

# Accurate Static Branch Prediction by Value Range Propagation

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#### **Motivation**

Approaches to obtaining branch prediction data:

- Heuristics based on nesting and coding styles
  - Based on assumptions
  - Poor accuracy
- Real execution profiling
  - Require programmer intervention
  - Time consuming
  - Can be impractical / inapplicable
- Source code hints supplied by the programmer
  - Require programmer intervention
  - Inconvenient
  - Potentially more inaccurate

Goal: Predict branching behavior as accurately as execution profiling and as fast as static analysis, without programmer intervention

#### Introduction

#### **Constant Propagation**

- Identify expressions that are constant
- Evaluate constant expressions at compile time
- Propagate information around the control flow graph

#### Value Range Propagation

- Value ranges are propagated rather than constants
- Determine weighted range of values an expression can have during program execution
- Examine weighted value range

# **Key Contribution**

- Objective of branch prediction is to determine likelihood of taking each conditional branch
- Heuristic methods mark each branch as "taken" or "not taken"
- Useful but not ideal

#### Value range propagation produces probabilities.

- Out edges of each conditional branch are marked with probabilities
- More accurately assess degree of speculation

### **Component #1: Value Range Updates**

```
1 [4:4:0] = "100% chance of being 4"
1 [0:8:2] = "100% chance of being a
            value in {0, 2, 4, 6, 8}"
```

Value Range: P[L:U:S]

```
Operations r3 = r1 + r2
  r1: { 0.7[32:256:1], 0.3[3:21:3] }
+ r2: { 0.6[16:100:4], 0.4[8:8:0] }
  r3: { 0.42[48: 356: 1], 0.28[40: 264: 1]
       0.18[19: 121: 1], 0.12[11:29:3]
```

```
30% chance r1 in {3, 6, 9, 12, 15, 18, 21}
 0.3 [3 : 21 : 3]
+ 0.6 [16 : 100 : 4]
                            60% chance r2 in {16, 20, 24, ....., 96, 100}
0.18 [19 : 121 : 1]
                            18% chance r3 in {19, 20, 21, ....., 120, 121}
```

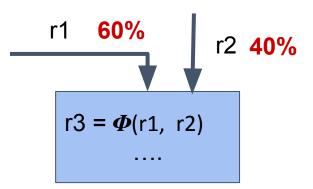
Largest common divisor Information Loss! The output is generalized/ over-estimated

# **Component #1: Value Range Updates**

# Phi nodes $r3 = \Phi(r1, r2)$

r1: { 1[32:42:1]}

r2: { 0.6[0:10:2], 0.4[30:30:0] }



r3 has 60% chance to be r1 and 40% chance to be r2

```
r3: { 0.6*1[32:42:1], 0.4*0.6[0:10:2], 0.4*0.4[30:30:0] } = { 0.6[32:42:1], 0.24[0:10:2], 0.16[30:30:0] }
```

# **Component #2: Loop Carried Expressions**

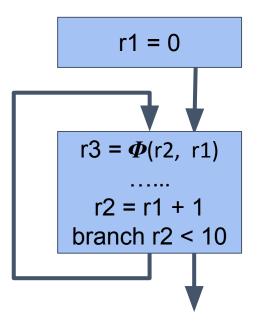
- When at least one in-edge to a phi-node is a backedge
- Derivation of how the variable may be computed from its previous value and the values of other variables.
- In practice, use templates to to identify simple inductive derivations such as loop counters

#### Template:

```
(old value) = (constant)
(new value) = (old value) + (constant)
branch (new value) (operator) (constant)
```

```
r1 = 0
r2= r1 + 1
branch r2 < 10
```

```
r3: { 1[0:10:1] }
```



#### **Component #3: CFG and Queues**

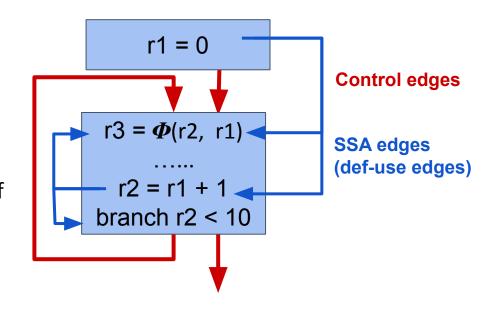
Control flow graph in SSA form

#### • FlowWorkList:

 Add control edges to successor basic blocks when the current branch probability is updated

