

EECS 230
ENGINEERING ELECTROMAGNETICS
Leland Pierce

Transmission Lines 8

Announcements

post-lab2 and pre-lab3 are due this sunday night

exam1: monday, oct 7, 5-6:20pm (80 minutes)

alternate: tuesday, oct 8, 5-6:20pm rooms: TBD

email me if you want to take the alternate.

those in monday lab can take the alternate, I hope

coverage: chapters 1-2

thru today's lecture/homework

4 problems, similar to homework

3-page formula sheet on canvas (will be provided)

bring handwritten single page

bring calculator, ruler, compass, pencils

Chapter 2 Overview

What is a transmission line?

Why study transmission lines?

model

diffeq

solve diffeq

wave propagation

lossless transmission line

microstrip lines

reflections

standing waves

impedance

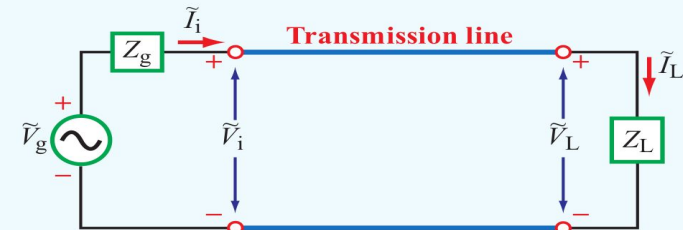
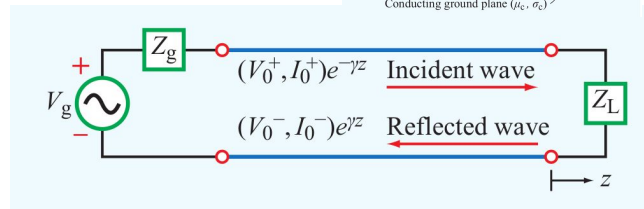
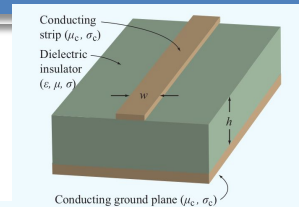
short, open

matching

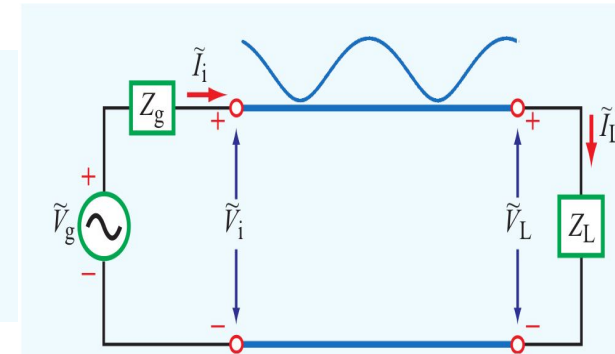
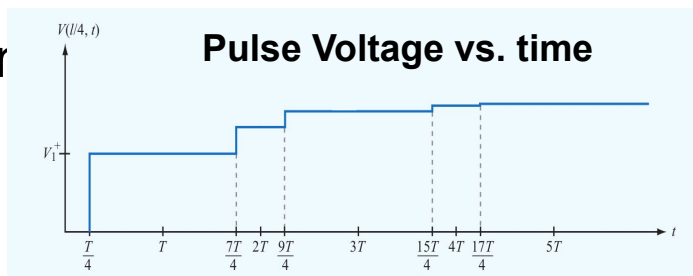
power flow

smith chart

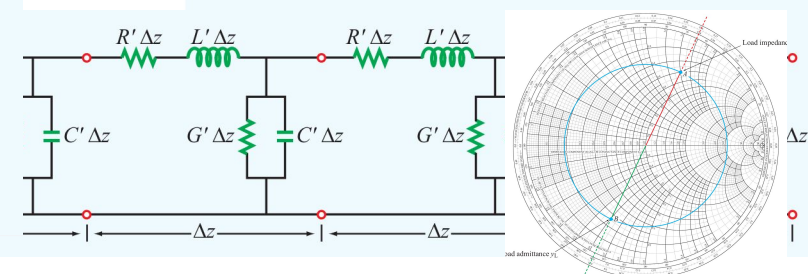
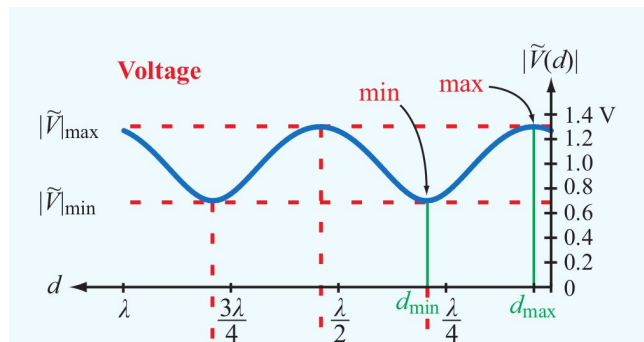
transients



Typical High-Frequency Circuit



Waves on line: old methods don't work



Today's Lecture Coverage

Review Sections 2-1 through 2-10 of the book:

2-1: What is a transmission line? Why study transmission lines?

2-2: Lumped-Element Model

2-3: Governing Differential Eqns

2-4: Solve the Differential Equations

Properties of the solution: wave propagation

2-5: Lossless Microstrip Line

2-6: Lossless Transmission Lines

2-7: Lossless Transmission Lines: Wave Impedance

2-8: Lossless Transmission Lines: Special Cases

2-9: Lossless Transmission Lines: Power Flow

2-10: The Smith Chart

2-11: Matching using the Smith Chart

Sections 2-11, 2-12 of the book:

2-11: Matching using the Smith Chart

2-12: Transients on Transmission Lines

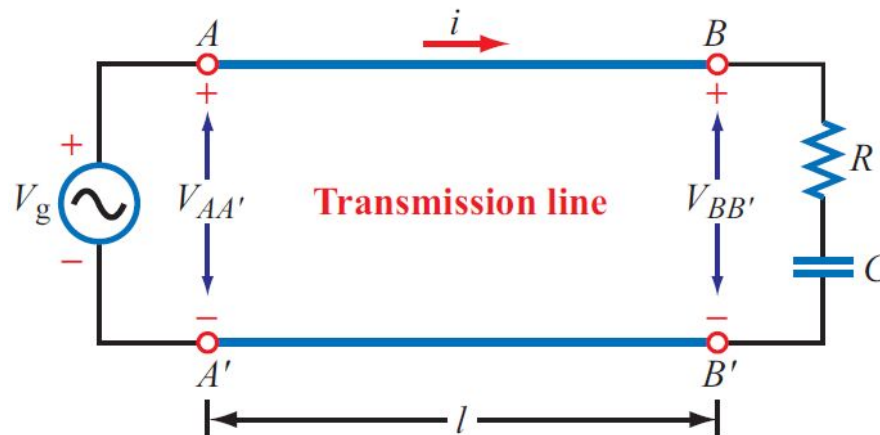
Chapter 2 Review

- A transmission line connects a **generator** to a **load**.



Chapter 2 Review

Phase Delay due to length of transmission line:



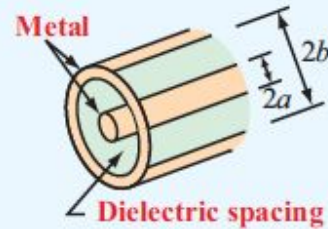
$$\phi_0 = \frac{\omega l}{c} = \frac{2\pi f l}{c} = 2\pi \frac{l}{\lambda} \text{ radians.}$$

$l/\lambda \lesssim 0.01$: Can ignore transmission-line effects

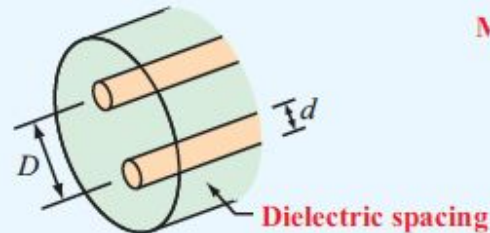
$l/\lambda \gtrsim 0.01$: Must deal with phase shift, and other effects...

Chapter 2 Review

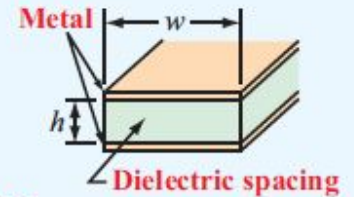
Different geometries for transmission lines



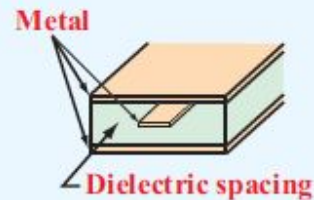
(a) Coaxial line



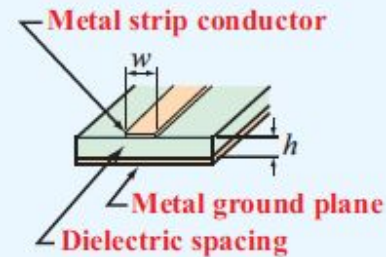
(b) Two-wire line



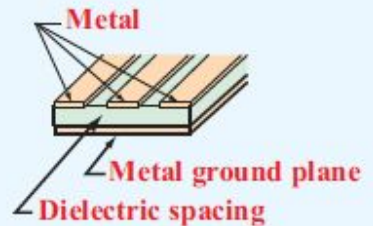
(c) Parallel-plate line



(d) Strip line

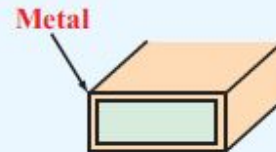


(e) Microstrip line

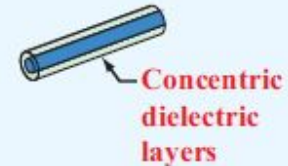


(f) Coplanar waveguide

TEM Transmission Lines



(g) Rectangular waveguide

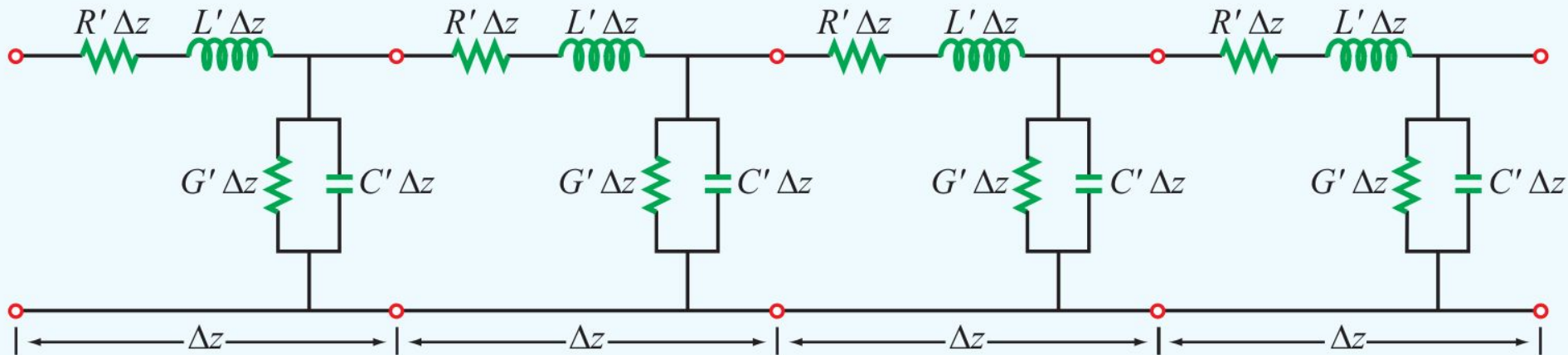


(h) Optical fiber

Higher-Order Transmission Lines

Chapter 2 Review

Lumped-Element Model:



All parameters are "per unit length":

R': Combined Resistance of BOTH conductors: \square/m

L': Combined Inductance of BOTH conductors, H/m

G': Conductance of insulation

between inner and outer conductor, S/m

C': Capacitance

between inner and outer conductors, F/m

Chapter 2 Review

Lumped-Element Values: geometry/materials/freq

Table 2-1 Transmission-line parameters R' , L' , G' , and C' for three types of lines.

Parameter	Coaxial	Two-Wire	Parallel-Plate	Unit
R'	$\frac{R_s}{2\pi} \left(\frac{1}{a} + \frac{1}{b} \right)$	$\frac{2R_s}{\pi d}$	$\frac{2R_s}{w}$	Ω/m
L'	$\frac{\mu}{2\pi} \ln(b/a)$	$\frac{\mu}{\pi} \ln \left[(D/d) + \sqrt{(D/d)^2 - 1} \right]$	$\frac{\mu h}{w}$	H/m
G'	$\frac{2\pi\sigma}{\ln(b/a)}$	$\frac{\pi\sigma}{\ln \left[(D/d) + \sqrt{(D/d)^2 - 1} \right]}$	$\frac{\sigma w}{h}$	S/m
C'	$\frac{2\pi\epsilon}{\ln(b/a)}$	$\frac{\pi\epsilon}{\ln \left[(D/d) + \sqrt{(D/d)^2 - 1} \right]}$	$\frac{\epsilon w}{h}$	F/m

$$R_s = \sqrt{\pi f \mu_c / \sigma_c}$$

Chapter 2 Review

Transmission-line governing Differential Equations

$$-\frac{d\tilde{V}(z)}{dz} = (R' + j\omega L') \tilde{I}(z),$$
$$-\frac{d\tilde{I}(z)}{dz} = (G' + j\omega C') \tilde{V}(z).$$

(telegrapher's equations in phasor form)

Chapter 2 Review

Transmission-line governing Differential Equation for V :

$$\frac{d^2 \tilde{V}(z)}{dz^2} - \gamma^2 \tilde{V}(z) = 0,$$

(wave equation for $\tilde{V}(z)$)

$$\gamma = \sqrt{(R' + j\omega L')(G' + j\omega C')}.$$

(propagation constant)

Chapter 2 Review

Complex propagation constant:

$$\gamma = \alpha + j\beta$$

Where:

γ : Units of 1/m

α : Attenuation constant, units of Np/m (>0 in this class)

β : Phase constant, units of rad/m

Np and radians are both "dimensionless", and are the conventional "units" for these parameters.

Chapter 2 Review

Form of the solution: traveling waves, going in both directions:

$$\tilde{V}(z) = V_0^+ e^{-\gamma z} + V_0^- e^{\gamma z} \quad (\text{V}),$$

$$\tilde{I}(z) = \frac{V_0^+}{Z_0} e^{-\gamma z} - \frac{V_0^-}{Z_0} e^{\gamma z} \quad (\text{A}).$$

$$Z_0 = \frac{R' + j\omega L'}{\gamma} = \sqrt{\frac{R' + j\omega L'}{G' + j\omega C'}} \quad (\Omega),$$

Chapter 2 Review

Solution in time-domain

$$v(z, t) = |V_0^+| e^{-\alpha z} \cos(\omega t - \beta z + \phi^+) \\ + |V_0^-| e^{+\alpha z} \cos(\omega t + \beta z + \phi^-)$$

Remaining unknowns are determined via specification of source and load.

Chapter 2 Review

- The wave equation for a general Transmission Line.

$$\frac{d^2 \tilde{V}(z)}{dz^2} - \gamma^2 \tilde{V}(z) = 0, \quad (2.21)$$

- General solution of the wave equation
 - *It involves both incident and reflected waves*

$$\tilde{V}(z) = V_0^+ e^{-\gamma z} + V_0^- e^{\gamma z} \quad (\text{V}),$$

$$\tilde{I}(z) = I_0^+ e^{-\gamma z} + I_0^- e^{\gamma z} \quad (\text{A}).$$

Chapter 2 Review

- Useful Relations for lossless Transmission Lines:

$$\alpha = 0 \quad (\text{lossless line}),$$
$$\beta = \omega\sqrt{L'C'} \quad (\text{lossless line}). \quad (2.45)$$

$$\beta = \omega\sqrt{\mu\varepsilon} \quad (\text{rad/m}), \quad (2.49)$$

$$u_p = \frac{1}{\sqrt{\mu_0\varepsilon_0}} \frac{1}{\sqrt{\varepsilon_r}} = \frac{c}{\sqrt{\varepsilon_r}}$$

$$\lambda = \frac{u_p}{f} = \frac{c}{f} \frac{1}{\sqrt{\varepsilon_r}} = \frac{\lambda_0}{\sqrt{\varepsilon_r}}$$

$$Z_0 = \sqrt{\frac{L'}{C'}} \quad (\text{lossless line}), \quad (2.46) \quad (\text{REAL})$$

Chapter 2 Review

- Voltage reflection coefficient due to load:

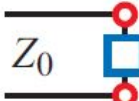

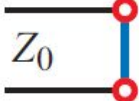
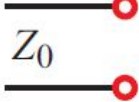
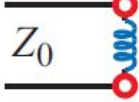
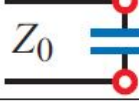
$$\begin{aligned}\Gamma &= \frac{V_0^-}{V_0^+} = \frac{Z_L - Z_0}{Z_L + Z_0} \\ &= \frac{Z_L/Z_0 - 1}{Z_L/Z_0 + 1} \\ &= \frac{z_L - 1}{z_L + 1}\end{aligned}$$

- Load impedance in terms of Γ :

$$Z_L = \frac{1 + \Gamma}{1 - \Gamma} Z_0$$

Chapter 2 Review

Reflection Coefficient $\Gamma = |\Gamma|e^{j\theta_r}$

Load	$ \Gamma $	θ_r
 $Z_L = (r + jx)Z_0$	$\left[\frac{(r - 1)^2 + x^2}{(r + 1)^2 + x^2} \right]^{1/2}$	$\tan^{-1} \left(\frac{x}{r - 1} \right) - \tan^{-1} \left(\frac{x}{r + 1} \right)$
 Z_0	0 (no reflection)	irrelevant
 (short)	1	$\pm 180^\circ$ (phase opposition)
 (open)	1	0 (in-phase)
 $jX = j\omega L$	1	$\pm 180^\circ - 2 \tan^{-1} x$
 $jX = \frac{-j}{\omega C}$	1	$\pm 180^\circ + 2 \tan^{-1} x$

$$z_L = Z_L/Z_0 = (R + jX)/Z_0 = r + jx$$

Chapter 2 Review

- Concept of standing wave

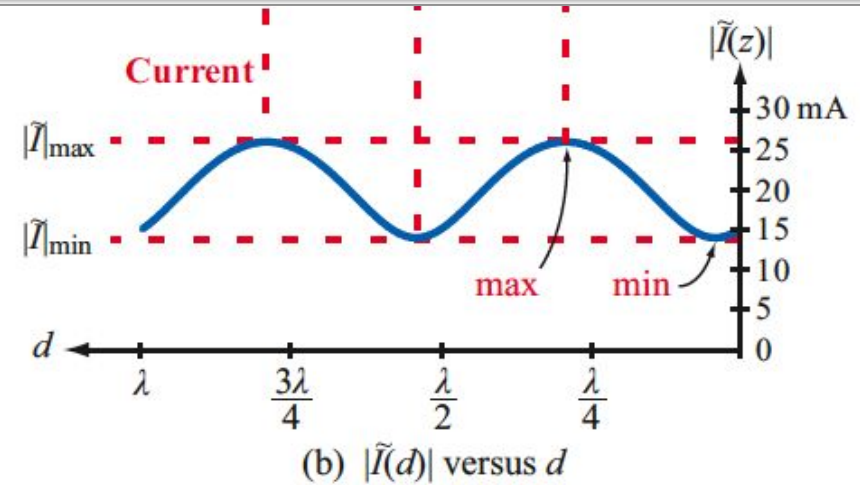
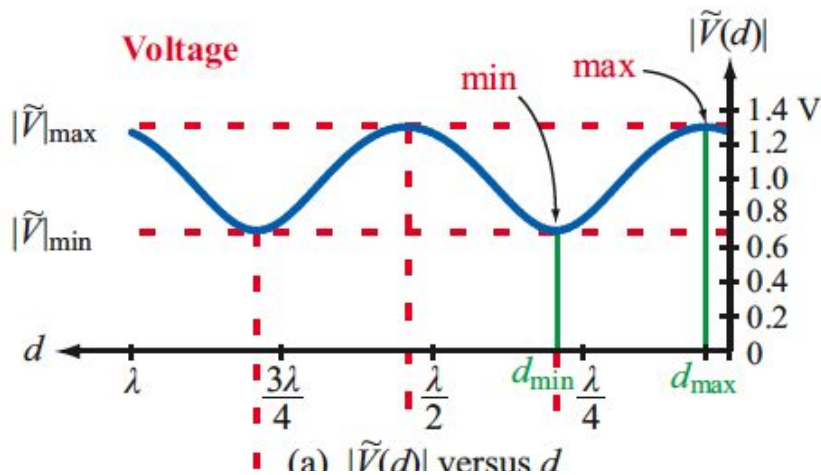
$$\tilde{V}(z) = V_0^+ (e^{-j\beta z} + \Gamma e^{j\beta z}),$$

$$\tilde{I}(z) = \frac{V_0^+}{Z_0} (e^{-j\beta z} - \Gamma e^{j\beta z}).$$

- Voltage (current) magnitudes at any point on line:

$$|\tilde{V}(d)| = |V_0^+| \left[1 + |\Gamma|^2 + 2|\Gamma| \cos(2\beta d - \theta_r) \right]^{1/2}. \quad (2.66)$$

Chapter 2 Review



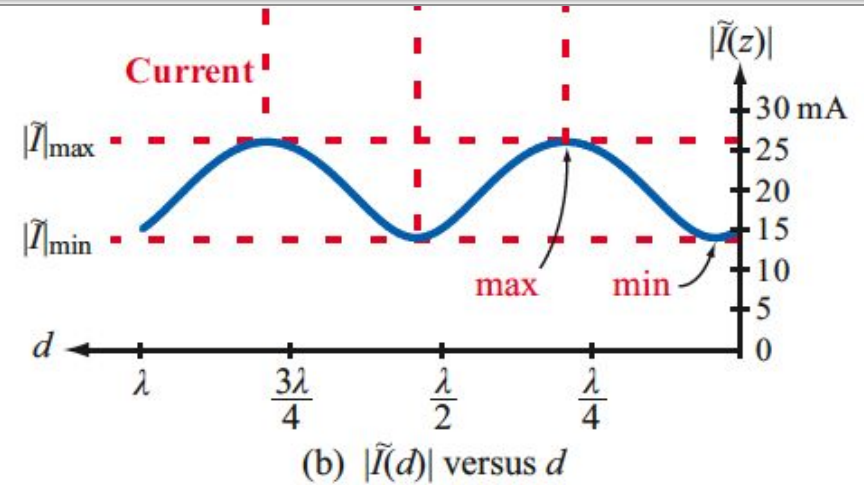
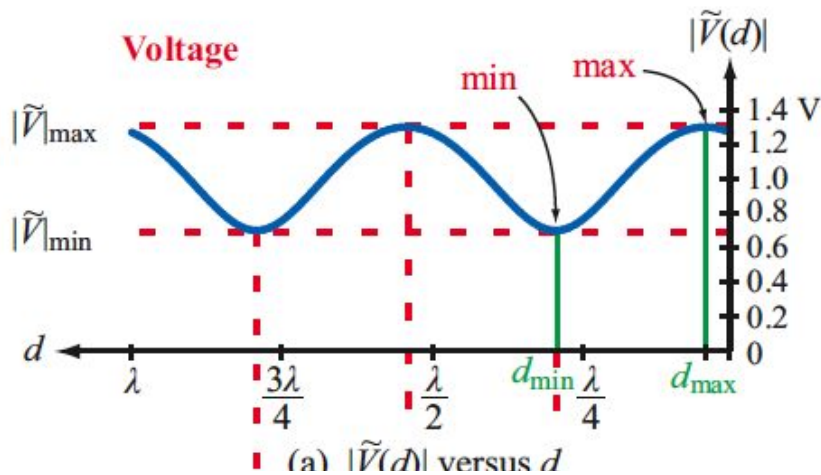
- Location of minima / maxima

$$d_{\max} = \frac{\theta_r + 2n\pi}{2\beta} = \frac{\theta_r \lambda}{4\pi} + \frac{n\lambda}{2},$$

$$\begin{cases} n = 1, 2, \dots & \text{if } \theta_r < 0, \\ n = 0, 1, 2, \dots & \text{if } \theta_r \geq 0, \end{cases} \quad (2.70)$$

Value of V_{\max} : $|\tilde{V}(d)| = |\tilde{V}|_{\max} = |V_0^+| [1 + |\Gamma|],$

