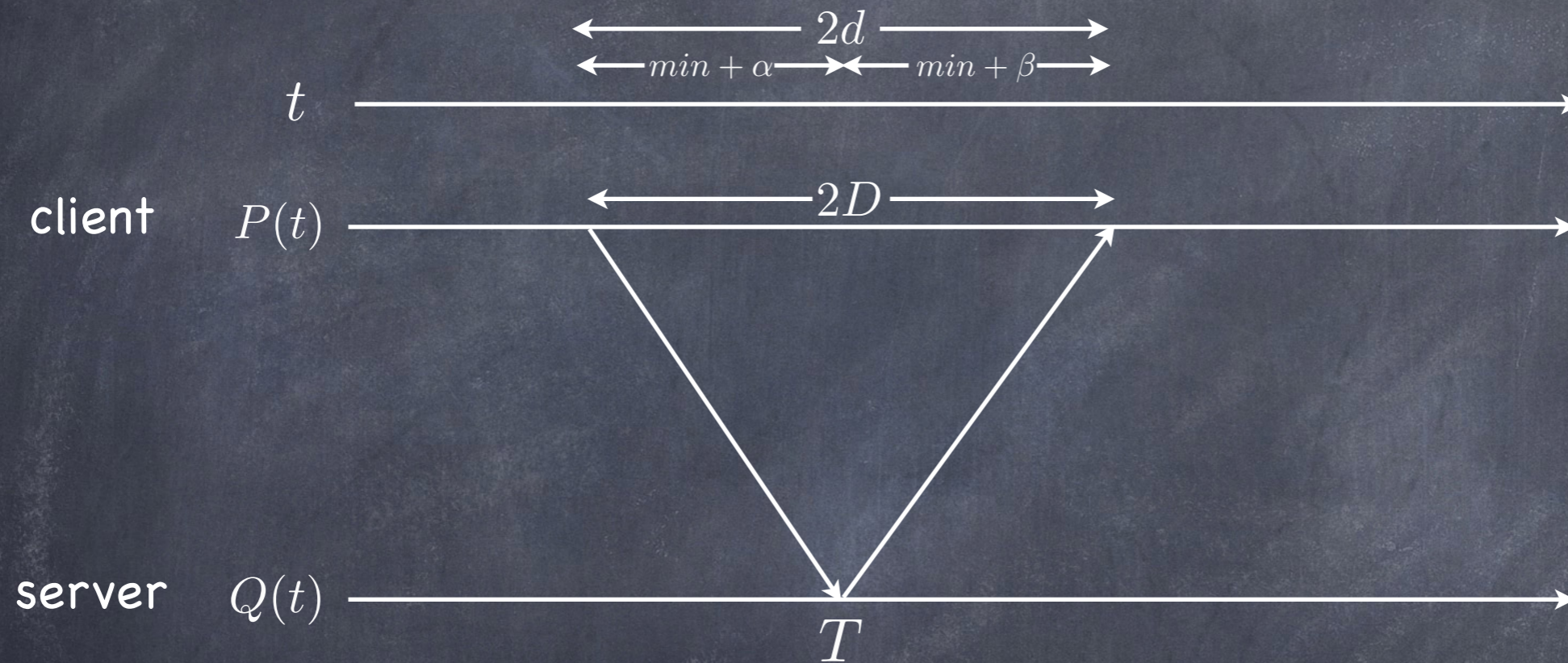
one extreme



another extreme

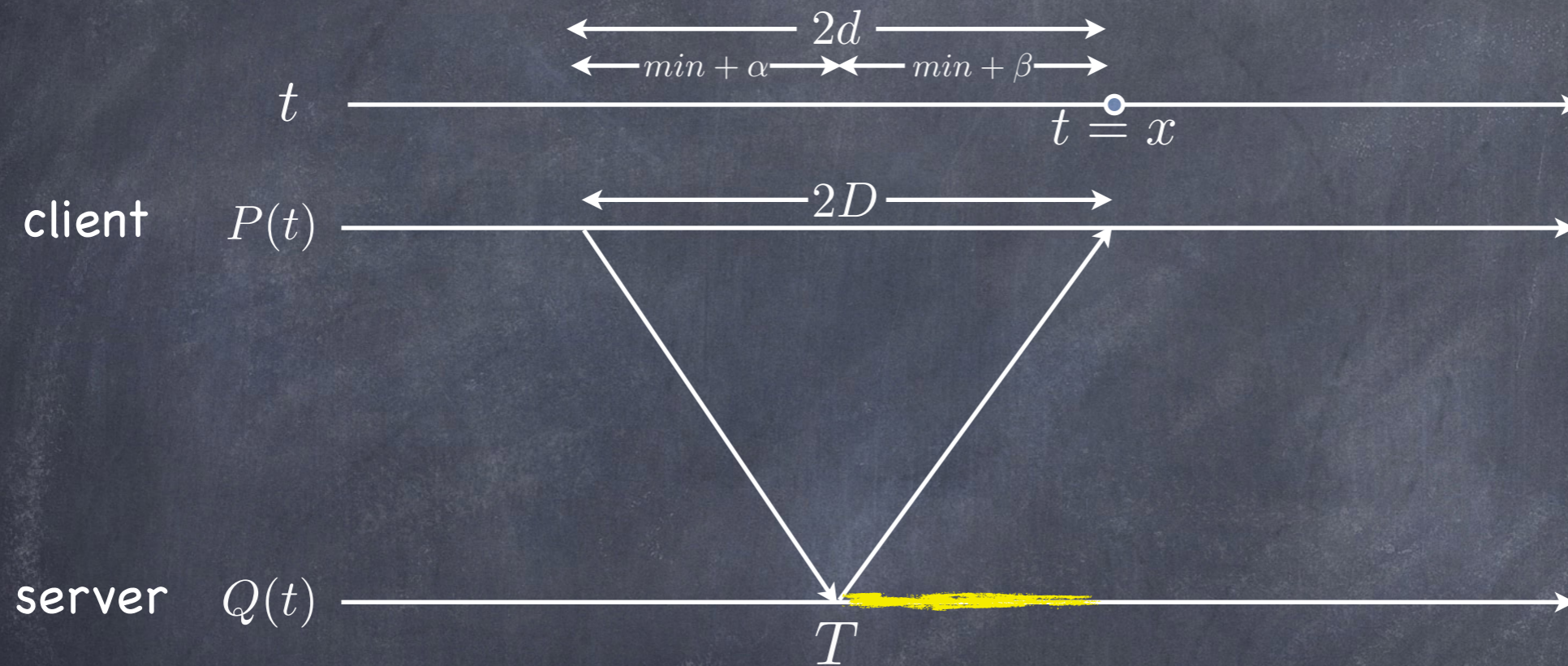


Problem #2: client drift



$$2d(1 - \rho) \leq 2D \leq 2d(1 + \rho)$$

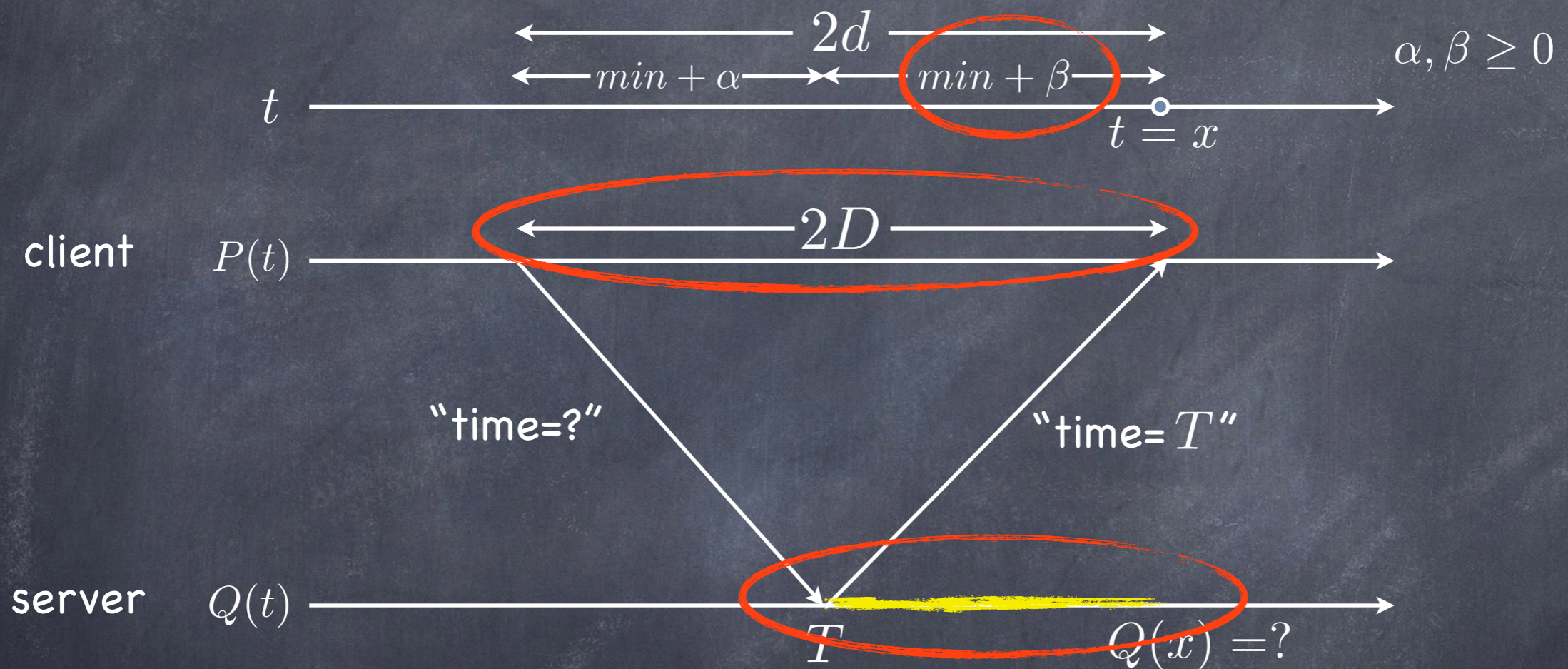
Problem #3: server drift



During the server's clock drifts

Even if you know β , there is still some uncertainty!

Cristian's algorithm



Cristian's algorithm

Naive estimation: $Q(x) = T + (min + \beta)$



(take server's drift into account)

$$Q(x) \in [T + (min + \beta)(1 - \rho), T + (min + \beta)(1 + \rho)]$$



$0 \leq \beta \leq 2d - 2min$ (take delay into account)

$$\begin{aligned} Q(x) &\in [T + (min + 0)(1 - \rho), T + (min + 2d - 2min)(1 + \rho)] \\ &= [T + (min)(1 - \rho), T + (2d - min)(1 + \rho)] \end{aligned}$$



$2d \leq 2D(1 + \rho)$ (take client's drift into account)

$$\begin{aligned} Q(x) &\in [T + (min)(1 - \rho), T + (2D(1 + \rho) - min)(1 + \rho)] \\ &= [T + (min)(1 - \rho), T + 2D(1 + 2\rho) - min(1 + \rho)] \end{aligned}$$

Client's estimation and precision

Client's best guess: $Q(x) = T + D(1 + 2\rho) - \min \cdot \rho$

Maximum error: $e = D(1 + 2\rho) - \min$

You can keep trying, until you
achieve the required precision

(if that precision is reasonable)