#### SSAWorkList:

- Add def-use edges if the value range of the def is updated
- → ensures all values ranges (and thus the branch probabilities) are updated until convergence



```
FlowWorkList = {All out-edges from the start node}

SSAWorkList = Ø

value range probabilities = 0

value ranges = T

Probability of out-edges from the start node = 1

While (True):

If (!FlowWorkList && !SSAWorkList): break

Take next item i from either one of the worklists
```



```
While (True):
    If (!FlowWorkList && !SSAWorkList): break
    Take next item i from either one of the worklists
    If (i is control flow edge):
         Visit target BB \boldsymbol{n} that \boldsymbol{i} points to
         If (visited[n]):
              Evaluate only the phi nodes in n
         Else:
              Evaluate every expression in n
         visited[n] = 1
     Else If (i is SSA edge):
         Evaluate the expression that i points to
```

```
Evaluate(Expression e):
    ...
    Else If (e is phi-node && !loop_derived[e]):
        Evaluate e by merging value ranges according to the branch probability of each e's in-edges

If (new value range != old value range):
        Add the SSA edge starting at that expression e to the SSAWorkList
```

```
Evaluate(Expression e):
    ...
    Else If (e is an expression && !loop_derived[e]):
        Evaluate e by performing value range operations

If (new value range != old value range):
        Add the SSA edge starting at that expression e to the SSAWorkList
```

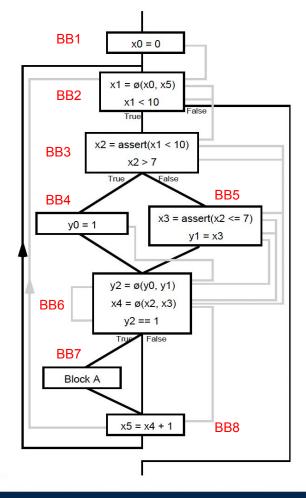
```
Evaluate(Expression e):
    ...
Else If (e is a conditional branch && !loop_derived[e]):
    Determine the probability p of taking the branch by
    examining the relevant variable's value range

If (new p != old p):
    Mark the out-edges with new probabilities
    Add out-edges to the FlowWorkList
```

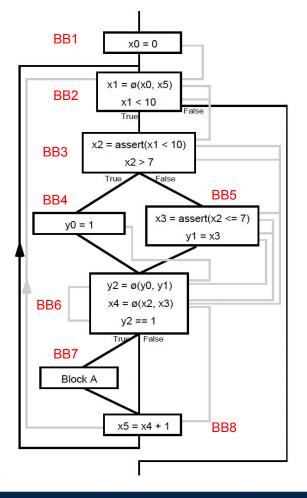
```
Value Range:
x0 {0[T]}
x1 {0[T]}
x2 {0[T]}
x3 {0[T]}
x4 {0[T]}
x5 {0[T]}
y0 {0[T]}
y1 {0[T]}
```

 $\{0[T]\}$ 

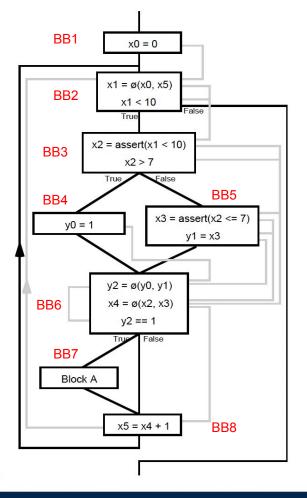
```
FlowWorkList = {start→BB1}
SSAWorkList = ∅
```