Chapter 2 Review



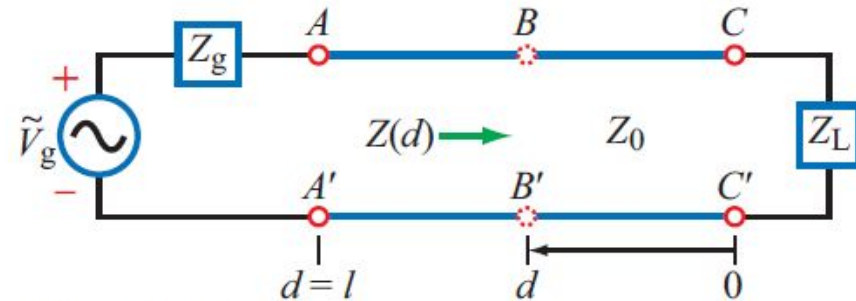
- Spatial period of standing wave: $\frac{\lambda}{2}$
- Standing wave ratio S:

$$S = \frac{|\tilde{V}|_{\max}}{|\tilde{V}|_{\min}} = \frac{1 + |\Gamma|}{1 - |\Gamma|}$$

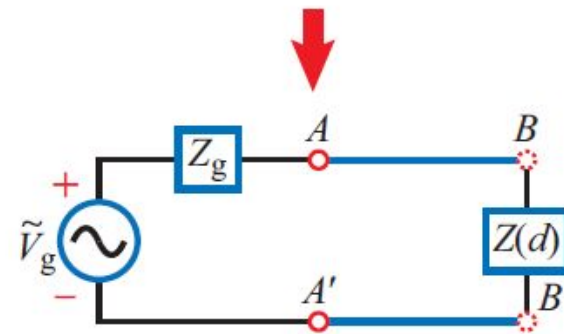
Chapter 2 Review

Wave Impedance:
At a distance d from the load:

$$\begin{aligned}
 Z(d) &= \frac{\tilde{V}(d)}{\tilde{I}(d)} \\
 &= \frac{V_0^+ [e^{j\beta d} + \Gamma e^{-j\beta d}]}{V_0^+ [e^{j\beta d} - \Gamma e^{-j\beta d}]} Z_0 \\
 &= Z_0 \left[\frac{1 + \Gamma e^{-j2\beta d}}{1 - \Gamma e^{-j2\beta d}} \right] \\
 &= Z_0 \left[\frac{1 + \Gamma_d}{1 - \Gamma_d} \right] \quad (\Omega),
 \end{aligned}$$



(a) Actual circuit



(b) Equivalent circuit

Chapter 2 Review

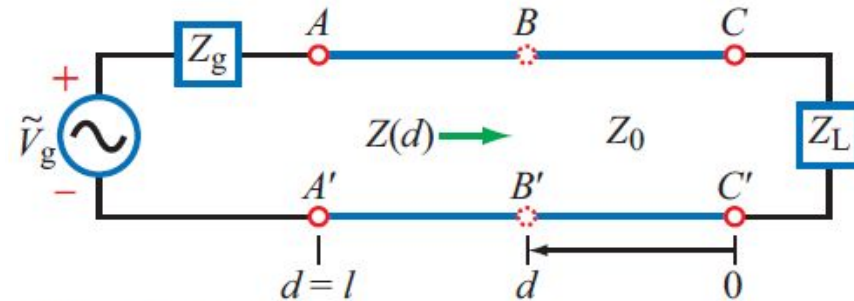
Define the phase-shifted voltage reflection coefficient:

$$\Gamma_d = \Gamma e^{-j2\beta d} = |\Gamma| e^{j\theta_r} e^{-j2\beta d}$$

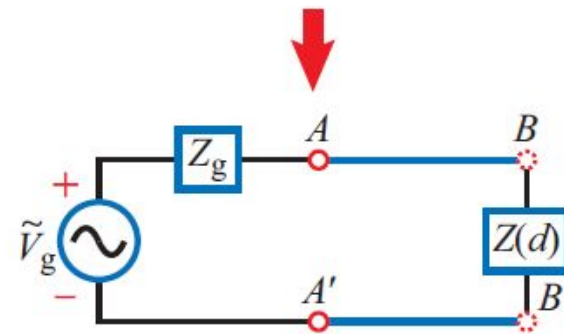
$$= |\Gamma| e^{j(\theta_r - 2\beta d)}$$

$Z(d)$ is different than Z_0 :
Ratio of **Total** Voltage and
Current

Recall: $Z_0 = \frac{V_0^+}{I_0^+}$

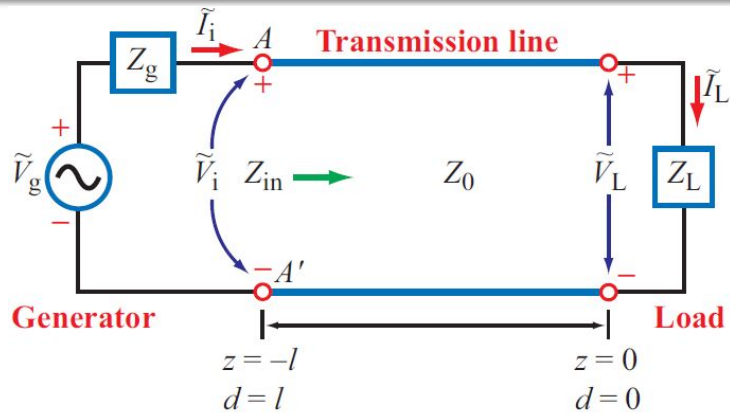


(a) Actual circuit



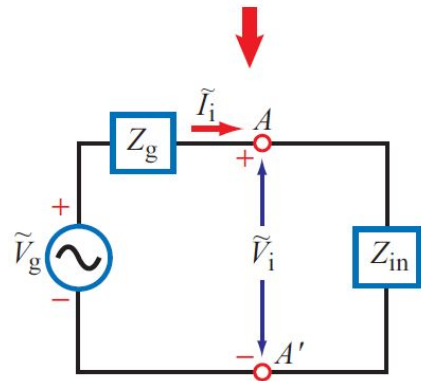
(b) Equivalent circuit

Chapter 2 Review



Input impedance:
impedance of the transmission
line at $d=l$:

$$Z_{in} = Z(d=l) = \frac{\tilde{V}(d=l)}{\tilde{I}(d=l)}$$

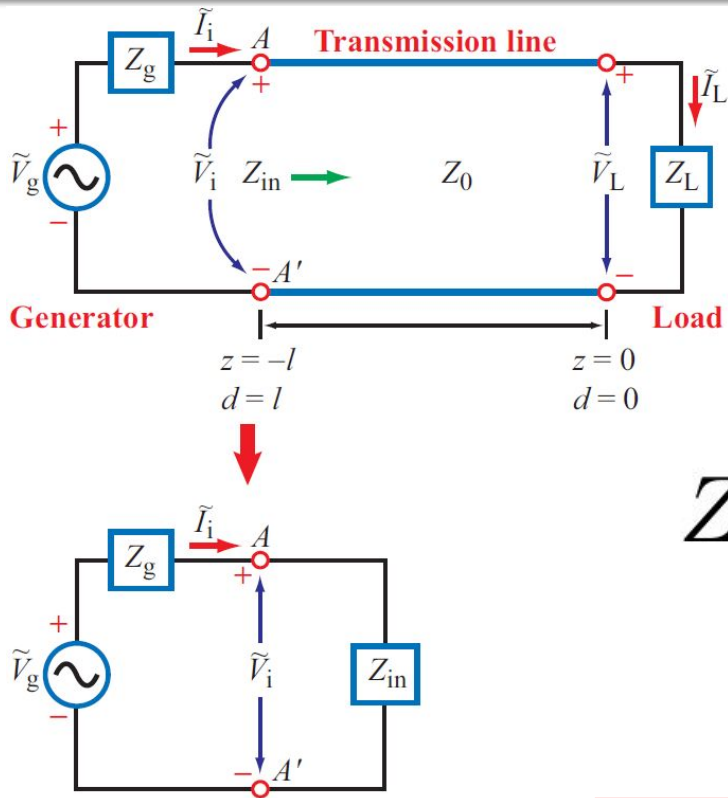


Note that Z_{in} is different from the
Characteristic Impedance, and is different
from the Load Impedance:

$$Z_{in} \neq Z_0$$

$$Z_{in} \neq Z_L$$

Chapter 2 Review

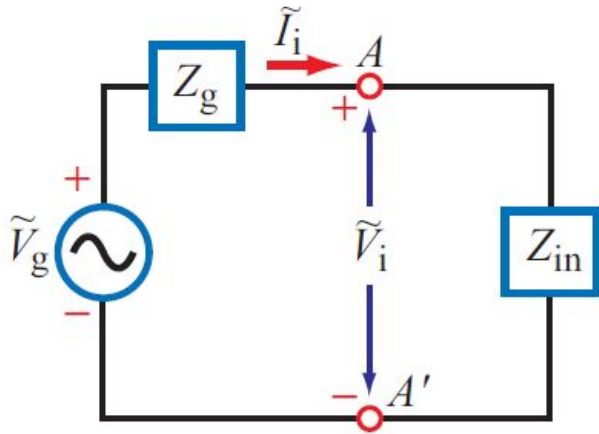


Input impedance:
impedance of the transmission line at $d=l$:

$$Z_{in} = Z(d = l) = \frac{\tilde{V}(d = l)}{\tilde{I}(d = l)}$$

$$Z_{in} = Z_0 \left[\frac{z_L + j \tan(\beta l)}{1 + j z_L \tan(\beta l)} \right]$$

Chapter 2 Review



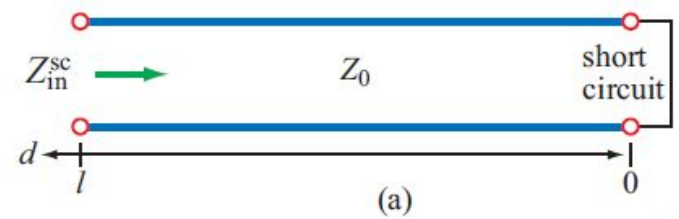
Voltage Amplitude:

$$V_0^+ = \left(\frac{\tilde{V}_g Z_{in}}{Z_g + Z_{in}} \right) \left(\frac{1}{e^{j\beta l} + \Gamma e^{-j\beta l}} \right).$$

We used the boundary conditions (Z_L , Z_g , V_g , I) to solve for the 2 unknowns.

This completes the solution of the transmission line differential equation.

Chapter 2 Review



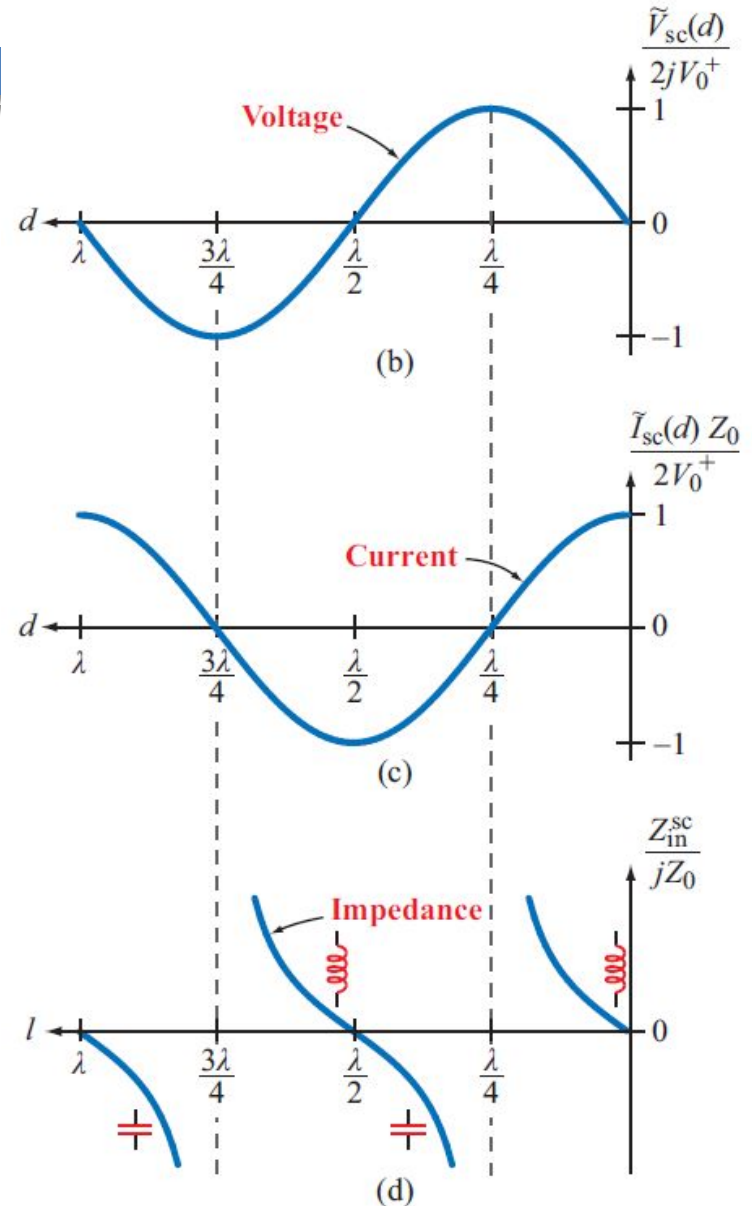
For the short-circuited line:

$$\Gamma = -1$$

$$\tilde{V}_{sc}(d) = 2jV_0^+ \sin \beta d,$$

$$\tilde{I}_{sc}(d) = \frac{2V_0^+}{Z_0} \cos \beta d,$$

$$Z_{sc}(d) = \frac{\tilde{V}_{sc}(d)}{\tilde{I}_{sc}(d)} = jZ_0 \tan \beta d.$$



Chapter 2 Review

At its input, the short-circuited line appears like an inductor or a capacitor depending on the sign of

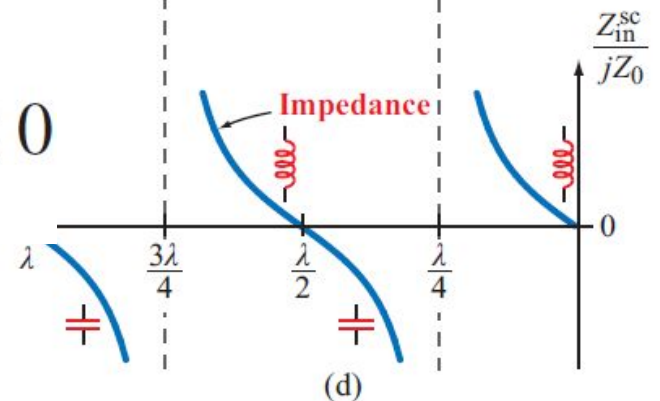
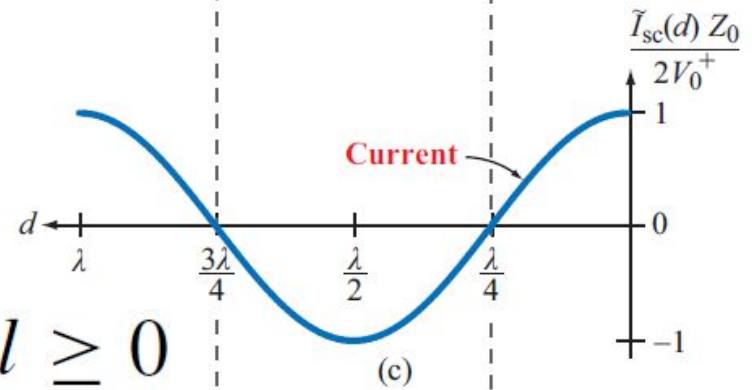
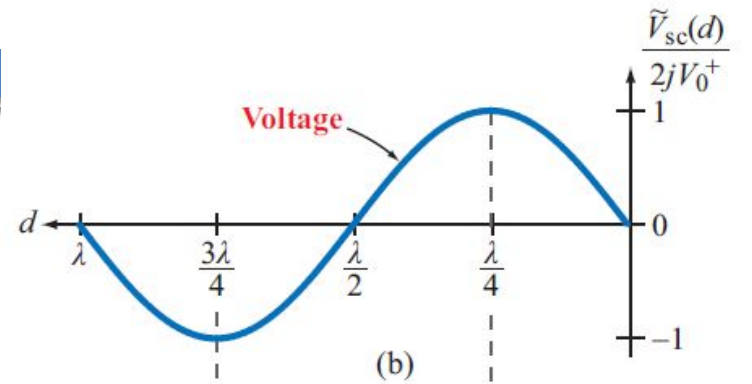
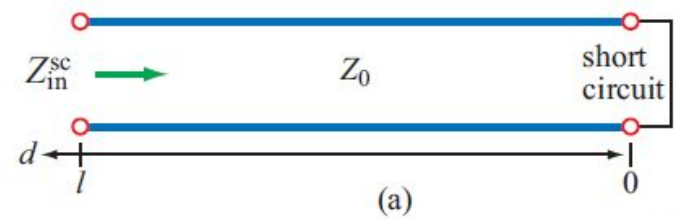
$$\tan \beta d$$

$$j\omega L_{\text{eq}} = jZ_0 \tan \beta l, \quad \text{if } \tan \beta l \geq 0$$

$$\text{if } \tan \beta l \geq 0$$

$$\frac{1}{j\omega C_{\text{eq}}} = jZ_0 \tan \beta l, \quad \text{if } \tan \beta l \leq 0$$

$$\text{if } \tan \beta l \leq 0$$



Chapter 2 Review

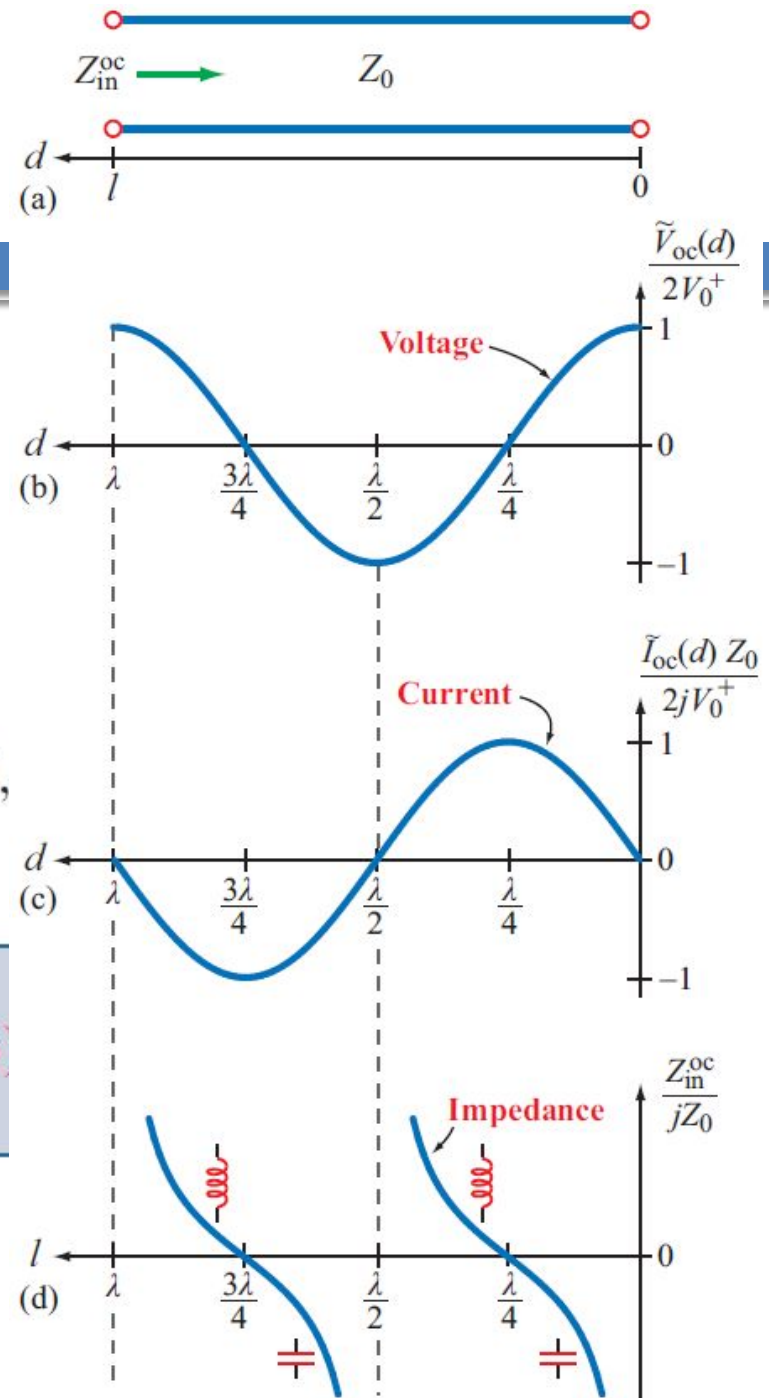
Open-circuited Line:

$$\Gamma = 1$$

$$\tilde{V}_{oc}(d) = V_0^+ [e^{j\beta d} + e^{-j\beta d}] = 2V_0^+ \cos \beta d,$$

$$\tilde{I}_{oc}(d) = \frac{V_0^+}{Z_0} [e^{j\beta d} - e^{-j\beta d}] = \frac{2jV_0^+}{Z_0} \sin \beta d,$$

$$Z_{in}^{oc} = \frac{\tilde{V}_{oc}(l)}{\tilde{I}_{oc}(l)} = -jZ_0 \cot \beta l. \quad (2.93)$$



Chapter 2 Review

Short-Circuit/Open-Circuit Method:

- Given length l
- Measure Z_{in} twice:
 - when terminated in a short
 - when terminated in an open

Use both: get Z_0, β :

$$Z_{in}^{sc} = \frac{\tilde{V}_{sc}(l)}{\tilde{I}_{sc}(l)} = jZ_0 \tan \beta l.$$

$$Z_{in}^{oc} = \frac{\tilde{V}_{oc}(l)}{\tilde{I}_{oc}(l)} = -jZ_0 \cot \beta l.$$



$$Z_0 = \sqrt{Z_{in}^{sc} Z_{in}^{oc}},$$

$$\tan \beta l = \sqrt{\frac{-Z_{in}^{sc}}{Z_{in}^{oc}}}.$$

Chapter 2 Review

Half-Wavelength Line:

$$Z_{\text{in}} = Z_0 \left(\frac{z_L + j \tan(\beta l)}{1 + j z_L \tan(\beta l)} \right)$$

If $l = n\lambda/2$, where n is an integer,

$$\tan \beta l = \tan [(2\pi/\lambda) (n\lambda/2)] = \tan n\pi = 0.$$

Consequently, Eq. (2.79) reduces to

$$Z_{\text{in}} = Z_L, \quad \text{for } l = n\lambda/2, \quad (2.96)$$

which means that a half-wavelength line (or any integer multiple of $\lambda/2$) does not modify the load impedance.

Chapter 2 Review

Quarter-Wavelength Line:

$$Z_{\text{in}} = Z_0 \left(\frac{z_L + j \tan(\beta l)}{1 + j z_L \tan(\beta l)} \right)$$

For $l = \lambda/4$, $\beta l = (2\pi/\lambda)(\lambda/4) = \pi/2$

So, as $\beta l \rightarrow \pi/2$, $\tan(\beta l) \rightarrow \infty$

$$\lim_{\beta l \rightarrow \pi/2} Z_{\text{in}} = Z_0 \left(\frac{j \tan(\beta l)}{j z_L \tan(\beta l)} \right) = \frac{Z_0^2}{Z_L}$$

$$Z_{\text{in}} = \frac{Z_0^2}{Z_L}, \quad \text{for } l = \lambda/4 + n\lambda/2.$$

Chapter 2 Review

Instantaneous Power Flow:

$$P(d, t) = P^i(d, t) + P^r(d, t)$$

The 2 terms are the **Incident** and **Reflected power**:

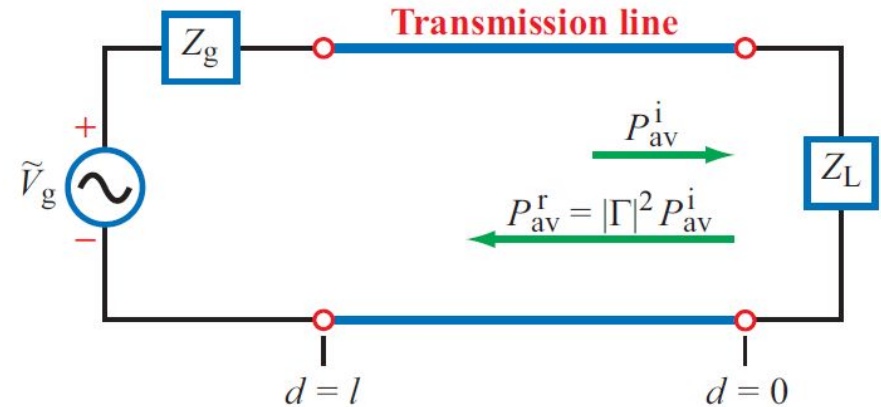
$$P^i(d, t) = \frac{|V_0^+|^2}{2Z_0} [1 + \cos(2\omega t + 2\beta d + 2\phi^+)],$$

$$P^r(d, t) = -|\Gamma|^2 \frac{|V_0^+|^2}{2Z_0} [1 + \cos(2\omega t - 2\beta d + 2\phi^+ + 2\theta_r)].$$

oscillating at **TWICE** the frequency of V or I

Chapter 2 Review

Average Power Flow:



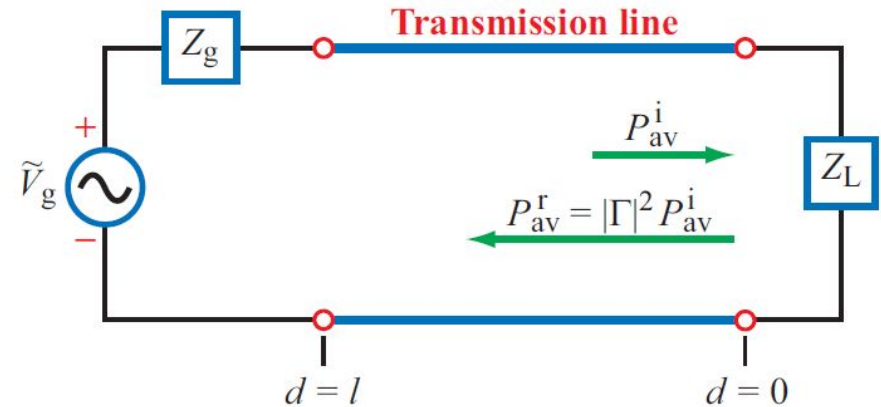
For the **incident** power, average over one period:

$$P_{\text{avg}}^i = \frac{\omega}{2\pi} \int_0^{\frac{2\pi}{\omega}} \frac{|V_0^+|^2}{2Z_0} [1 + \cos(2\omega t + 2\beta d + 2\phi^+)] dt$$

$$\omega = \frac{2\pi}{T}, \quad \text{hence} \quad T = \frac{2\pi}{\omega}$$

Chapter 2 Review

Average Power Flow:

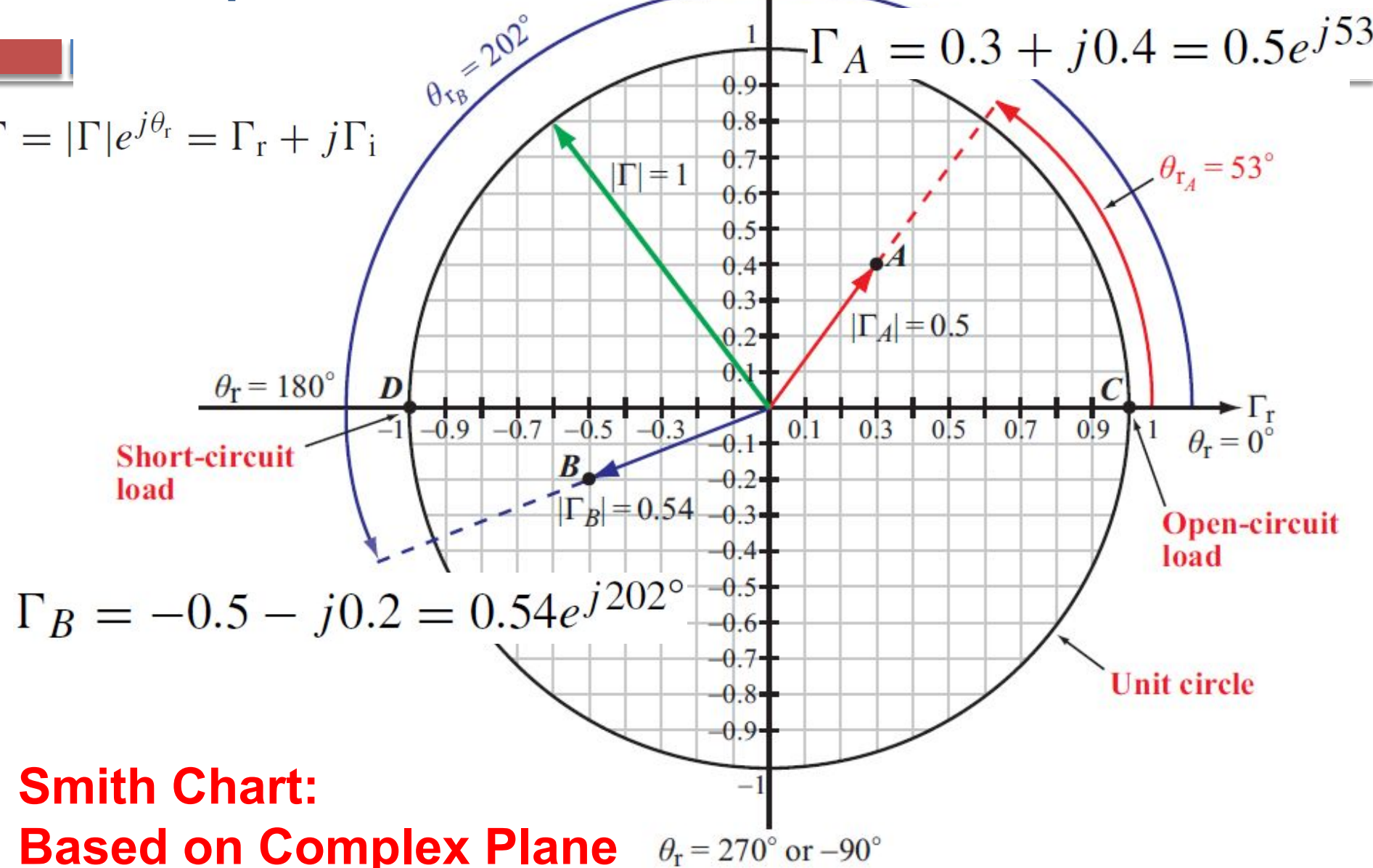


$$P_{avg}^i = \frac{|V_0^+|^2}{2Z_0}$$

$$P_{avg}^r = -|\Gamma|^2 P_{avg}^i$$

Chapter 2 Review

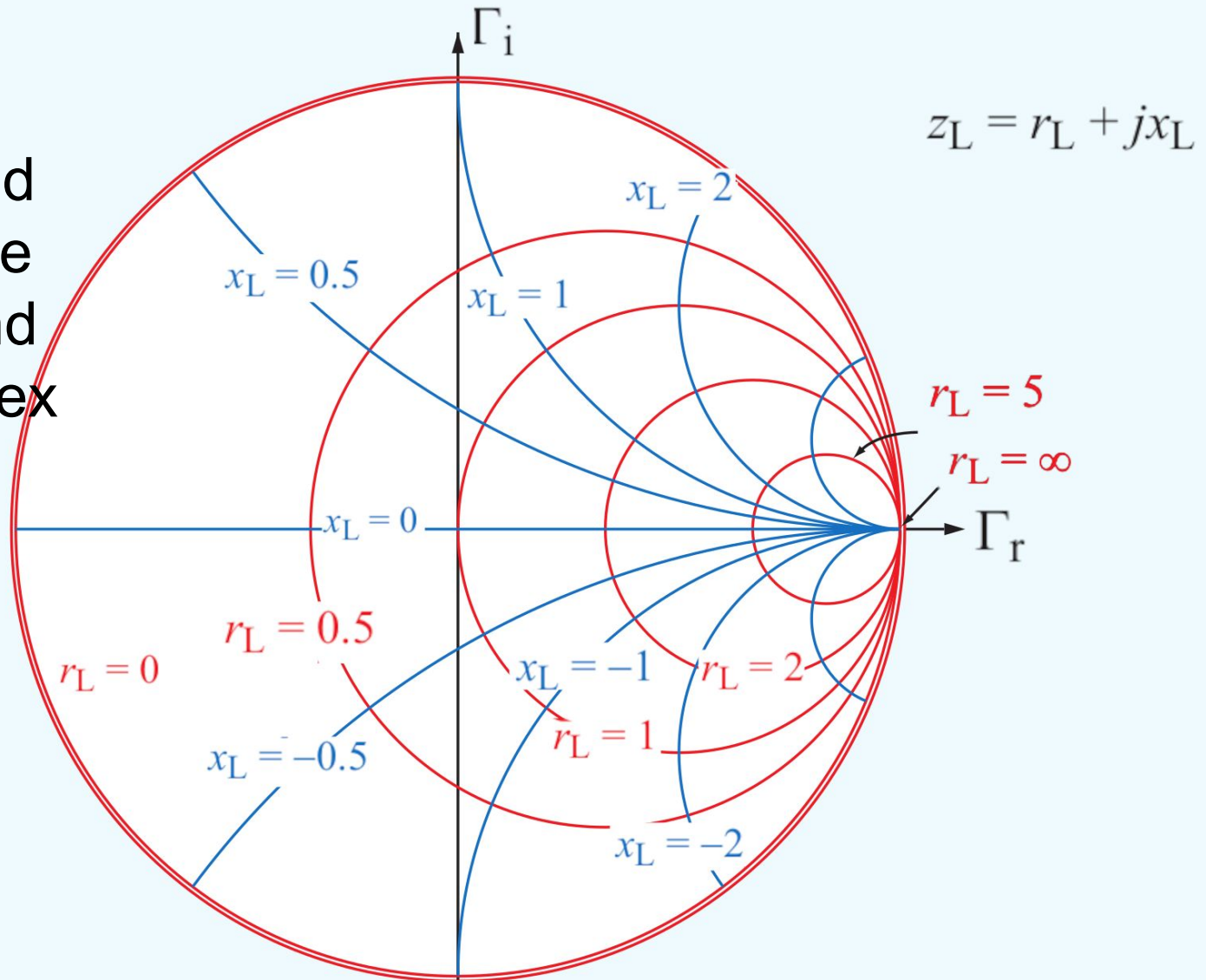
$$\Gamma = |\Gamma|e^{j\theta_r} = \Gamma_r + j\Gamma_i$$



**Smith Chart:
Based on Complex Plane**

Chapter 2 Review

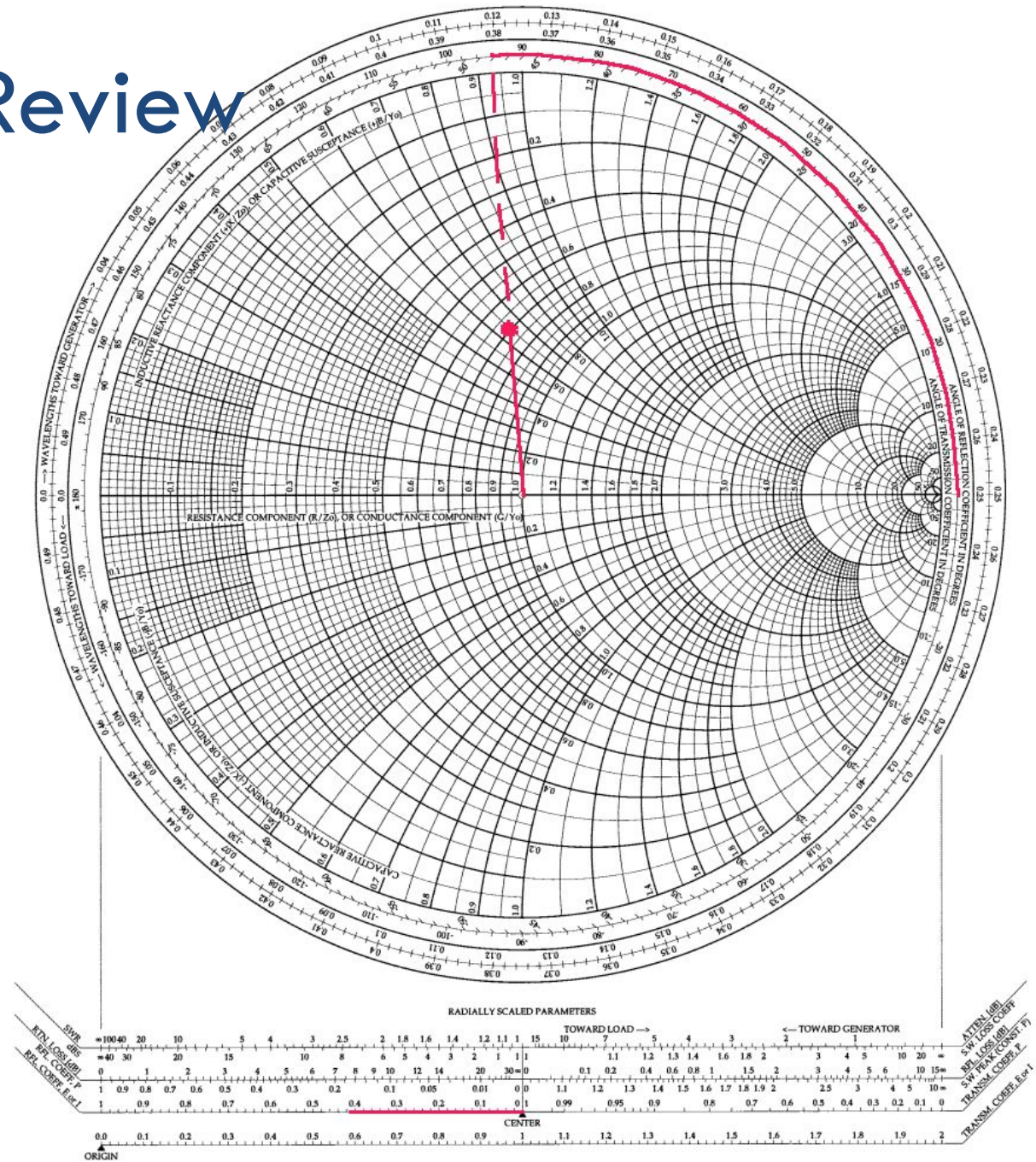
Superimposed
are coordinate
axes for r_L and
 x_L : the complex
load: z_L



Chapter 2 Review

If plotted z_L :
Obtain values for Γ_L
from the angle scale
and magnitude
scale:

0.41, 94°

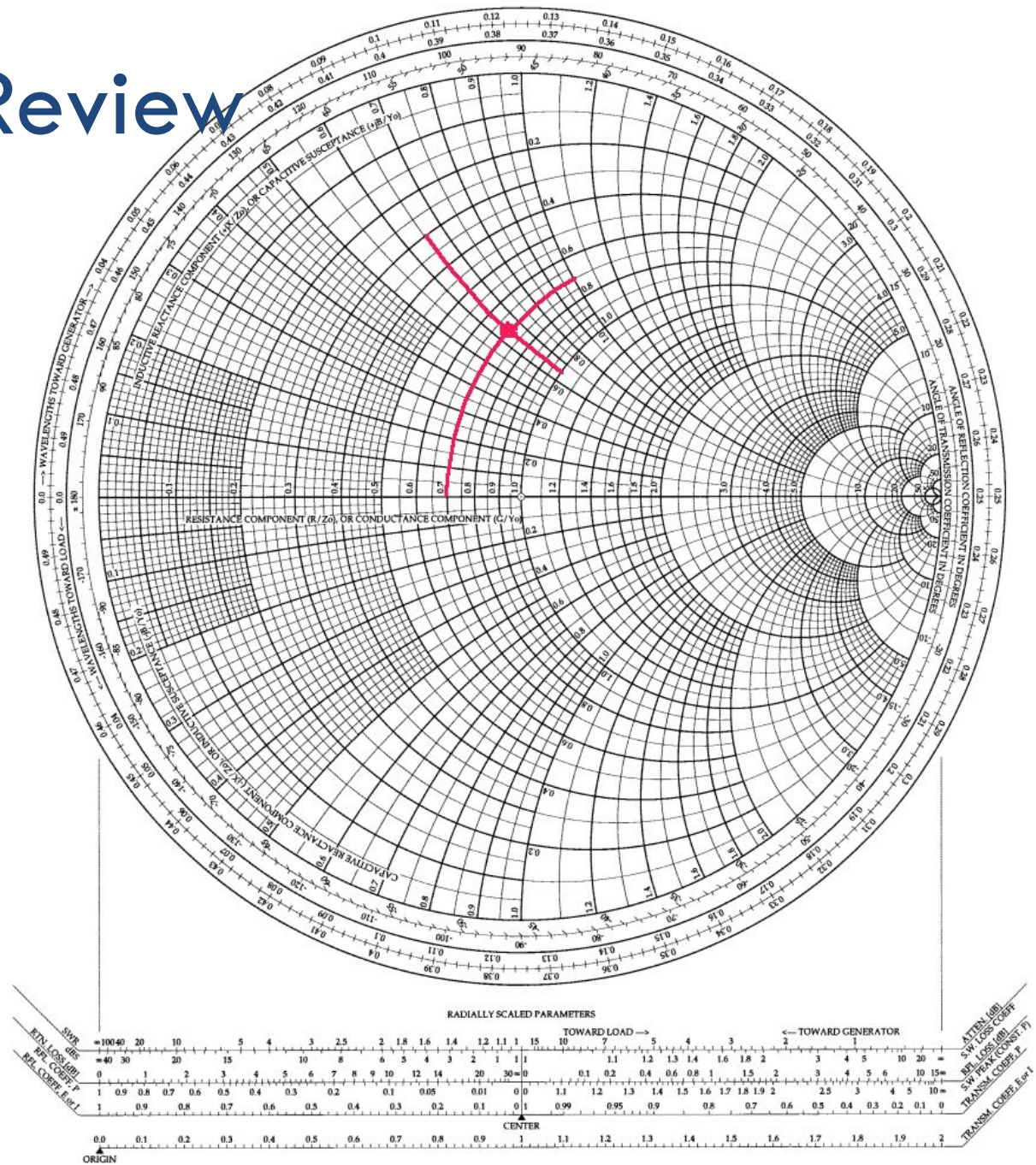


Chapter 2 Review

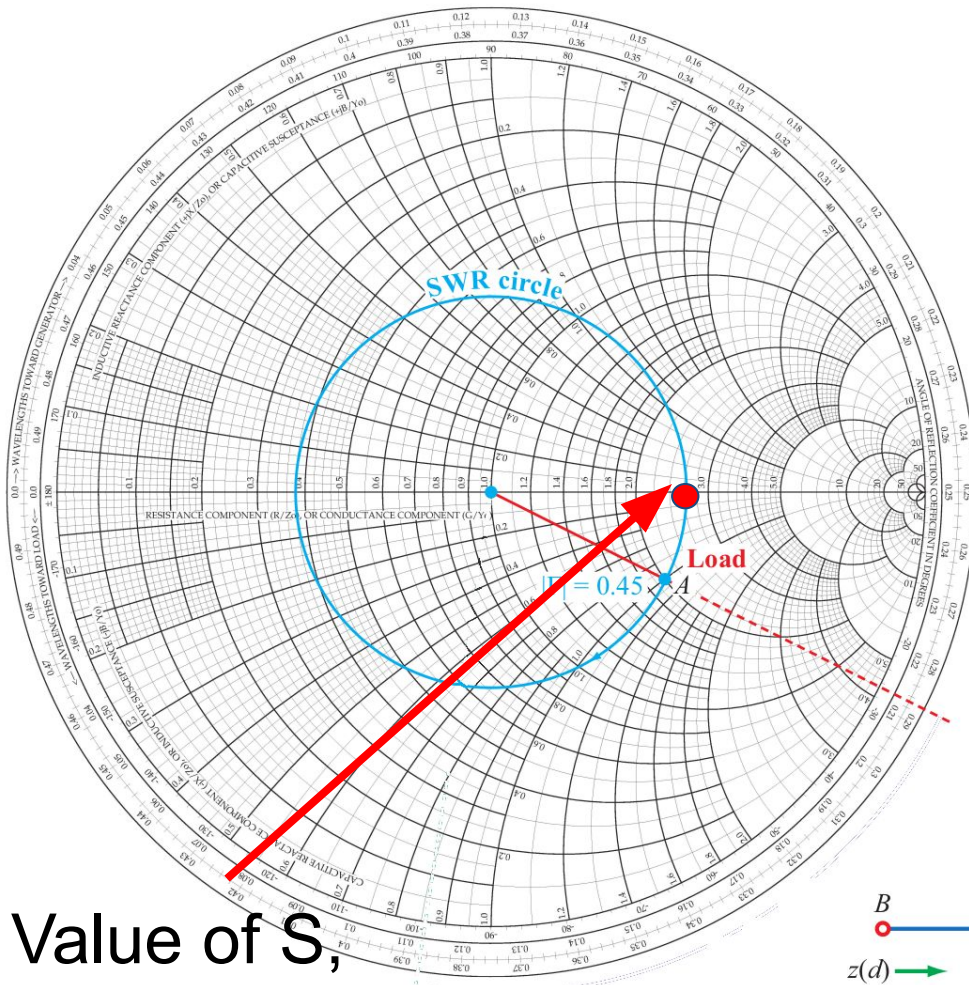
If plotted Γ_L :
Obtain values for
 r_L , x_L from the
nearest circles:

$$z_L = (0.7, 0.65)$$

To get Z_L :
Multiply z_L by Z_0



Chapter 2 Review



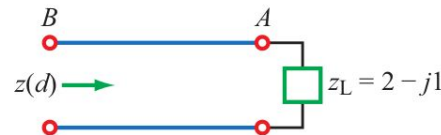
Value of S,
from r_L scale

All points on a circle centered at the origin have the same $|\Gamma|$.

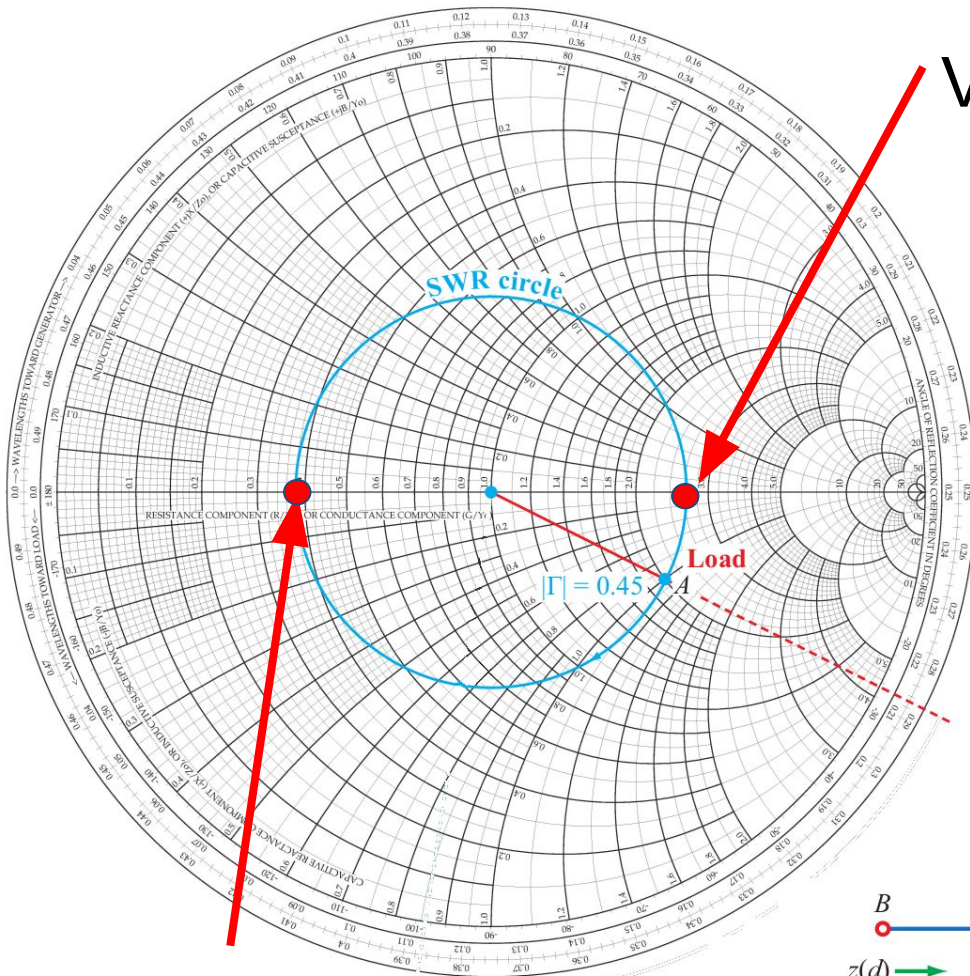
Since

$$S = \frac{1 + |\Gamma|}{1 - |\Gamma|}$$

this is also a circle of constant S (VSWR).