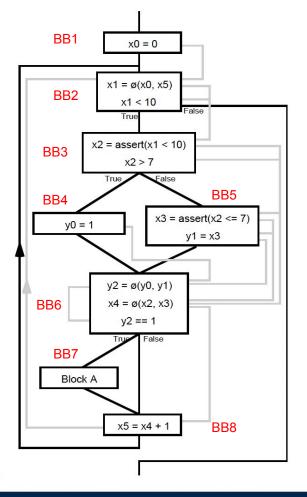
```
FlowWorkList = Ø
Value Range:
     {0[T]}
x0
                       SSAWorkList = Ø
     \{0[T]\}
x2
     \{0[T]\}
x3
     \{0[T]\}
                       Item i = start→BB1
     \{0[T]\}
х4
                       visited[BB1] != 1
х5
     \{0[T]\}
                       Evaluate all expressions in BB1
y0
     \{0[T]\}
     \{0[T]\}
     \{0[T]\}
```



```
FlowWorkList = Ø
Value Range:
    {1[0:0:0]}
x0
                     SSAWorkList = \{x1=\phi(x0, x5)\}
     \{0[T]\}
x1
x2
     {0[T]}
x3
     \{0[T]\}
                     Item i = start→BB1
х4
     {0[T]}
                     visited[BB1] != 1
х5
     \{0[T]\}
                     Evaluate all expressions in BB1
y0
     \{0[T]\}
                           Evaluate x0=0
     \{0[T]\}
     \{0[T]\}
```

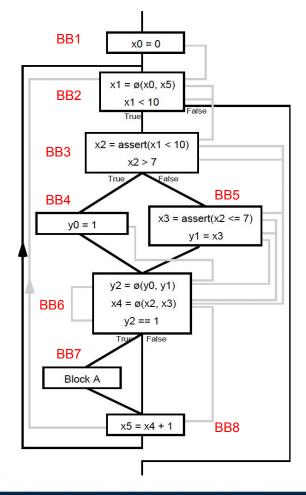


```
FlowWorkList = {BB1→BB2}
Value Range:
     {1[0:0:0]}
x0
                      SSAWorkList = \{x1=\Phi(x0, x5)\}
     \{0[T]\}
x1
x2
     {0[T]}
x3
     \{0[T]\}
                      Item i = start→BB1
х4
     {0[T]}
                      visited[BB1] != 1
х5
     \{0[T]\}
                      Evaluate all expressions in BB1
y0
     \{0[T]\}
                           Evaluate fall-through branch
     \{0[T]\}
     \{0[T]\}
```

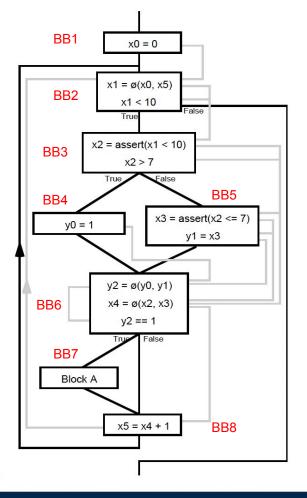


```
Value Range:
       {1[0:0:0]}
x0
x1
       \{0[T]\}
x2
       \{0[T]\}
x3
       \{0[T]\}
       \{0[T]\}
х4
х5
       \{0[T]\}
y0
       \{0[T]\}
       \{0[T]\}
       \{0[T]\}
```

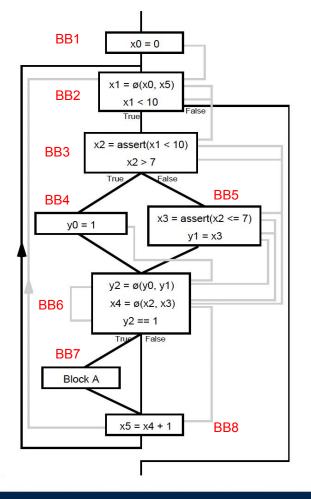
```
FlowWorkList = \{BB1\rightarrow BB2\}
SSAWorkList = \{x1=\Phi(x0, x5)\}
```



```
FlowWorkList = Ø
Value Range:
     {1[0:0:0]}
x0
                      SSAWorkList = \{x1=\Phi(x0, x5)\}
     \{0[T]\}
x1
x2
     {0[T]}
x3
     \{0[T]\}
                      Item i = BB1→BB2
х4
     {0[T]}
                      visited[BB2] != 1
х5
     \{0[T]\}
                      Evaluate all expressions in BB2
y0
     \{0[T]\}
     \{0[T]\}
     \{0[T]\}
```