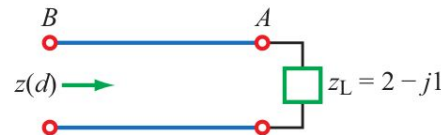


Chapter 2 Review

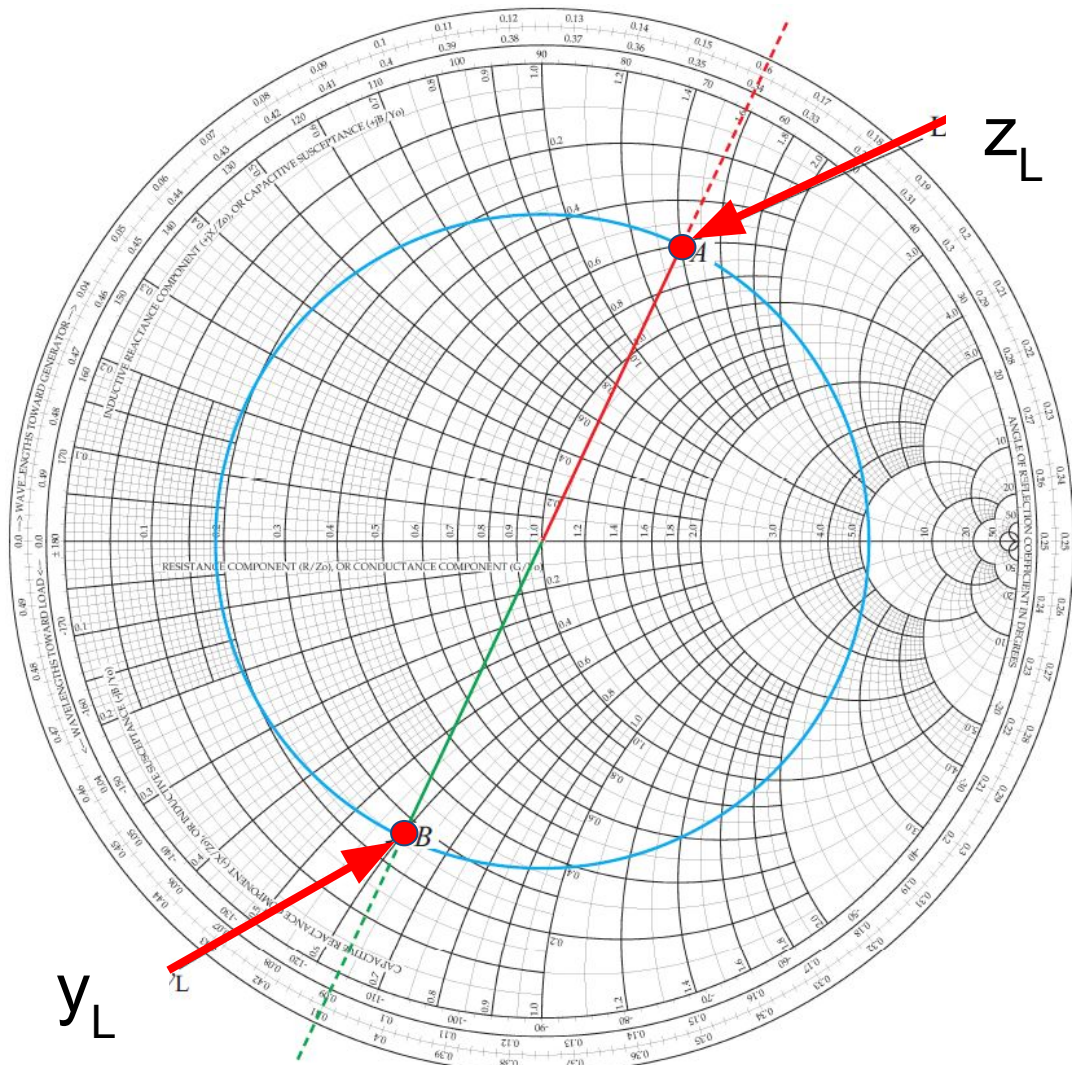


Voltage Maxima position

Voltage Minima position



Chapter 2 Review

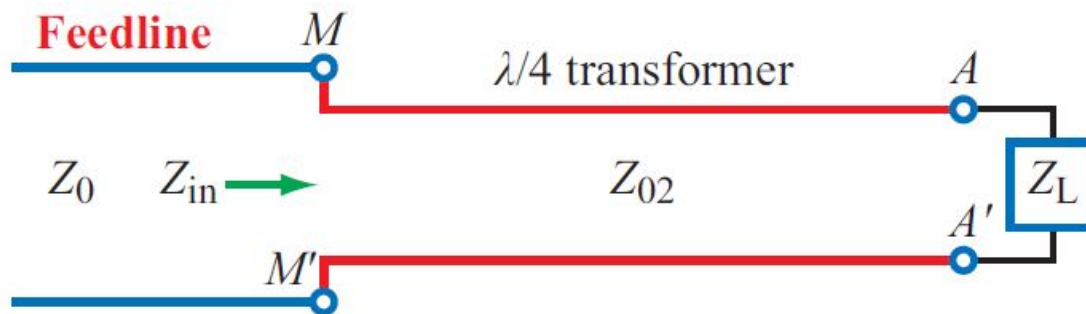


y_L and z_L are inverses of each other.

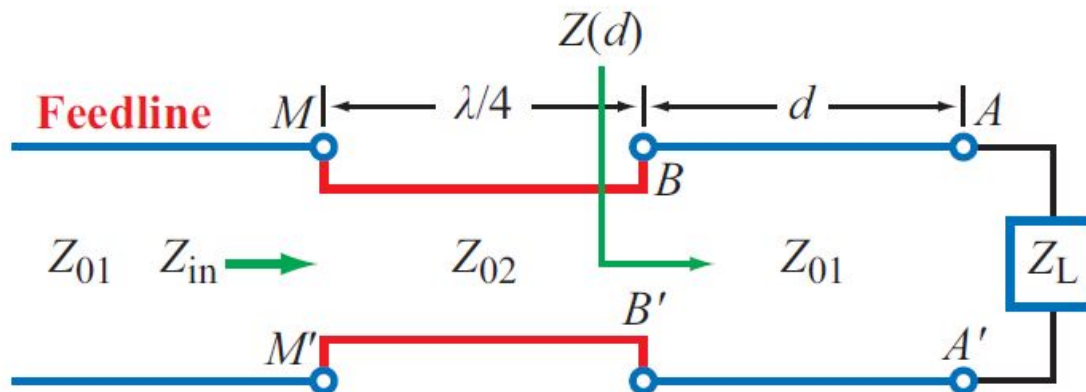
Occur $\lambda/4$ apart on the Smith Chart.

Chapter 2 Review

Example Matching Networks



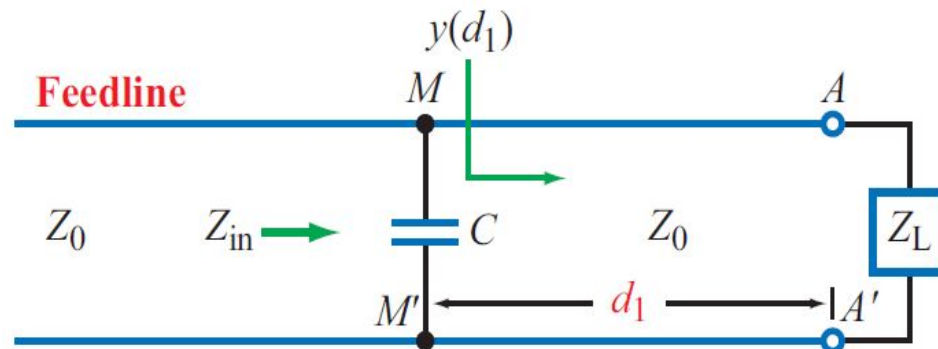
(a) In-series $\lambda/4$ transformer inserted at AA'



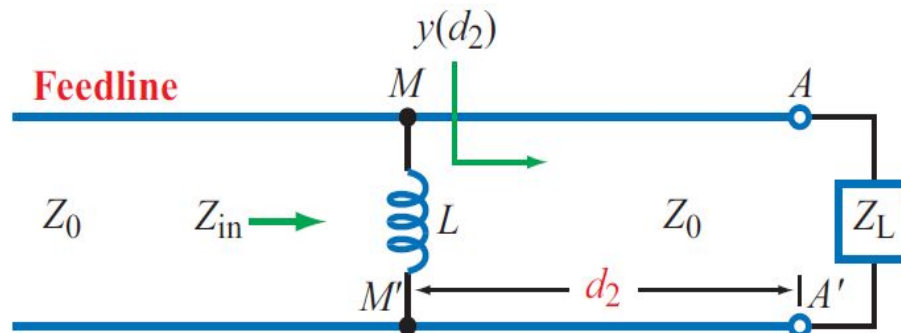
(b) In-series $\lambda/4$ transformer inserted at $d = d_{\max}$ or $d = d_{\min}$

Chapter 2 Review

Example Matching Networks



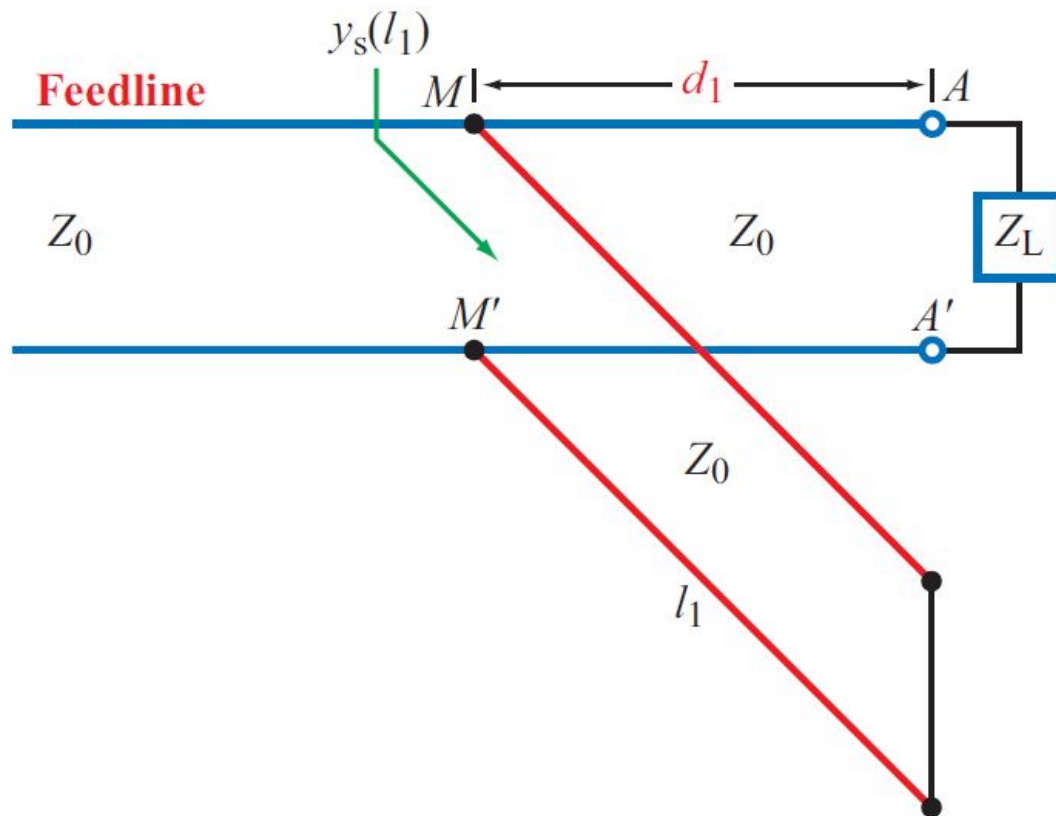
(c) In-parallel insertion of capacitor at distance d_1



(d) In-parallel insertion of inductor at distance d_2

Chapter 2 Review

Example Matching Networks



(e) In-parallel insertion of a short-circuited stub

In General:

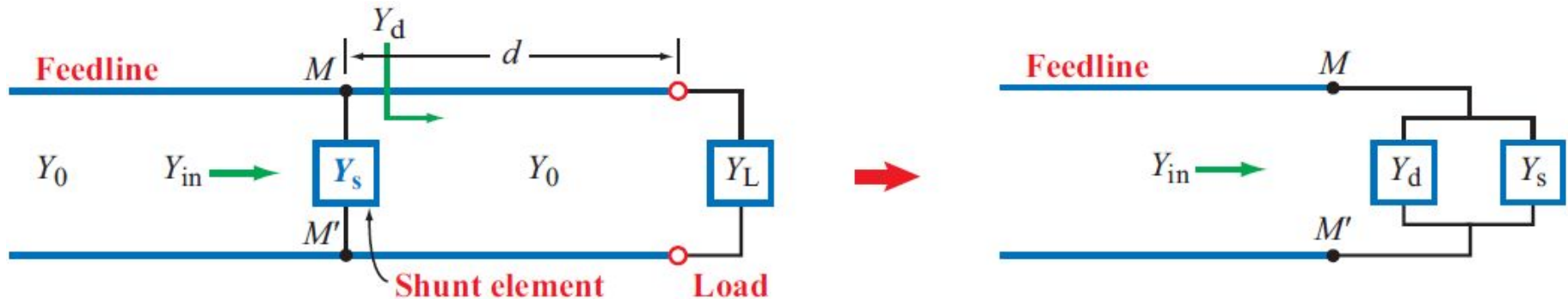
Matching Networks may consist of:

- * lumped elements, or:
- * TL sections,

Placed in

- * series or
- * parallel.

Chapter 2 Review



Lumped-Element matching using admittance

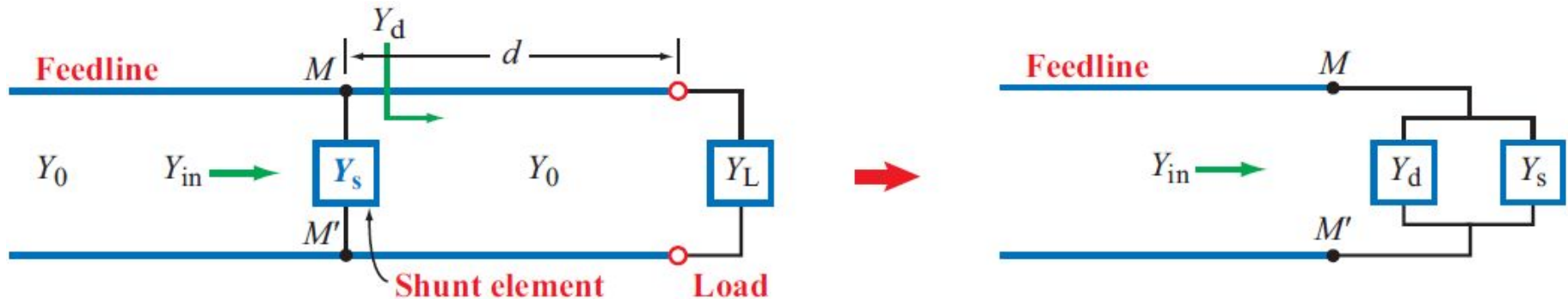
Y_L transformed to Y_d by the length of transmission line

$$Y_{in} = Y_d + Y_s$$

$$Y_{in} = (G_d + jB_d) + jB_s$$
$$= G_d + j(B_d + B_s).$$

Y_s only needs to be reactive, to cancel the reactive part of Y_d

Chapter 2 Review



Lumped-Element matching using admittance

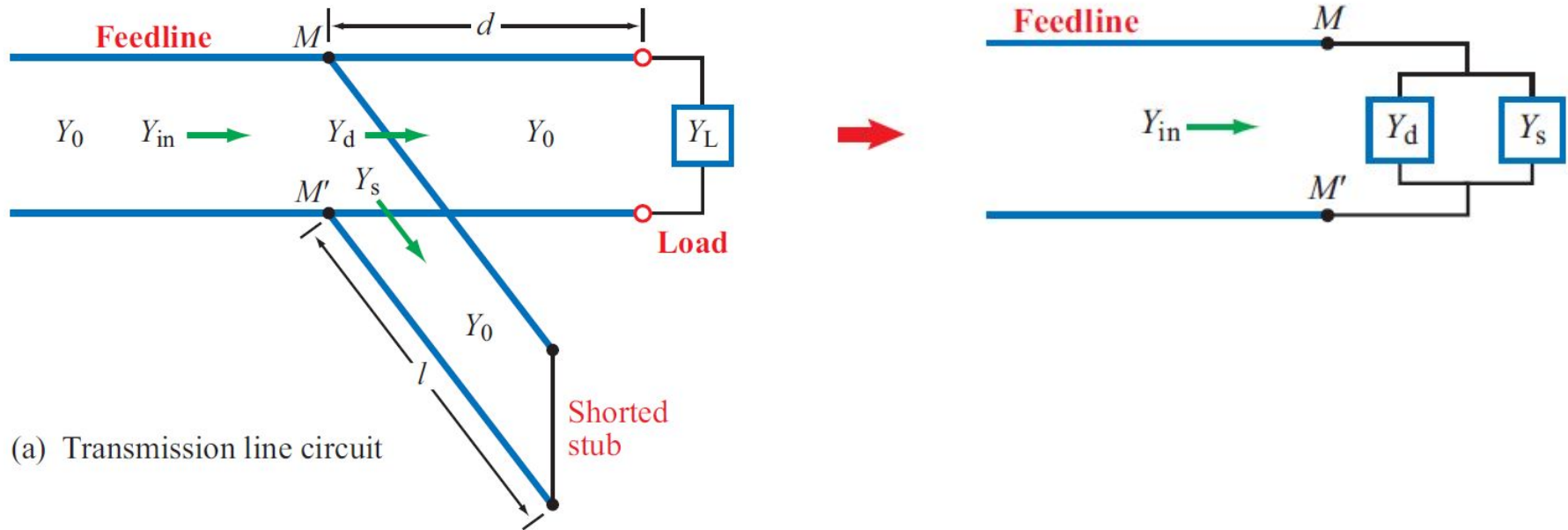
Normalized:

$$y_{in} = g_d + j(b_d + b_s).$$

$$g_d = 1 \quad (\text{real-part condition}),$$

$$b_s = -b_d \quad (\text{imaginary-part condition}).$$

Chapter 2 Review

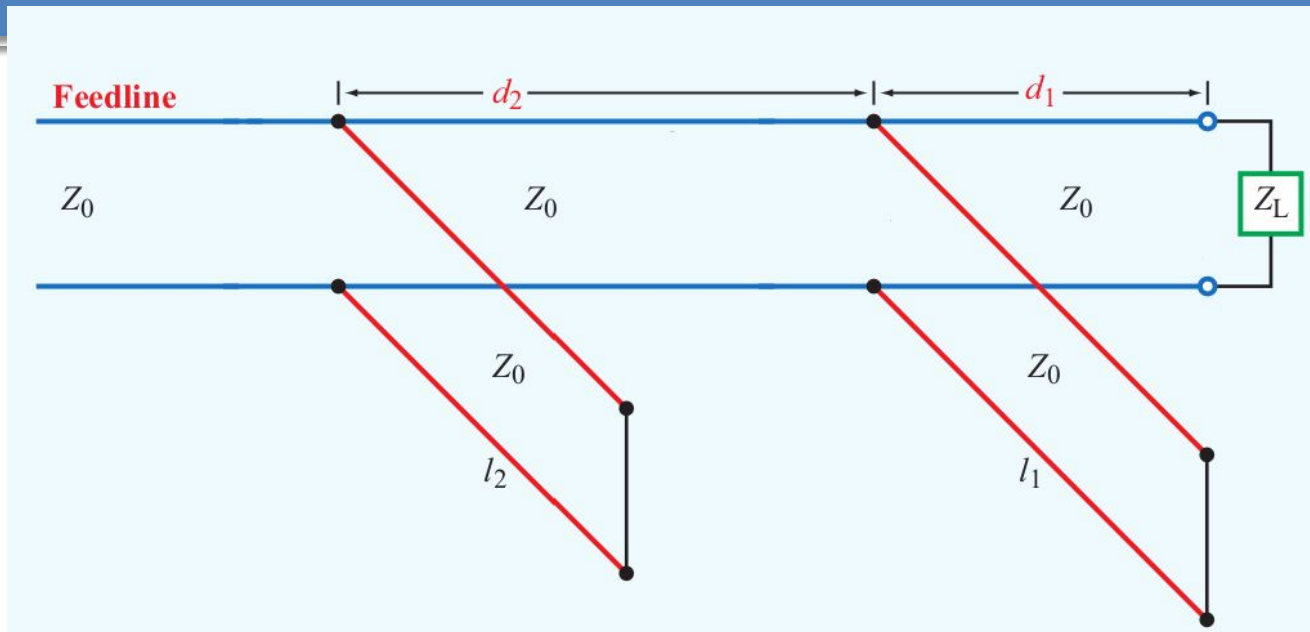


Single-stub Matching:

Can use the same process as before.

Except: transform y_s to a length of shorted transmission line instead of a lumped element.

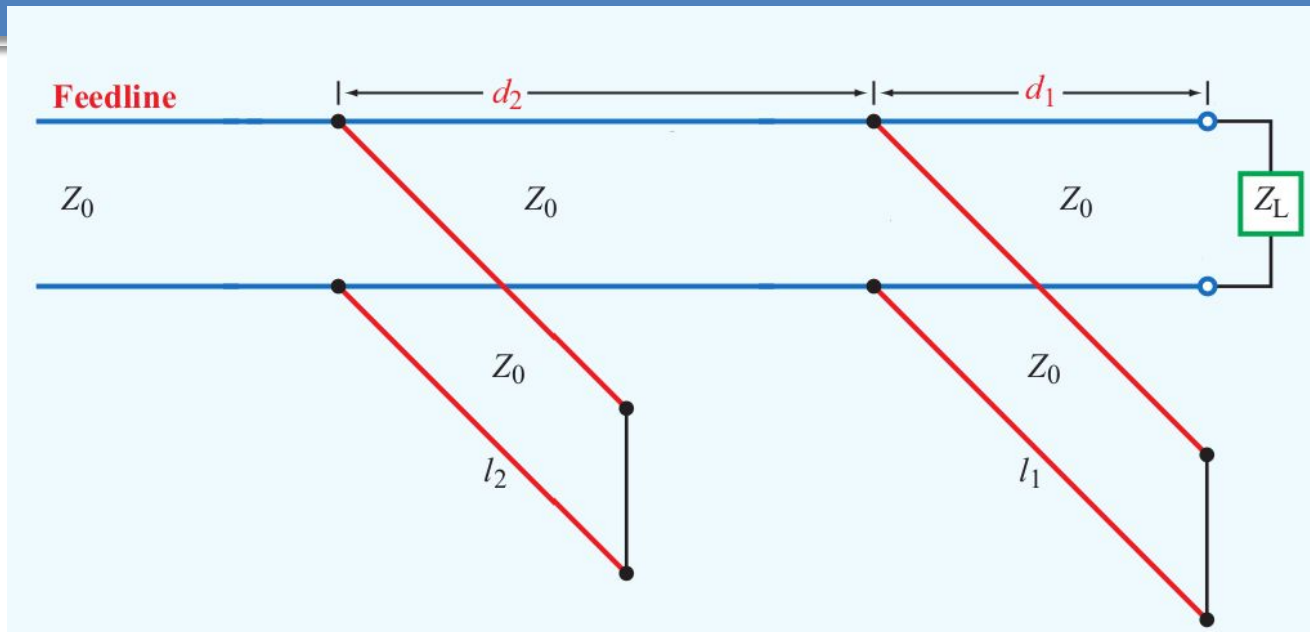
2-Stub Matching



We are given 2 places along a transmission line where we add shorted stubs: d_1 , d_2

What lengths, l_1 , l_2 , should we use for each stub to match the load?

2-Stub Matching

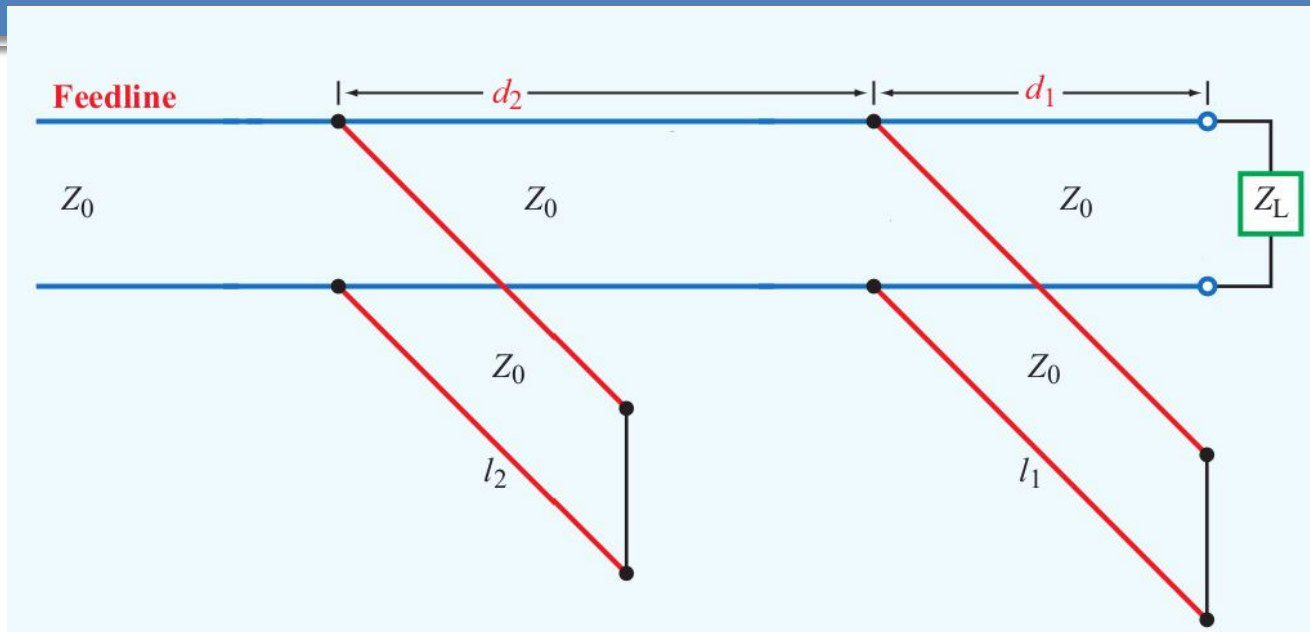


Given: $Z_0 = 50 \Omega$, $Z_L = 100 + j 100 \Omega$

$$d_1 = 0.6 \lambda \quad d_2 = 0.1 \lambda$$

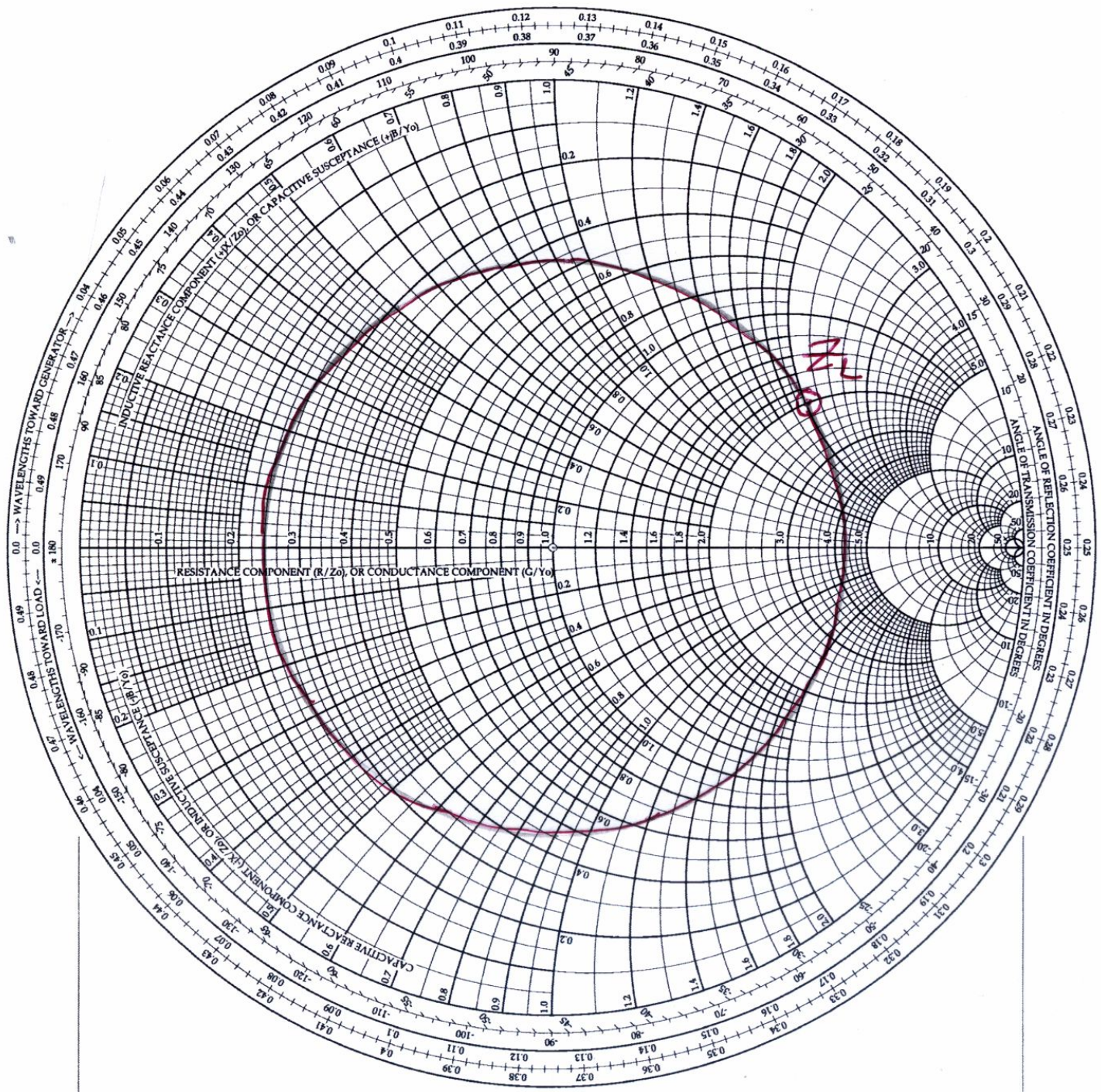
Find: l_1, l_2 , to match the load.

2-Stub Matching

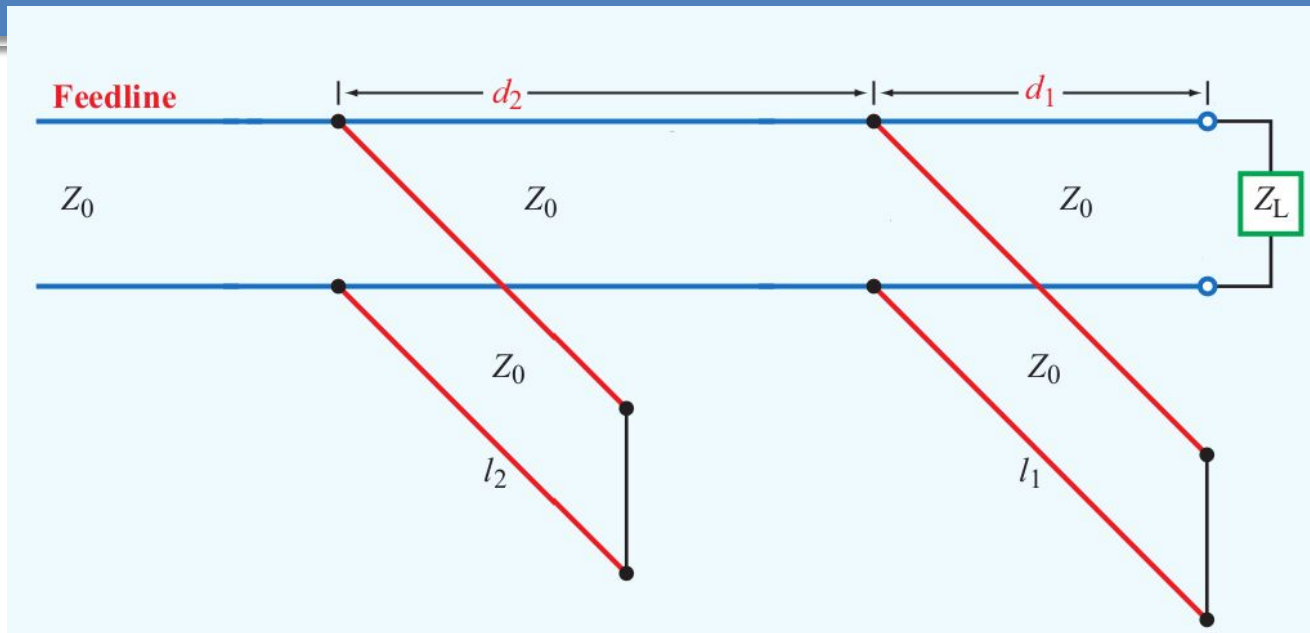


Step 1: plot $z_L = Z_L / Z_0 = 2 + j2$

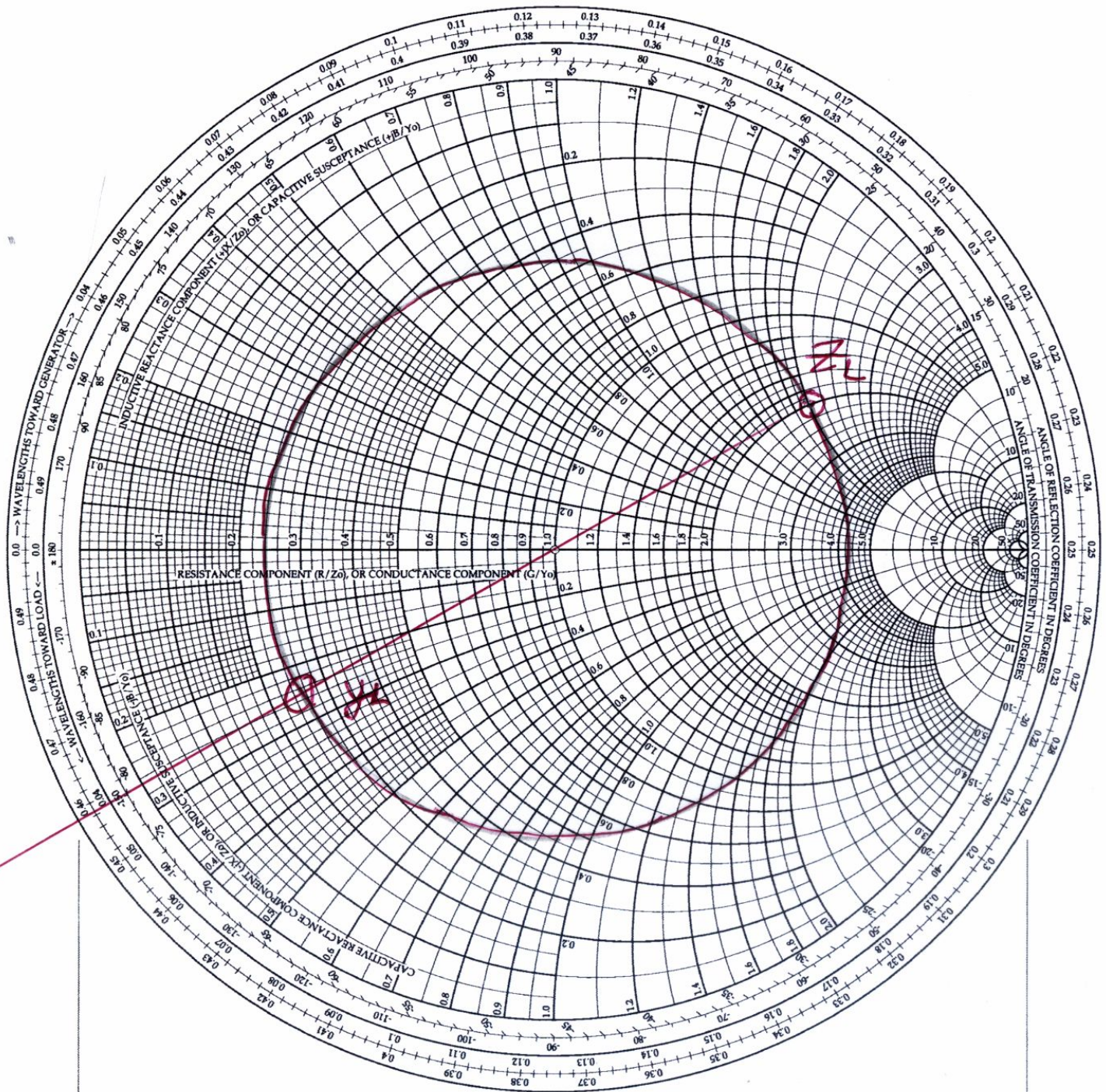
Step 2: Draw VSWR circle through z_L



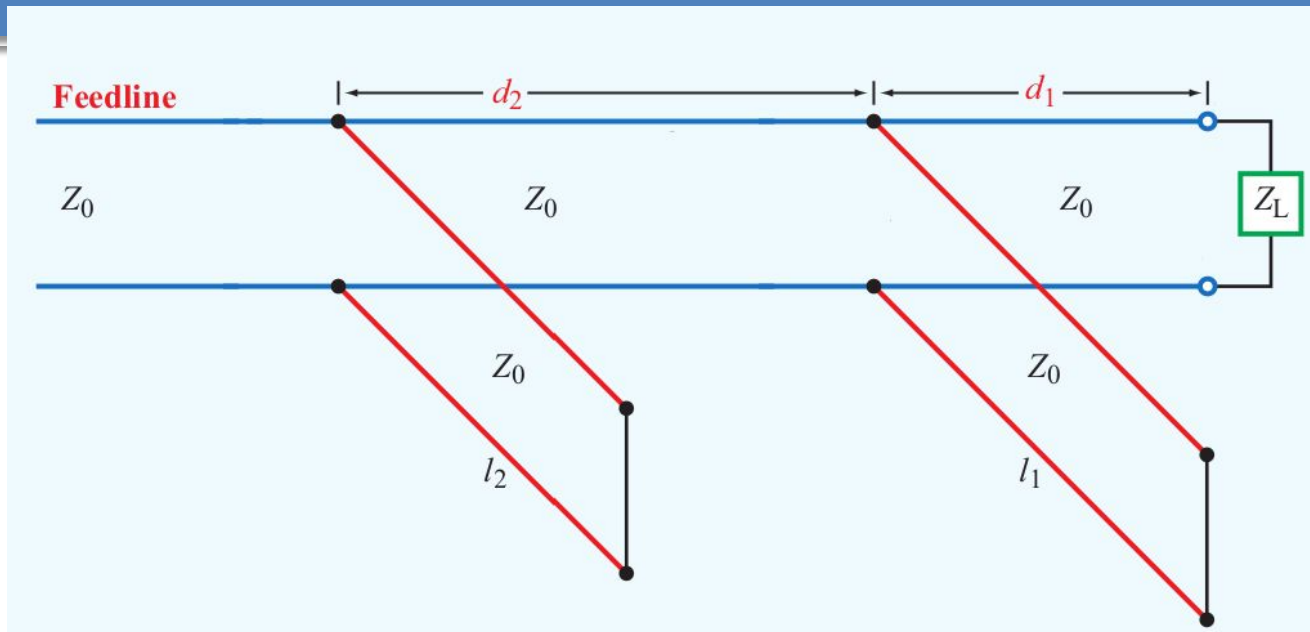
2-Stub Matching



Step 3: Find $y_L = 0.25 - j 0.25$



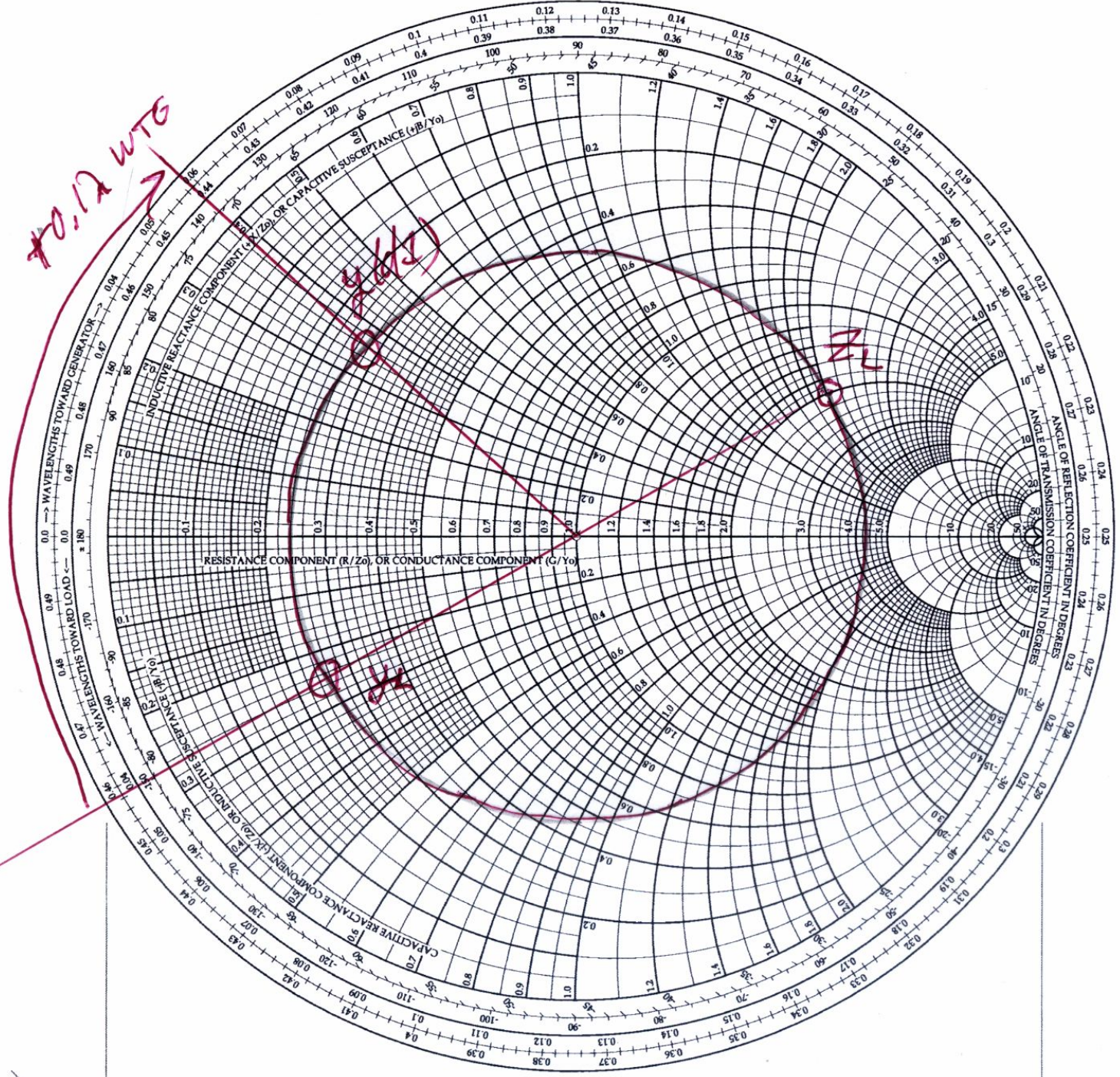
2-Stub Matching



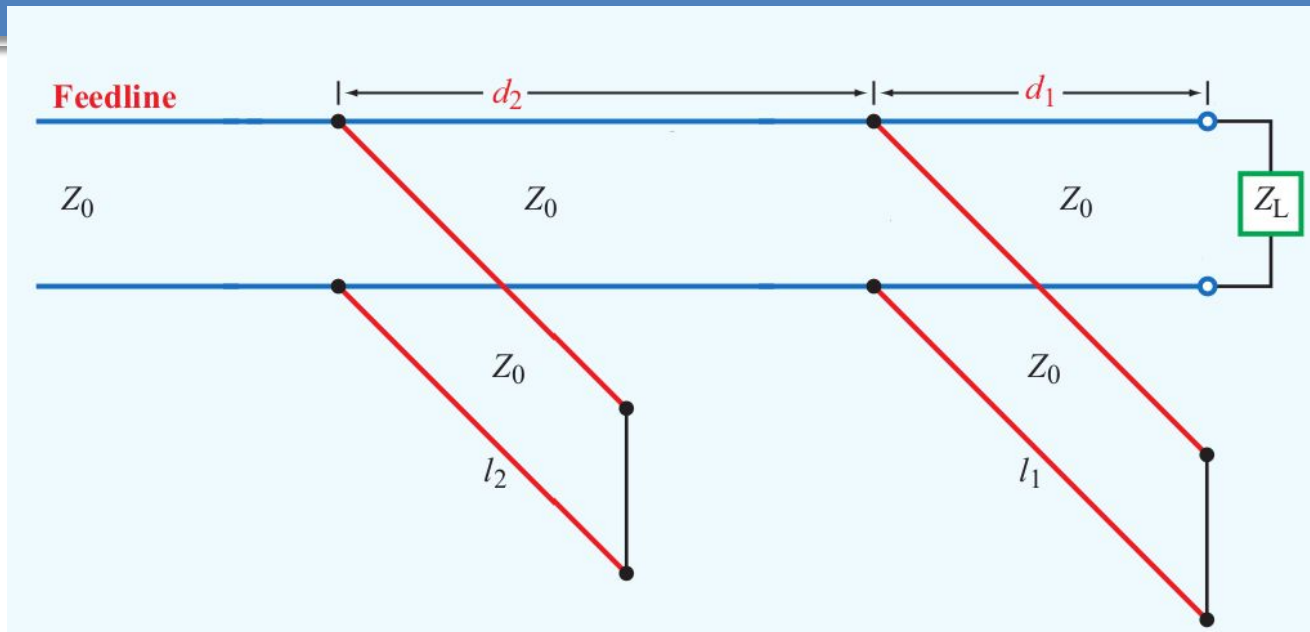
Step 4: Find $y(d_1)$ by rotating toward generator:
to rotate 0.6λ , can rotate 0.1λ from 0.4585λ
to: $+0.0585\lambda$

get: $y(d_1) = 0.28 + j 0.36$

0.12 WTL
←



2-Stub Matching



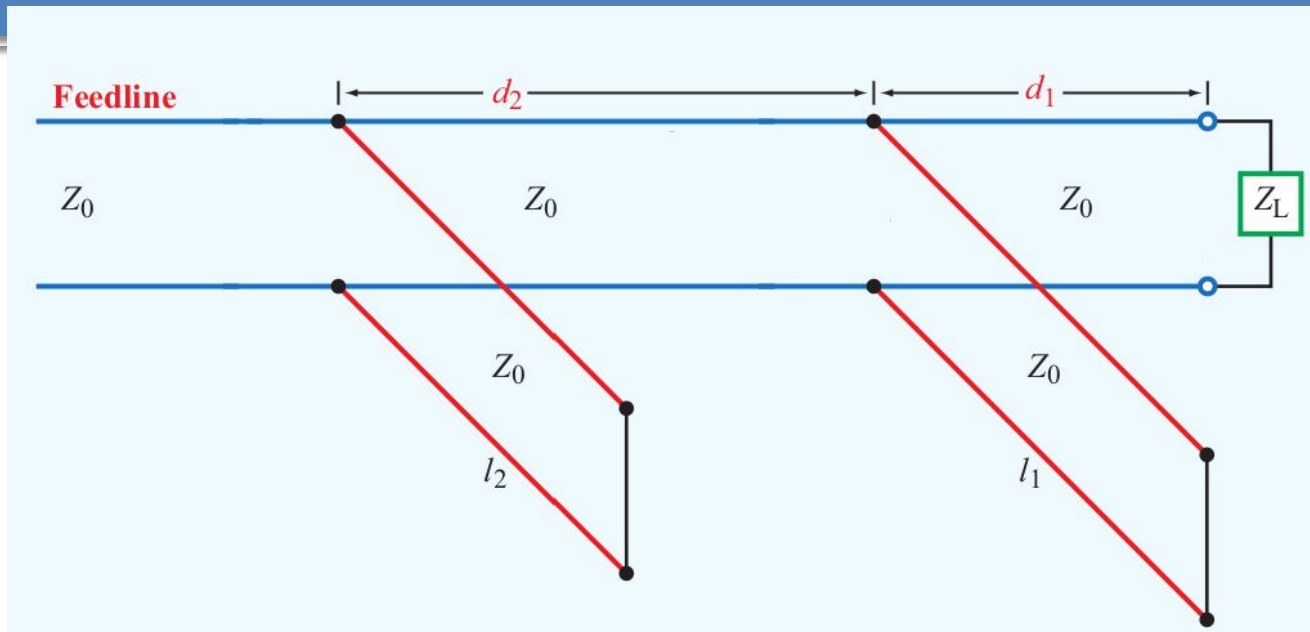
Step 5: Add the shorted stub.

Results in a new $y(d_1 + \text{stub})$

with a different imaginary part

What imaginary part do we want?