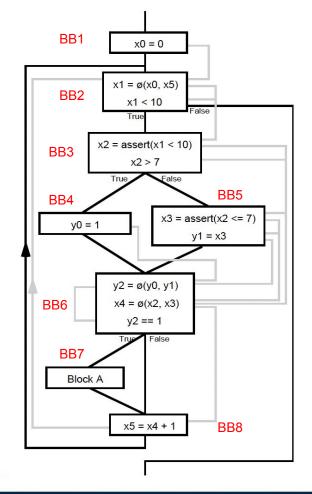


```
FlowWorkList = ∅
Value Range:
     {1[0:0:0]}
x0
                      SSAWorkList = \{x1=\Phi(x0, x5)\}
     \{0[T]\}
x1
x2
     {0[T]}
x3
     \{0[T]\}
                      Item i = BB1→BB2
х4
     {0[T]}
                      visited[BB2] != 1
х5
     \{0[T]\}
                      Evaluate all expressions in BB2
y0
     \{0[T]\}
                           Evaluate x1=\Phi(x0, x5)
     {0[T]}
     \{0[T]\}
                           → loop carried
```

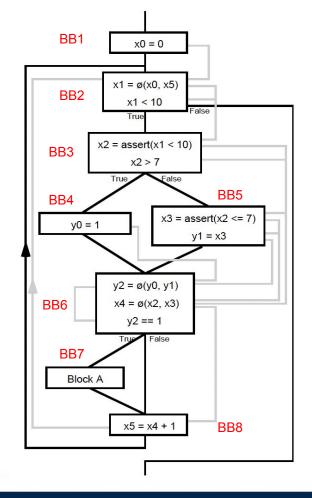


```
FlowWorkList = ∅
Value Range:
     {1[0:0:0]}
x0
                     SSAWorkList = \{x1=\Phi(x0, x5),
    {1[0:10:1]}
                     x1<10, x2=assert(x1<10)}
x2
     {0[T]}
x3
     \{0[T]\}
х4
     {0[T]}
                     Item i = BB1→BB2
х5
     \{0[T]\}
                     visited[BB2] != 1
y0
     \{0[T]\}
                     Evaluate all expressions in BB2
     {0[T]}
     \{0[T]\}
                          Evaluate x1=\Phi(x0, x5)
                          → loop carried
                           Derive successful!
                                                    control flow edge
```

SSA edge

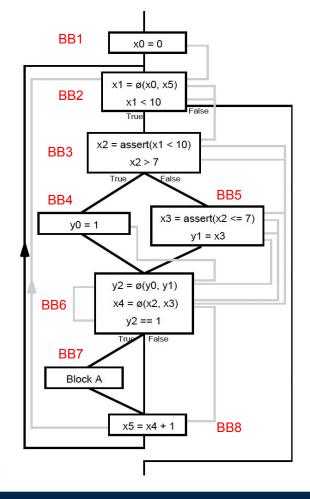


```
FlowWorkList = ∅
Value Range:
    {1[0:0:0]}
x0
                     SSAWorkList = \{x1=\Phi(x0, x5),
    {1[0:10:1]}
                     x1<10, x2=assert(x1<10)
x2
    {0[T]}
x3
     \{0[T]\}
х4
     {0[T]}
                     Item i = BB1→BB2
х5
     \{0[T]\}
                     visited[BB2] != 1
y0
     \{0[T]\}
                     Evaluate all expressions in BB2
     {0[T]}
     \{0[T]\}
                          Evaluate conditional branch
                          x1 < 10?
```



```
FlowWorkList = {BB2→BB3, BB2→end}
Value Range:
     {1[0:0:0]}
x0
                     SSAWorkList = \{x1=\Phi(x0, x5),
    {1[0:10:1]}
                     x1<10, x2=assert(x1<10)}
x2
     {0[T]}
х3
     \{0[T]\}
х4
     {0[T]}
                     Ttem i = BB1→BB2
х5
     {0[T]}
                     visited[BB2] != 1
y0
     {0[T]}
                     Evaluate all expressions in BB2
     {0[T]}
     {0[T]}
                          Evaluate conditional branch
                          x1 < 10?
Branch Prob:
                          prob(BB2\rightarrow BB3) = 0.91
x1<10
          0.91
                          prob(BB2\rightarrow end) = 0.09
```

Continue following the algorithm...