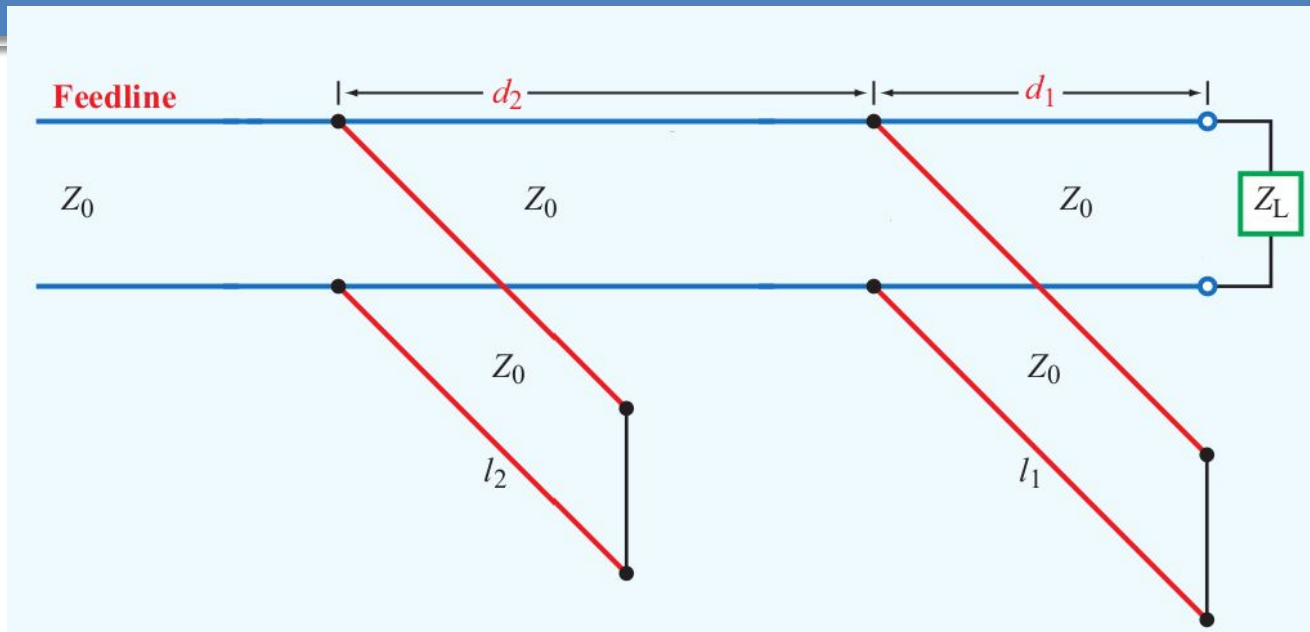
2-Stub Matching



Step 5: need $y(d_1 + \text{stub})$ such that $y(d_2)$ will have a real part of 1.

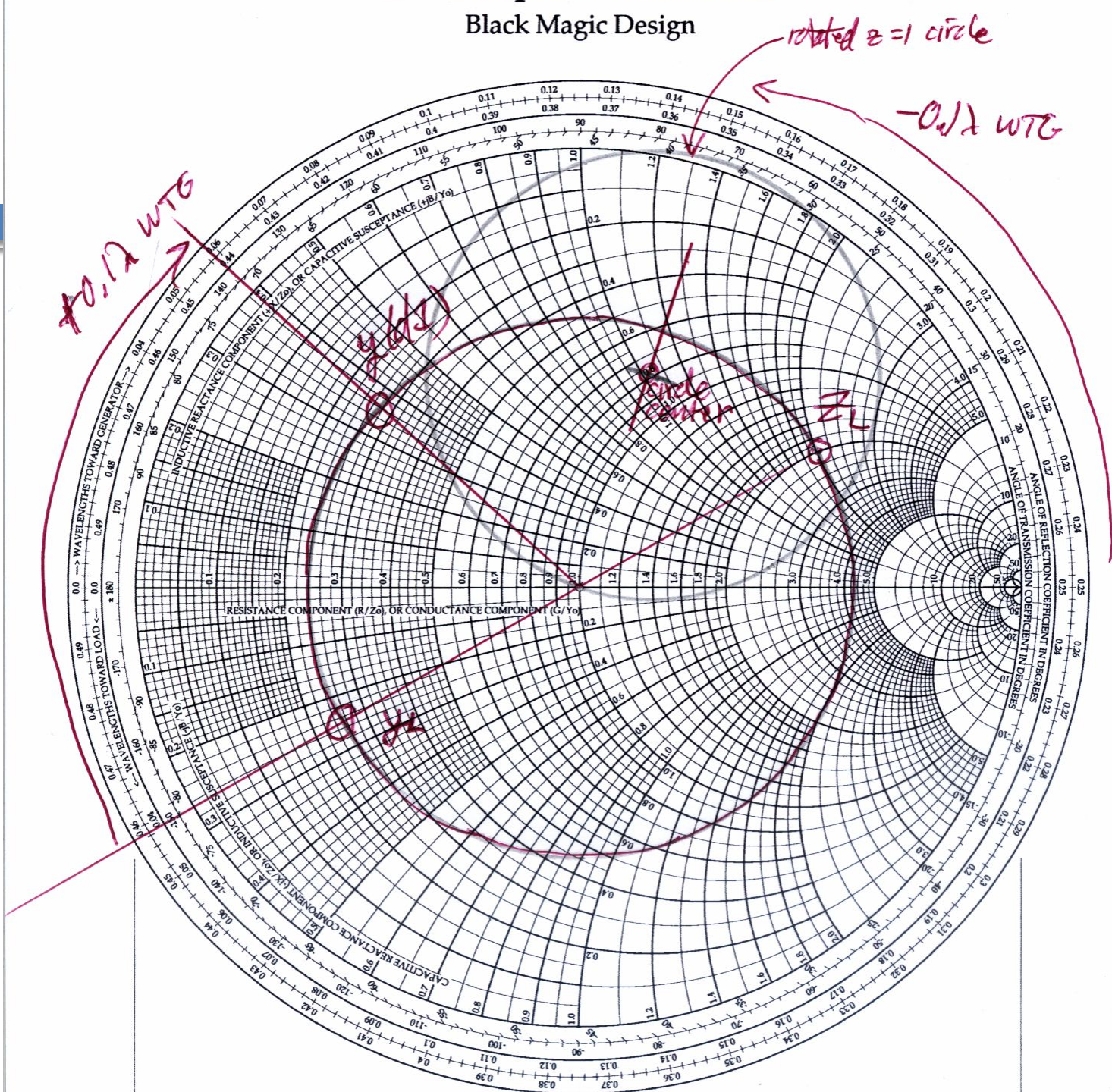
So when $y(d_1 + \text{stub})$ gets rotated on its VSWR circle it ends up on the $y=1$ circle.

2-Stub Matching

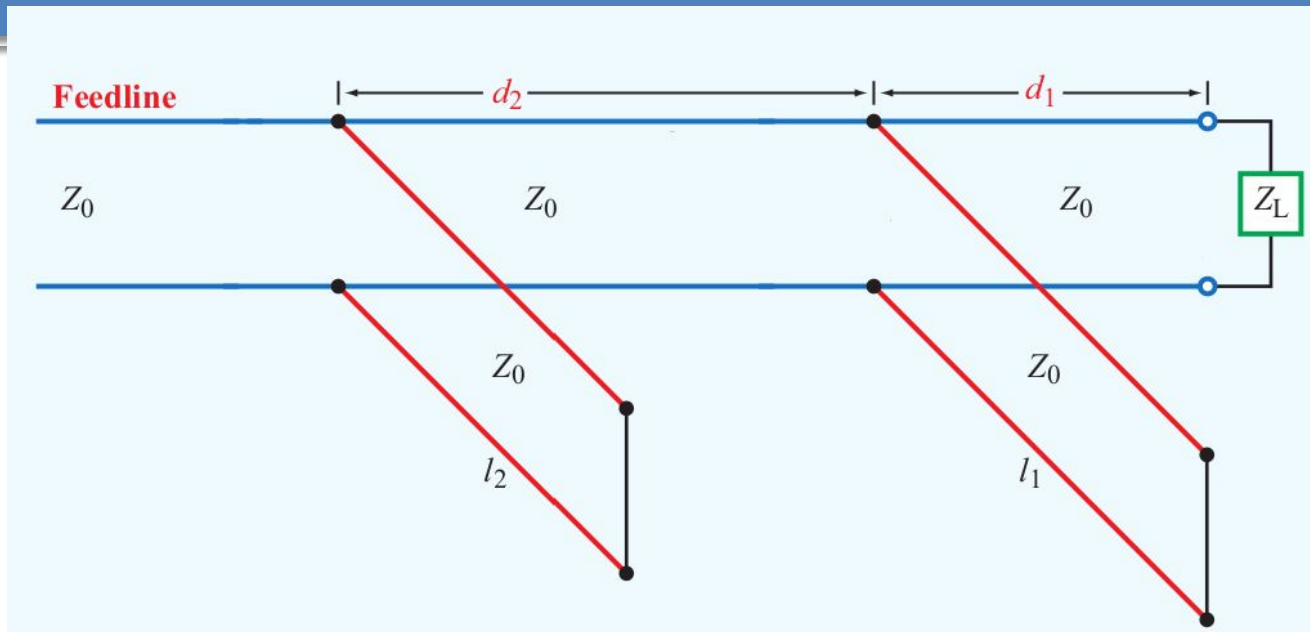


Step 5a: need to rotate the $y=1$ circle towards the load by $d_2=0.1\lambda$
from $WTG=0.25$ to 0.15λ
draw circle centered at $|\Gamma|=0.5$
on this radial line

Black Magic Design



2-Stub Matching

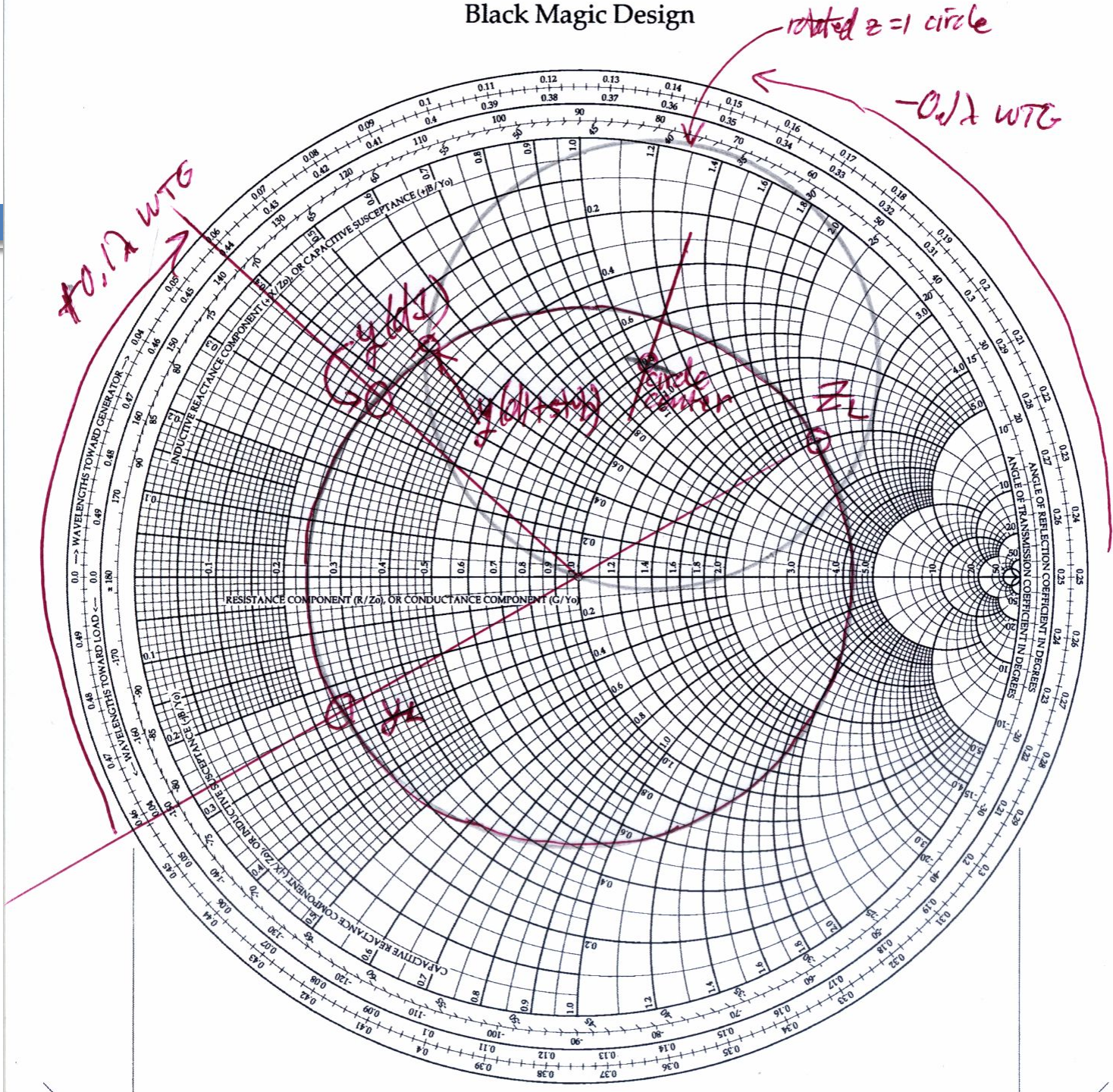


Step 5b: choose 1st stub length so we end up on this rotated circle.

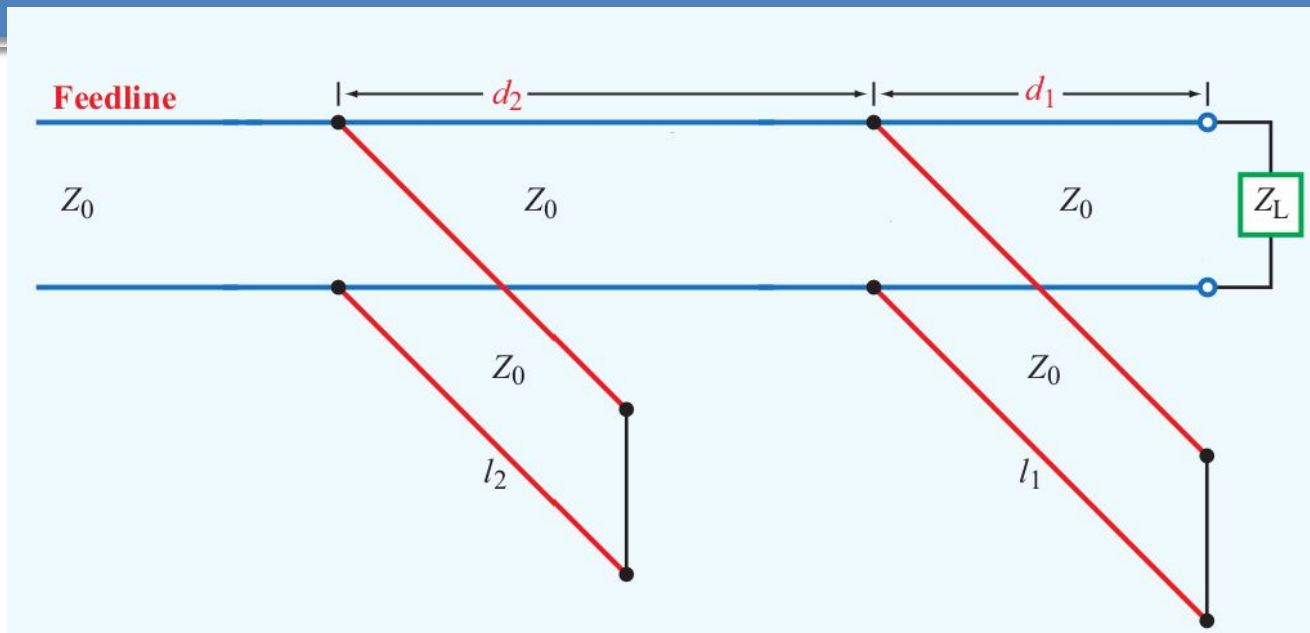
$y(\text{real part})$ does not change

$$y(d_1 + \text{stub}) = 0.28 + j 0.51$$

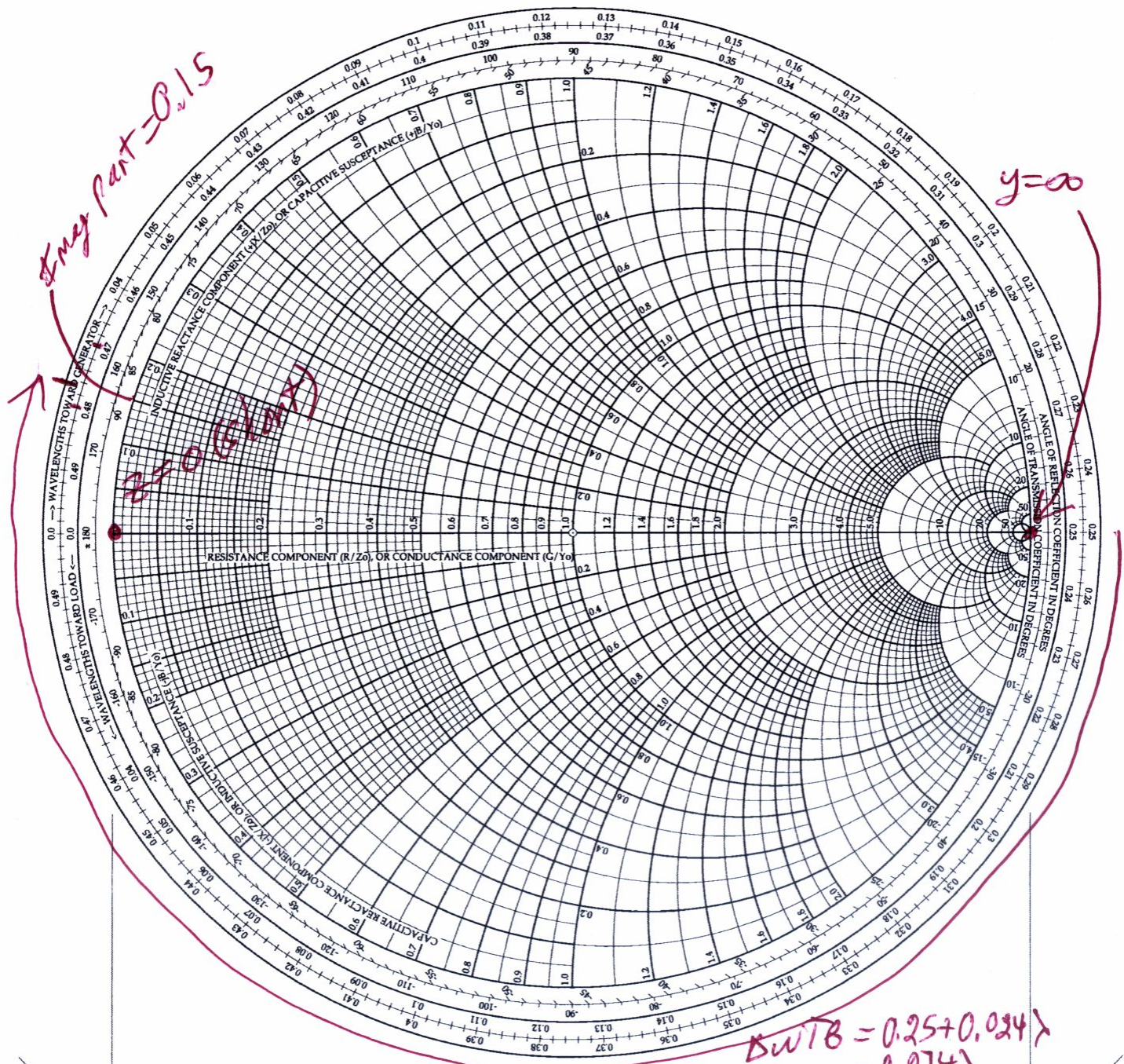
Black Magic Design



2-Stub Matching



Step 6: Use another smith chart to find the stub length to make this change in the imaginary part.
 $\Delta \text{-imag part} = 0.51 - 0.36 = 0.15$
gives length of stub1 as 0.274λ



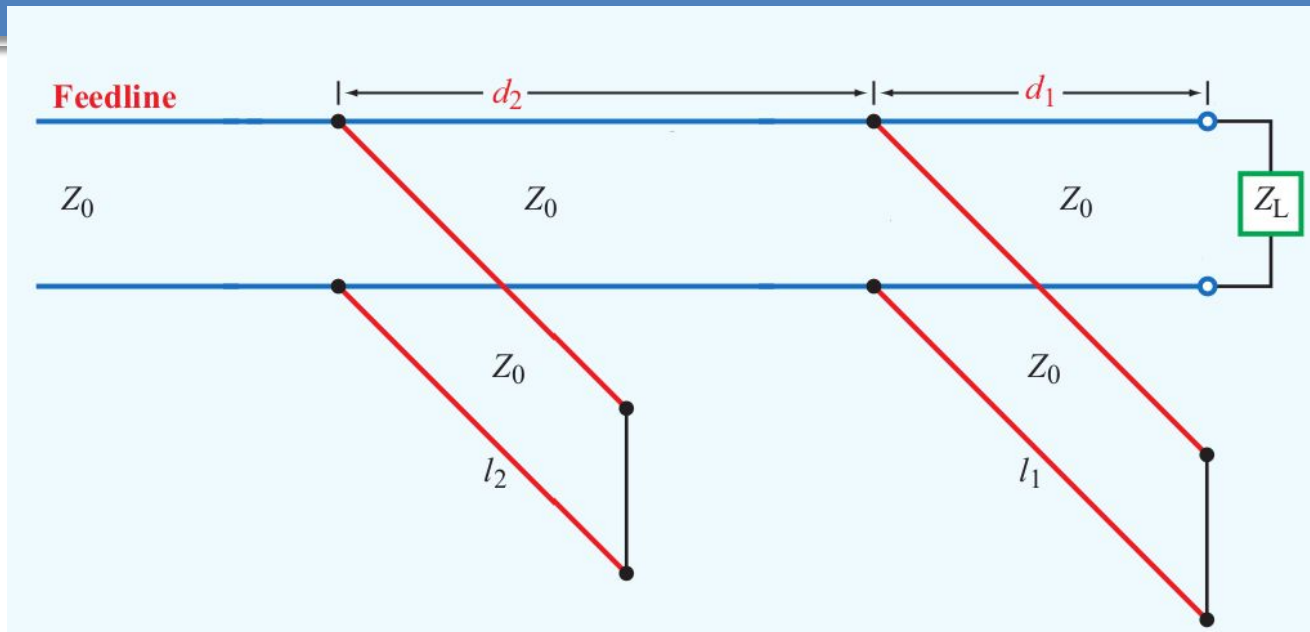
Imp Part = 0.15

y=0

270 DEGREES

$\Delta SWTB = 0.25 + 0.024 \lambda$
 $= 0.274 \lambda$

2-Stub Matching

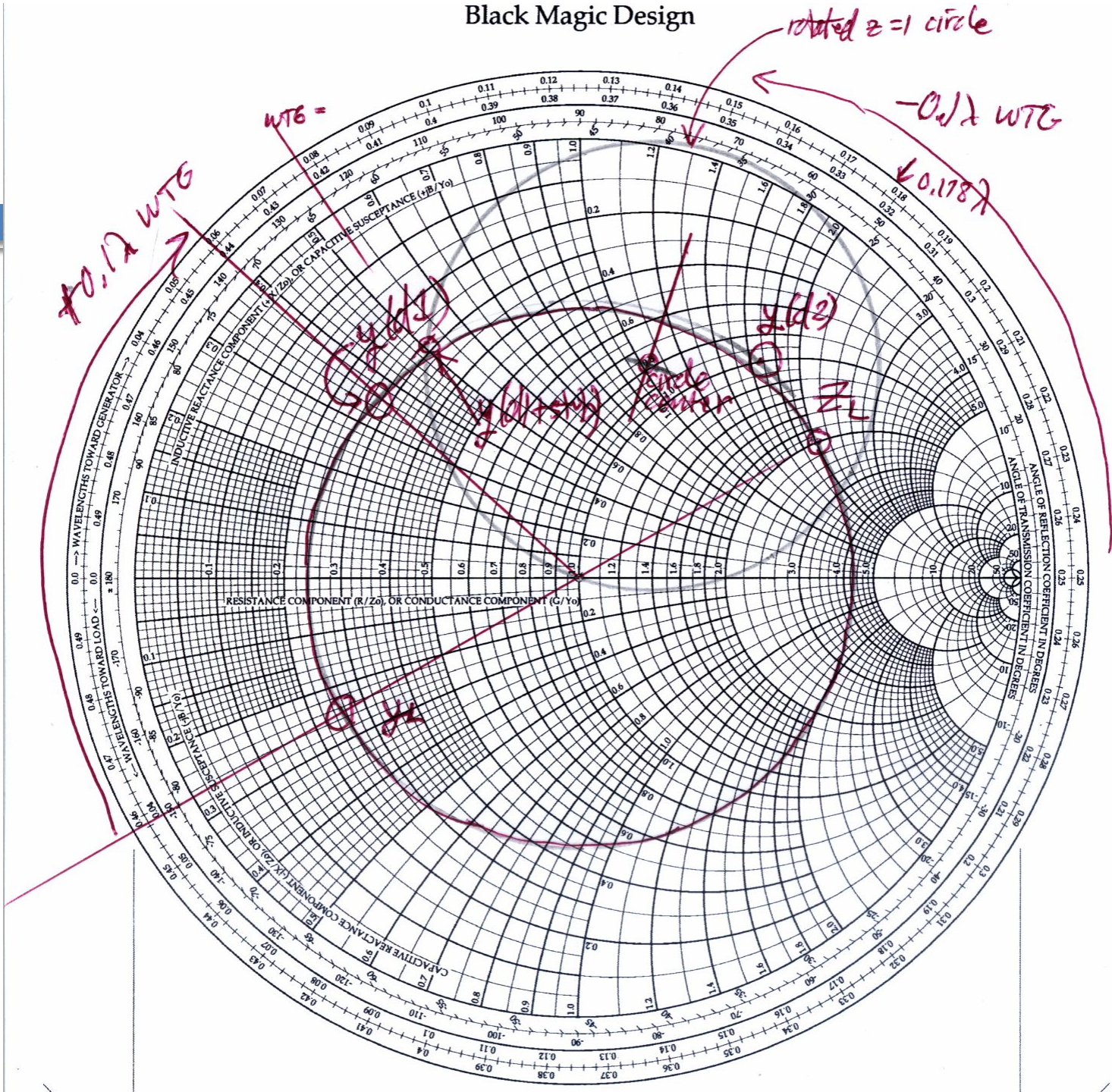


Step 7: rotate by d_2 toward generator to get $y(d_2)$.
(along constant- $|\Gamma|$ circle)

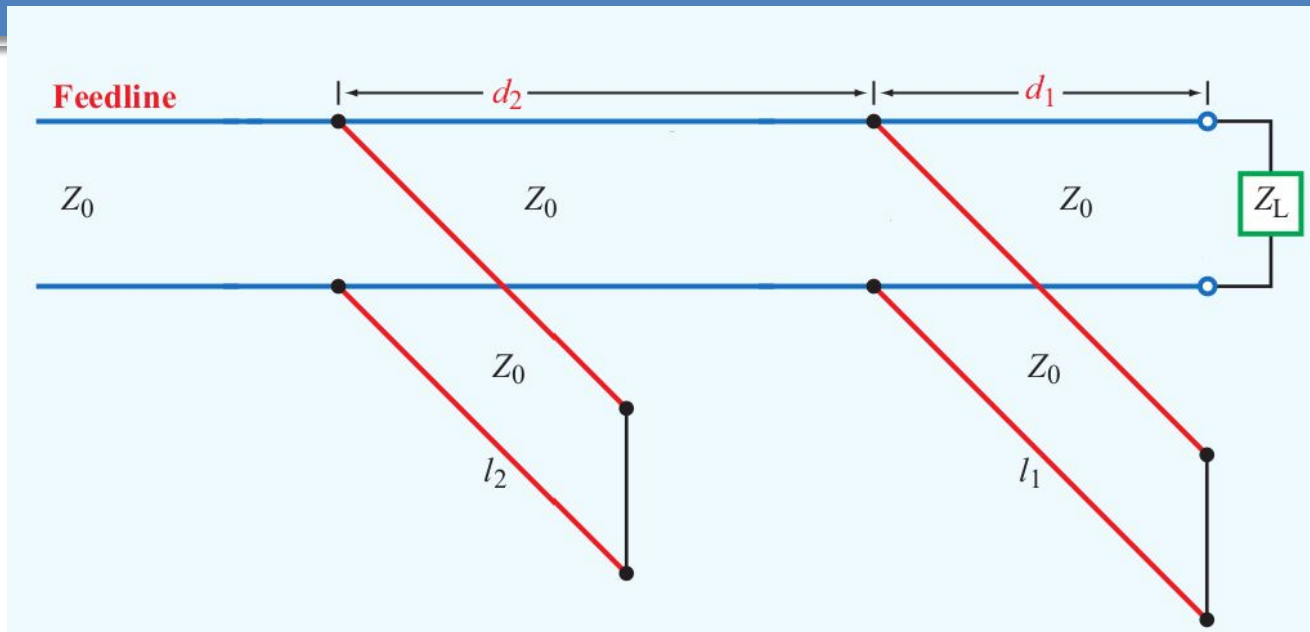
from $0.078\lambda + 0.1\lambda$ to: 0.178λ

$y(d_2) = 1 + j1.65$ (on the $y=1$ circle)

Black Magic Design

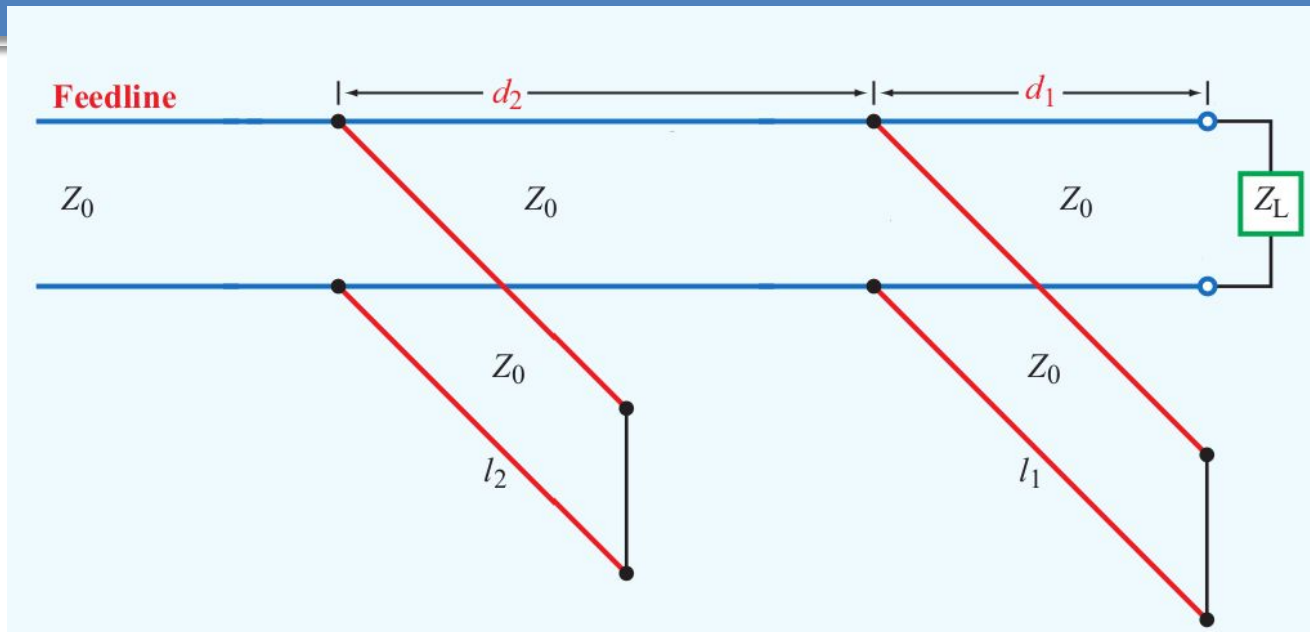


2-Stub Matching



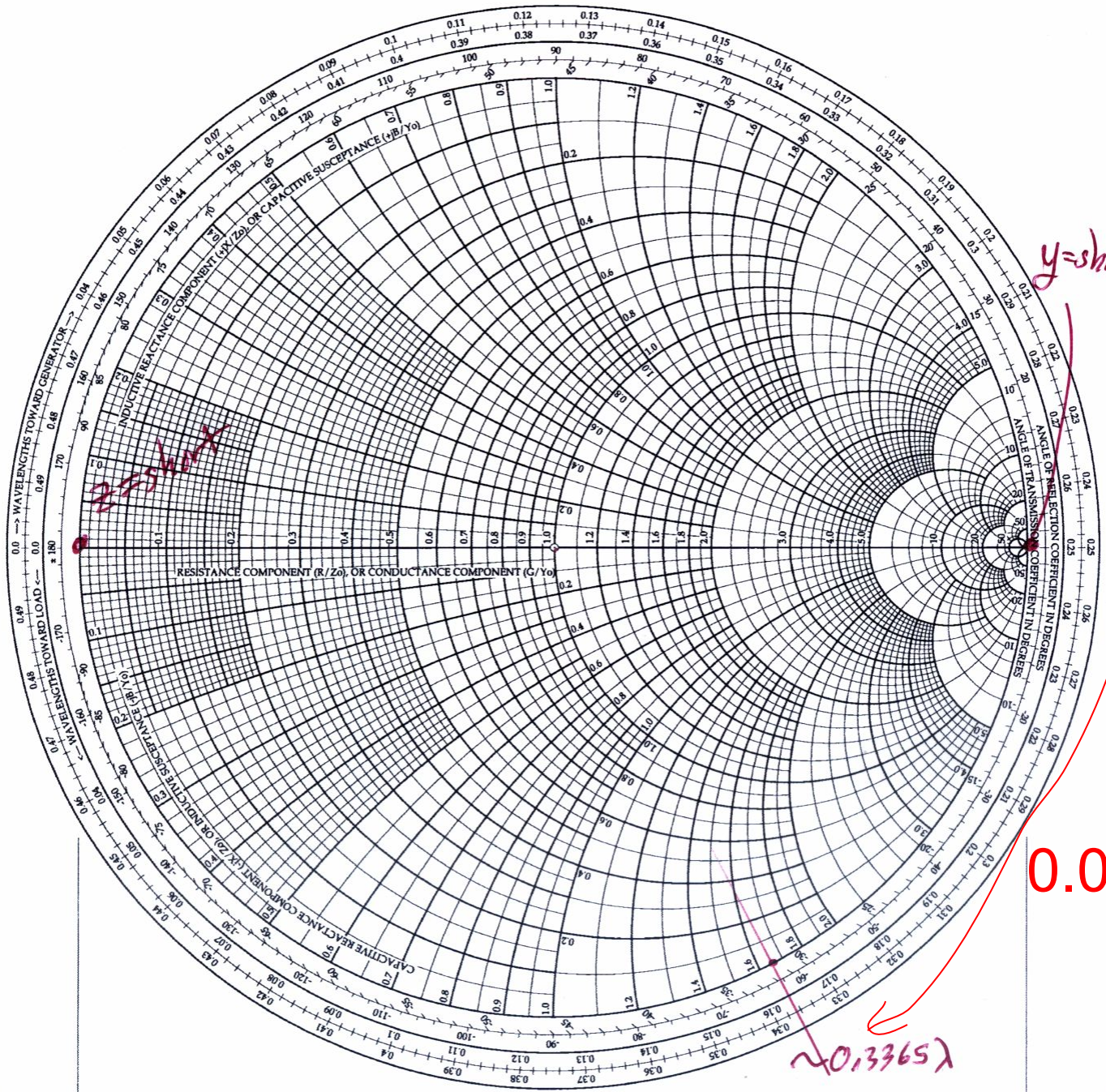
Step 8: Find change in imaginary part needed by stub2 so we end up at origin ($z=1+j0$). $= -j1.65$

2-Stub Matching



Step 9: Use another Smith Chart to find the length of the stub needed for that.

$$0.3365 - 0.25 = 0.0865\lambda$$

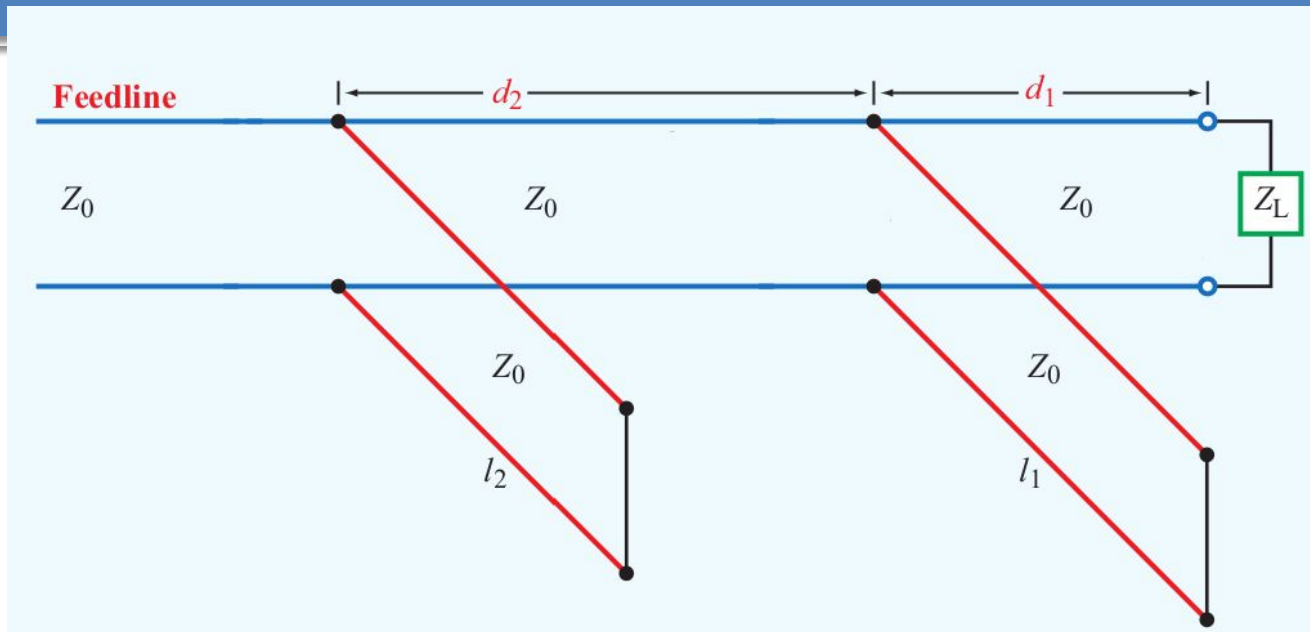


y = shai

0.0865λ

20.3365λ

2-Stub Matching



Step 10: Summary:

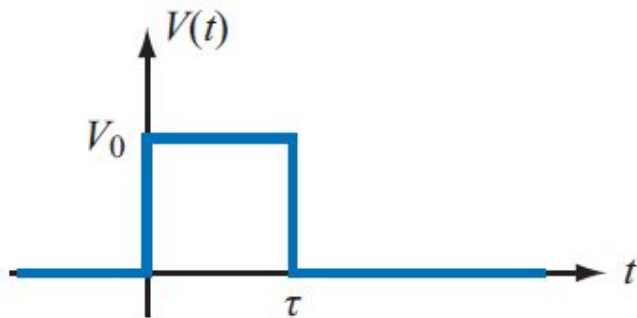
stub1 at $d=0.6\lambda$, length = 0.274λ

stub2 at $d=0.1\lambda$, length = 0.0865λ

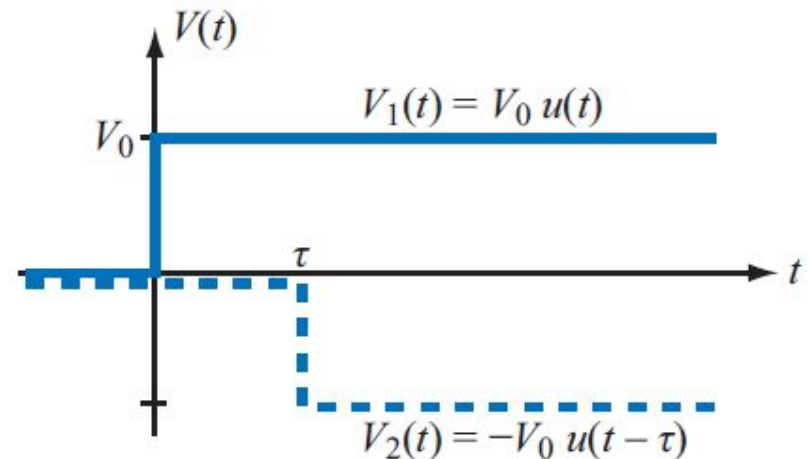
Transients

Change to operate in the time domain (instead of phasor domain)

Instead of sinusoidal sources, use rectangular pulses:



(a) Pulse of duration τ



(b) $V(t) = V_1(t) + V_2(t)$

Rectangular pulse is equivalent to the sum of two step functions

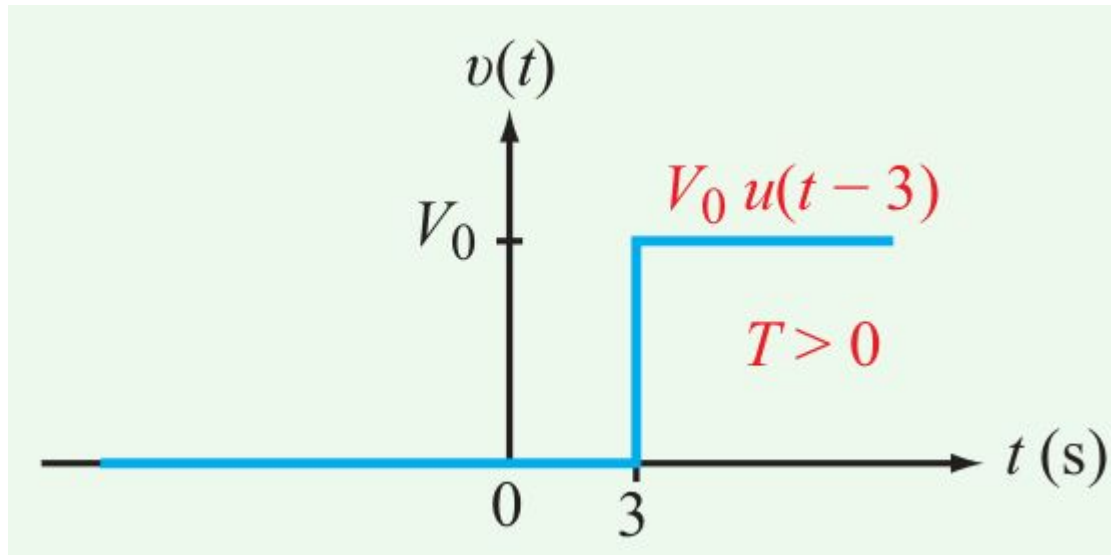
Transients

A General Step Function:

$$u(t) = A u(t - T)$$

A = amplitude

T = turn-on time



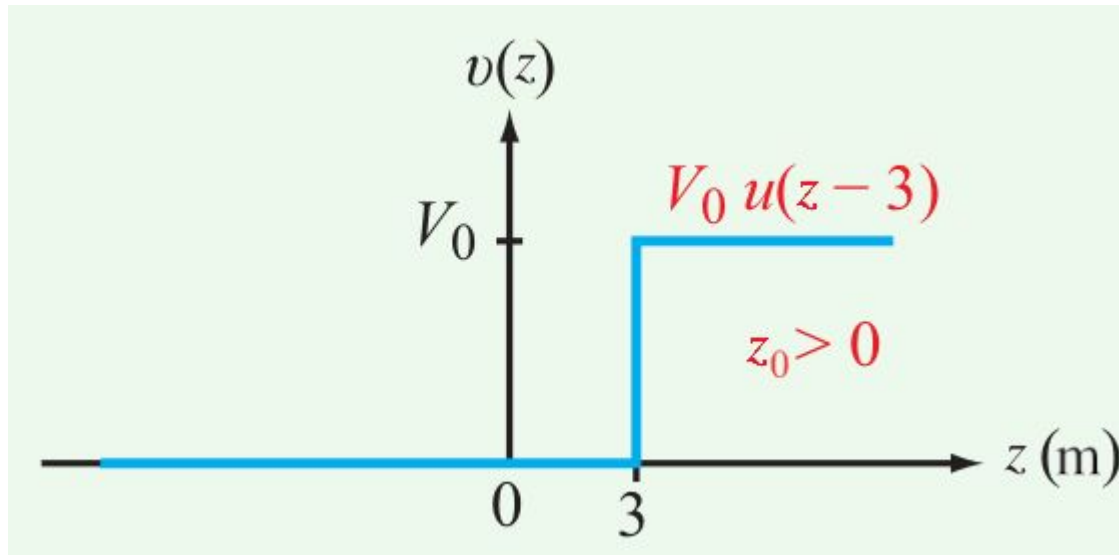
Transients

As a function of **distance**: (at some given time)

$$u(z) = A u(z - z_0)$$

A = amplitude

z_0 = turn-on distance



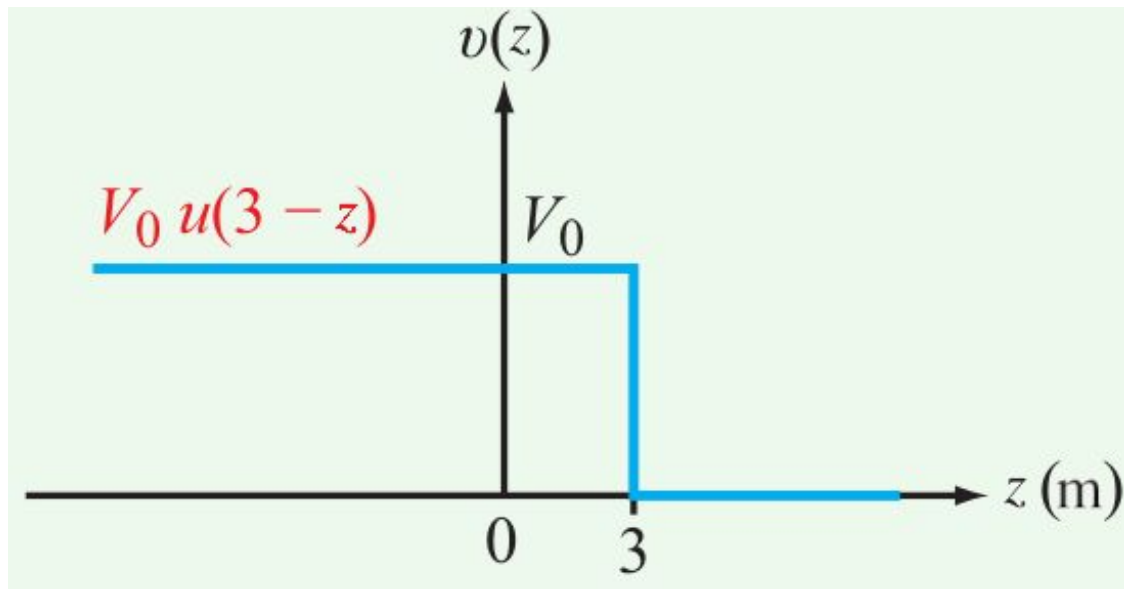
Transients

Reflected version:

$$u(z) = A u (z_0 - z)$$

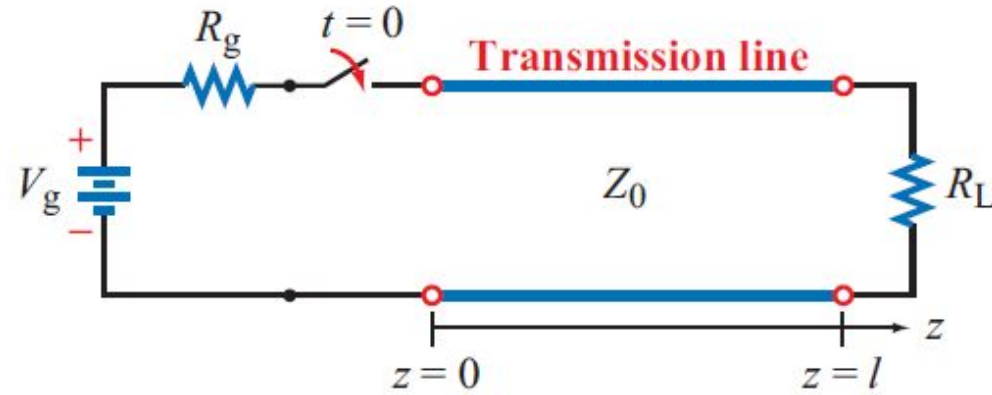
A = amplitude

z_0 = turn-off distance

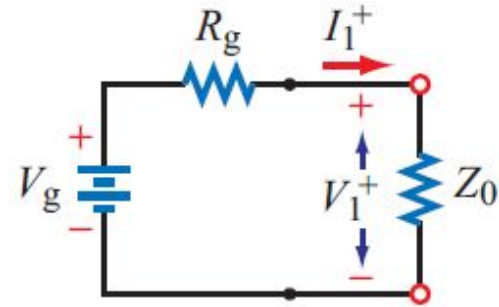


Transients

Need to keep track of voltage vs. time including every reflection.