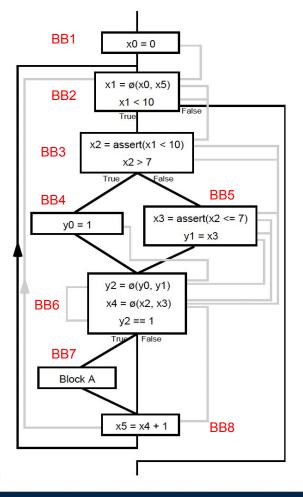
# **Eventually we get to...**

Value Range: {1[0:0:0]} x0 {1[0:10:1]} x2 {1[0:9:1]} х3 {1[0:7:1]} {1[0:9:1]} х4 x5 {1[1:10:1]} y0 {1[1:1:0]} {1[0:7:1]} {0.8[0:7:1], 0.2[1:1:0]} FlowWorkList = ∅ SSAWorkList = ∅

#### **Branch Prob:**

x1<10 0.91 x2>7 0.20

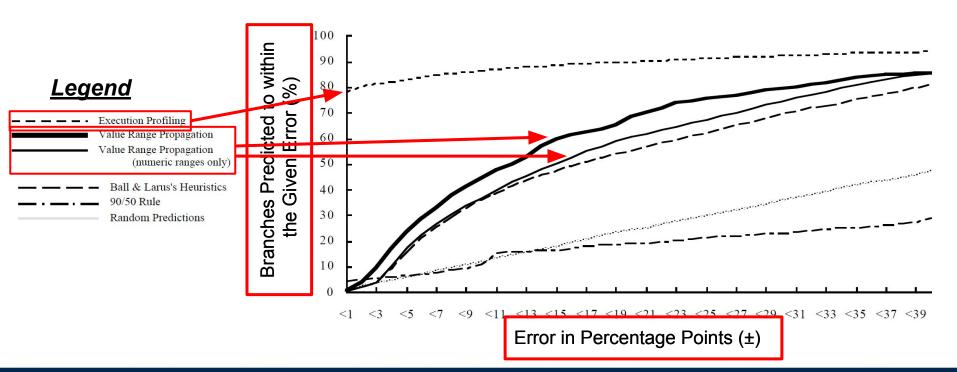
y2==1 0.3



#### Results

#### **Integer and pointer code benchmark**

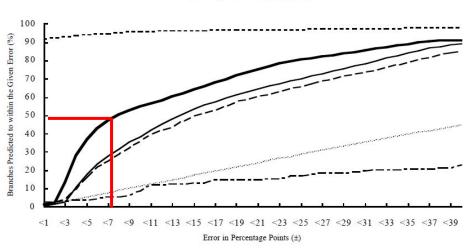
SPECint92 Unweighted



#### **Results**

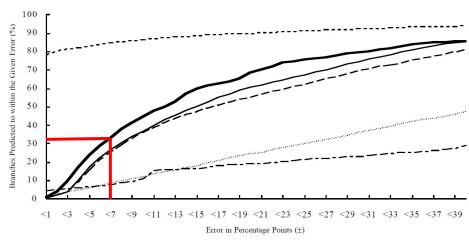
#### **Numeric code benchmark**

#### SPECfp92 Unweighted



#### Integer and pointer code benchmark

#### SPECint92 Unweighted



### Strength vs. Weaknesses

#### **Strengths**

- Extension of constant propagation
- Branch prediction granularity

#### Weaknesses

- Algorithm extensibility
- Probability accuracy is significantly worse than profile data

#### Conclusion

- Static branch prediction algorithm
- Extends constant propagation
- Flexible and efficient value range representation

```
{ Probability[Lower bound : Upper bound : Stride], ... }
```

Performs better than previous static branch prediction heuristics