(a) Transmission-line circuit



(b) Equivalent circuit at $t = 0^+$

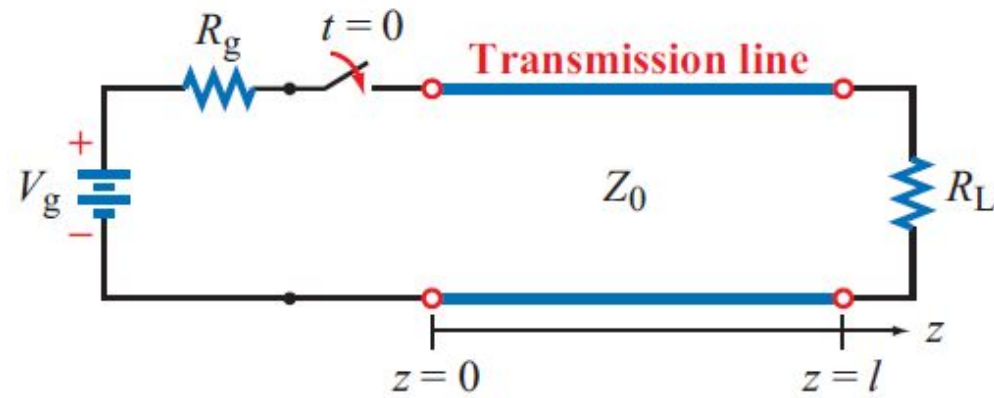
Initial current and voltage

$$I_1^+ = \frac{V_g}{R_g + Z_0},$$

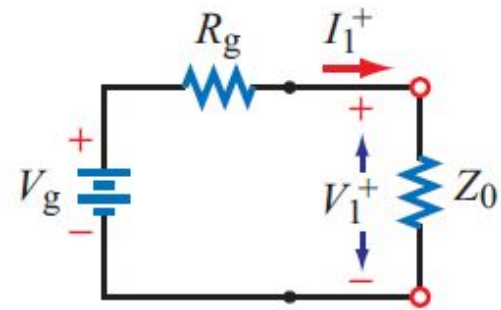
$$V_1^+ = I_1^+ Z_0 = \frac{V_g Z_0}{R_g + Z_0}$$

At $t=0^+$ the equiv ckt does not "see" R_L yet, only the transmission line.

Transient Response



(a) Transmission-line circuit



(b) Equivalent circuit at $t=0^+$

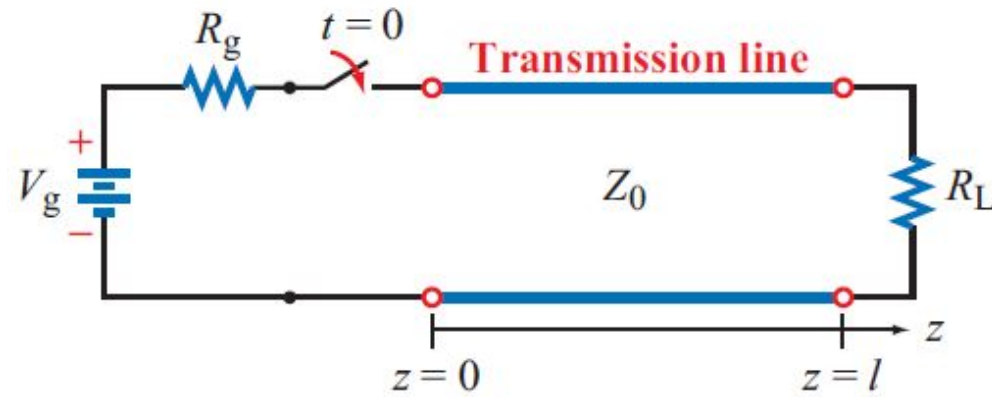
Reflection at the load

$$V_1^- = \Gamma_L V_1^+,$$

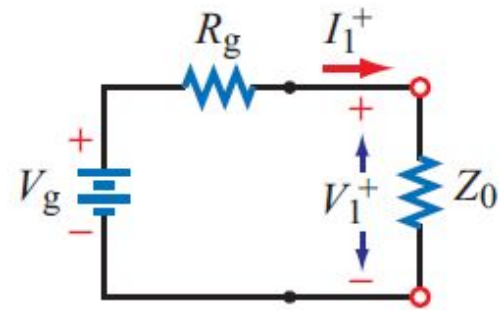
Load reflection coefficient

$$\Gamma_L = \frac{R_L - Z_0}{R_L + Z_0}$$

Transient Response



(a) Transmission-line circuit



(b) Equivalent circuit at $t=0^+$

Second transient

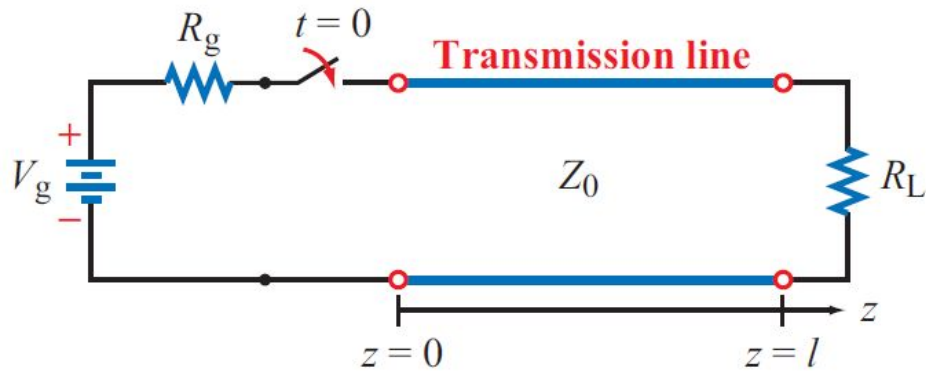
$$V_2^+ = \Gamma_g V_1^- = \Gamma_g \Gamma_L V_1^+$$

Generator reflection coefficient

$$\Gamma_g = \frac{R_g - Z_0}{R_g + Z_0}$$

This continues with every reflection...

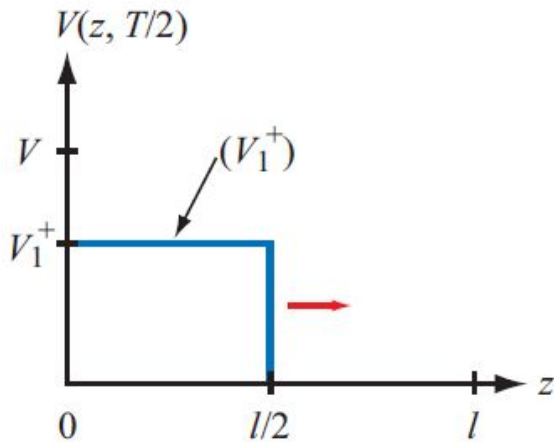
Voltage Pulse



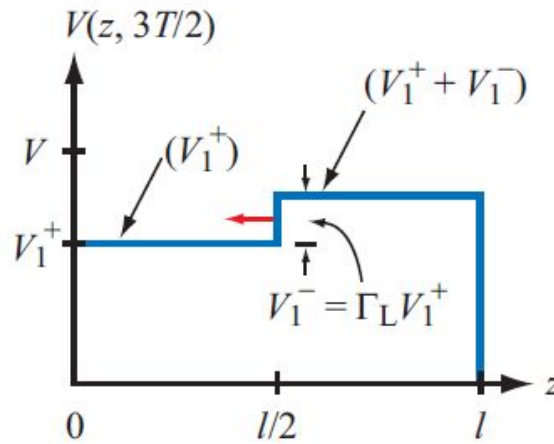
(a) Transmission-line circuit

$T = \ell/u_p$ is the time it takes the wave to travel the full length of the line

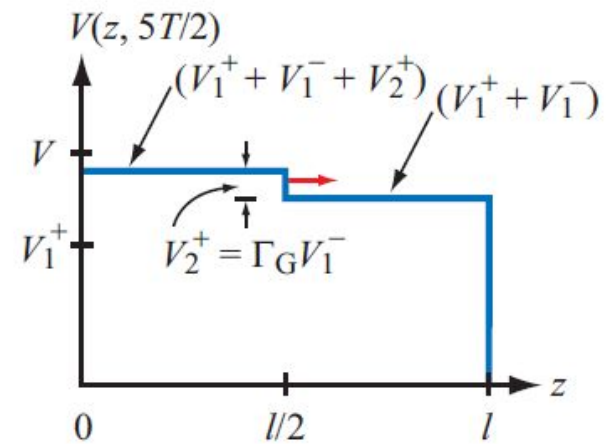
$R_g = 4Z_0$ and $R_L = 2Z_0$. The corresponding reflection coefficients are $\Gamma_L = 1/3$ and $\Gamma_g = 3/5$.



(a) $V(z)$ at $t = T/2$



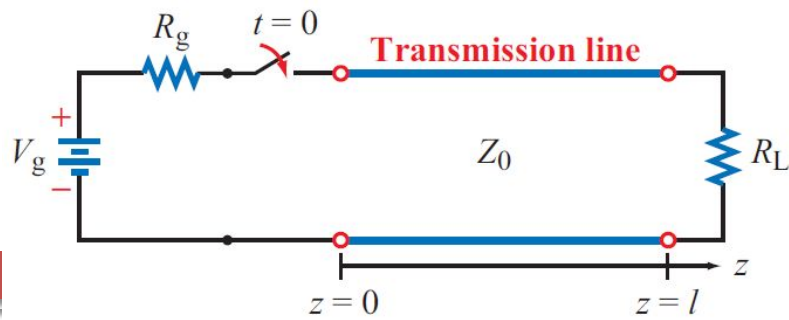
(b) $V(z)$ at $t = 3T/2$



(c) $V(z)$ at $t = 5T/2$

Voltage and Current Pulses

Reflection coefficient for current is the negative of that for voltage

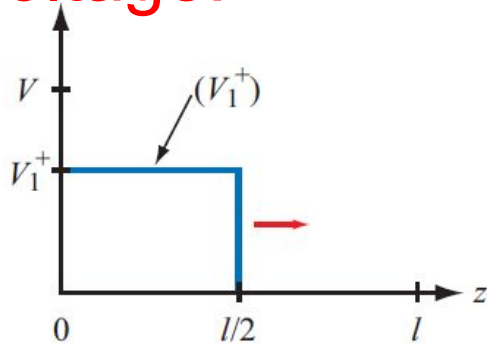


(a) Transmission-line circuit

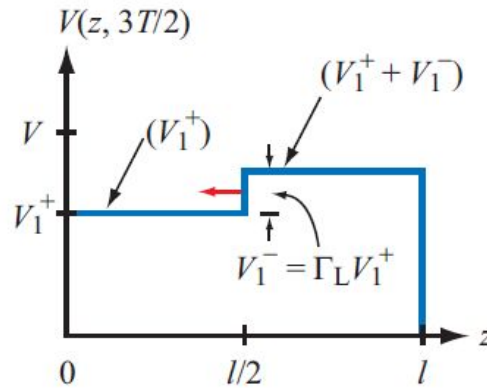
$$I_1^- = -\Gamma_L I_1^+$$

$$I_2^+ = -\Gamma_g I_1^- = \Gamma_g \Gamma_L I_1^+$$

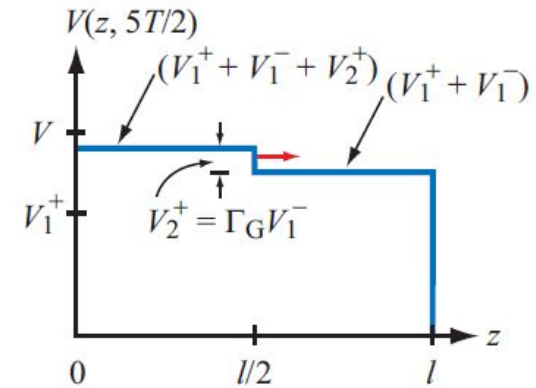
Voltage:



(a) $V(z)$ at $t = T/2$

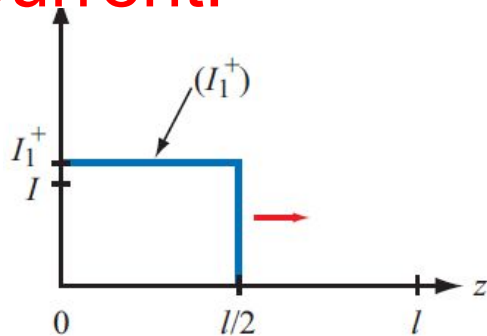


(b) $V(z)$ at $t = 3T/2$

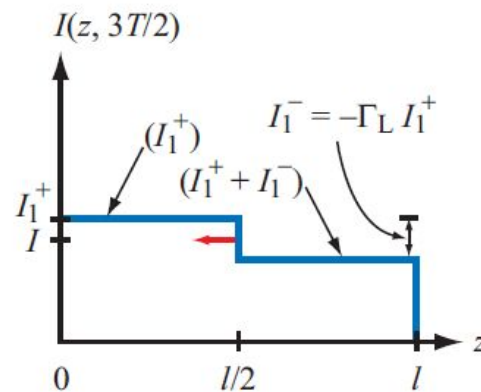


(c) $V(z)$ at $t = 5T/2$

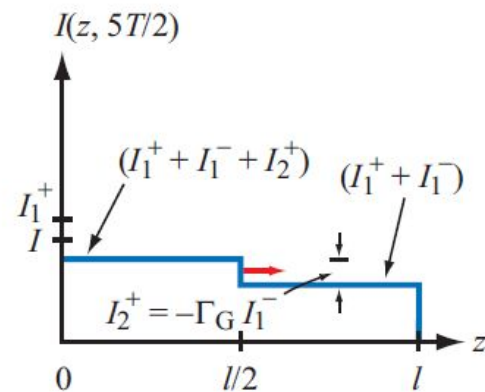
Current:



(d) $I(z)$ at $t = T/2$

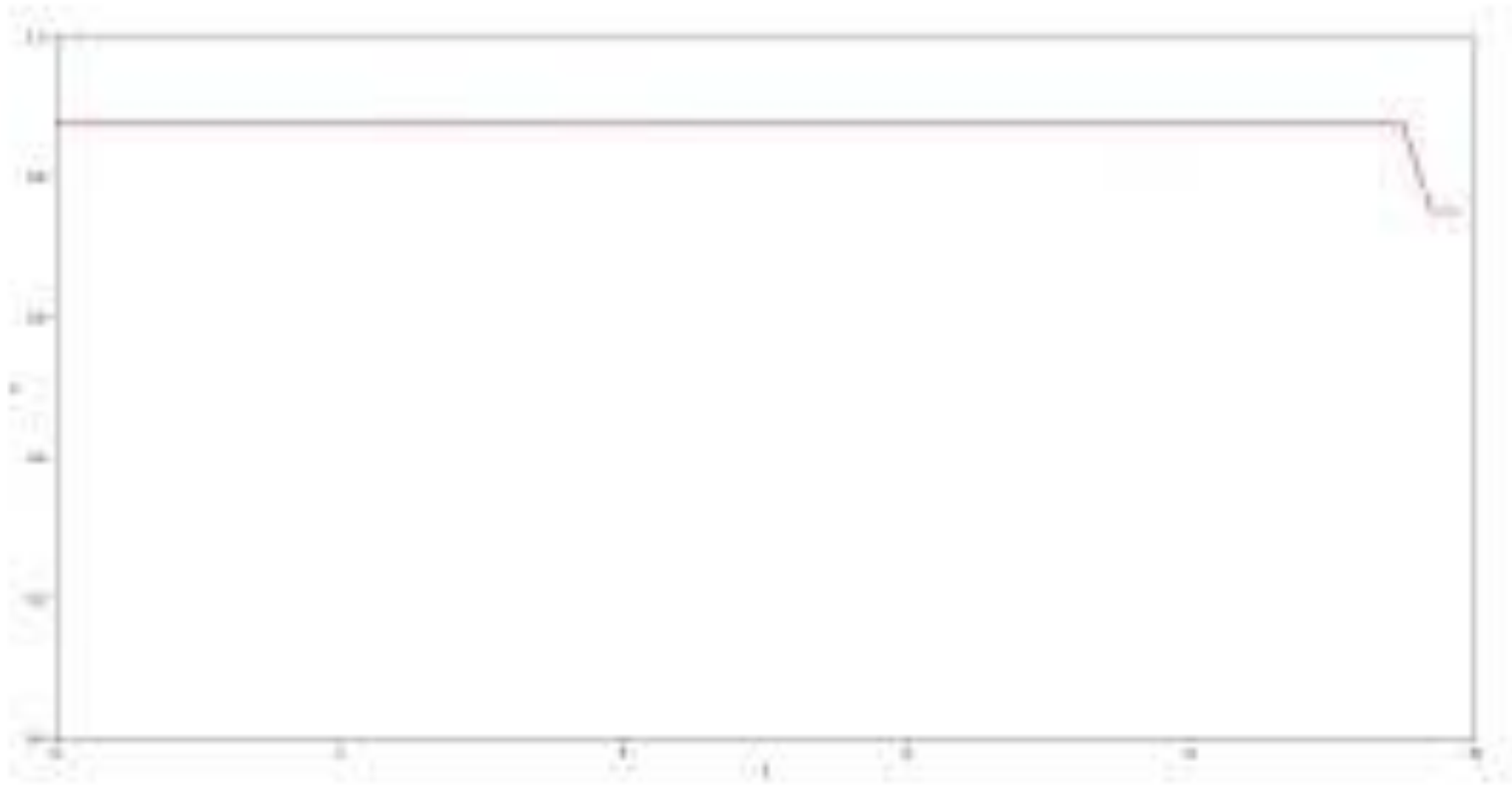


(e) $I(z)$ at $t = 3T/2$

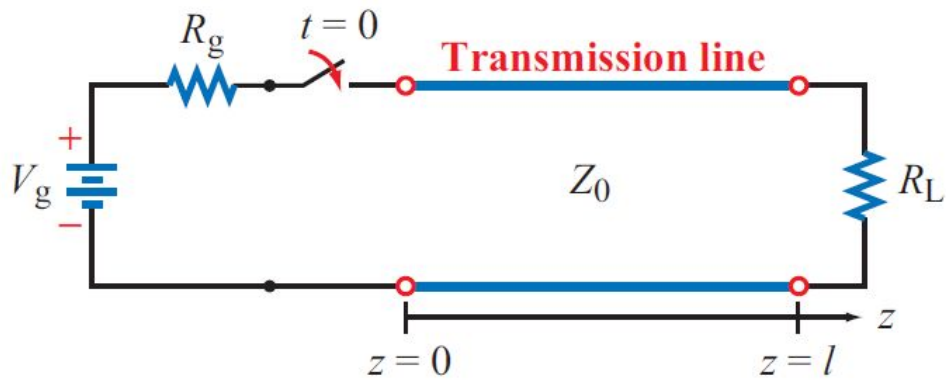


(f) $I(z)$ at $t = 5T/2$

Transient Response



Steady State Response



(a) Transmission-line circuit

$$\begin{aligned}
 V_\infty &= V_1^+ + V_1^- + V_2^+ + V_2^- + V_3^+ + V_3^- + \dots \\
 &= V_1^+ [1 + \Gamma_L + \Gamma_L \Gamma_g + \Gamma_L^2 \Gamma_g + \Gamma_L^2 \Gamma_g^2 + \Gamma_L^3 \Gamma_g^2 + \dots] \\
 &= V_1^+ [(1 + \Gamma_L)(1 + \Gamma_L \Gamma_g + \Gamma_L^2 \Gamma_g^2 + \dots)] \\
 &= V_1^+ (1 + \Gamma_L) [1 + x + x^2 + \dots],
 \end{aligned}$$

$$x = \Gamma_L \Gamma_g.$$

$$\frac{1}{1-x} = 1 + x + x^2 + \dots$$

for $|x| < 1$.

$$V_\infty = V_1^+ \frac{1 + \Gamma_L}{1 - \Gamma_L \Gamma_g}.$$

Steady State Response

$$\begin{aligned} V_{\infty} &= V_1^+ \frac{1 + \Gamma_L}{1 - \Gamma_L \Gamma_G} \\ &= \left(\frac{V_g Z_0}{R_g + Z_0} \right) \frac{1 + \frac{R_L - Z_0}{R_L + Z_0}}{1 - \frac{R_L - Z_0}{R_L + Z_0} \frac{R_g - Z_0}{R_g + Z_0}} \end{aligned}$$

multiply by: $\frac{R_L + Z_0}{R_L + Z_0}$

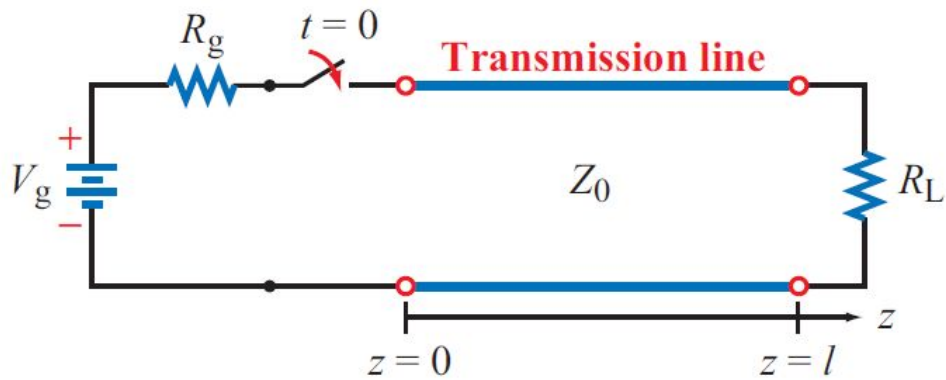
$$= \left(\frac{V_g Z_0}{R_g + Z_0} \right) \frac{R_L + Z_0 + R_L - Z_0}{R_L + Z_0 - (R_L - Z_0) \frac{R_g - Z_0}{R_g + Z_0}}$$

Steady State Response

$$\begin{aligned} &= \left(\frac{V_g Z_0}{R_g + Z_0} \right) \frac{R_L + Z_0 + R_L - Z_0}{R_L + Z_0 - (R_L - Z_0) \frac{R_g - Z_0}{R_g + Z_0}} \\ &= (V_g Z_0) \frac{2 R_L}{(R_g + Z_0)(R_L + Z_0) - (R_L - Z_0)(R_g - Z_0)} \\ &= V_g \frac{2 R_L Z_0}{R_g R_L + R_g Z_0 + R_L Z_0 + Z_0^2 - R_L R_g + R_L Z_0 + R_g Z_0 - Z_0^2} \\ &= V_g \frac{2 R_L Z_0}{2 R_g Z_0 + 2 R_L Z_0} \end{aligned}$$

$$V_\infty = \frac{V_g R_L}{R_g + R_L}$$

Steady State Response



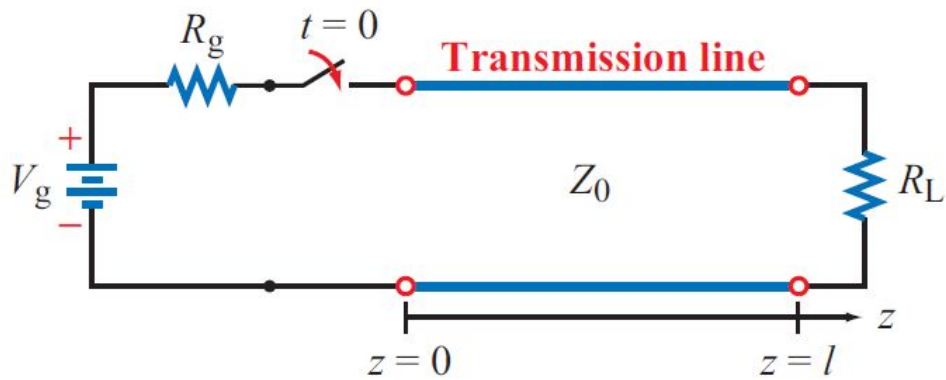
(a) Transmission-line circuit

Result is as expected from EECS 215:

$$V_{\infty} = \frac{V_g R_L}{R_g + R_L}$$

$$I_{\infty} = \frac{V_{\infty}}{R_L} = \frac{V_g}{R_g + R_L}$$

Steady State Response



(a) Transmission-line circuit

Result is as expected:

V_{∞}
 $t = \infty$

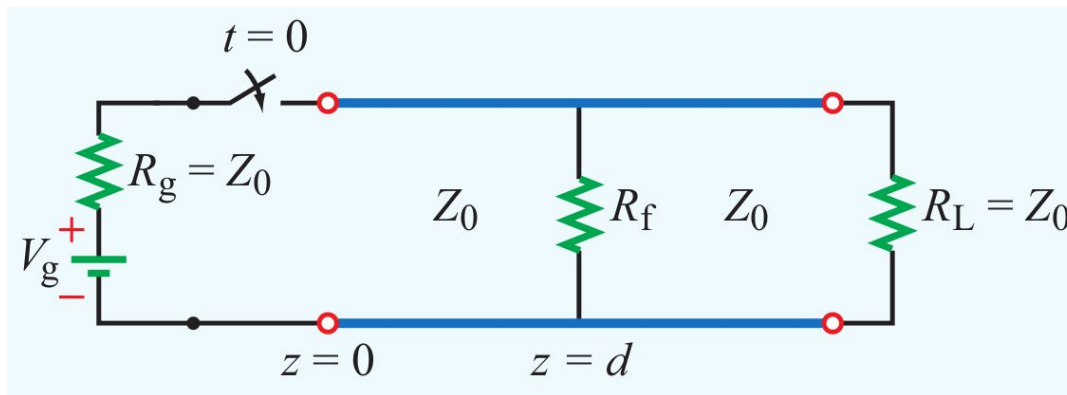
$$I_{\infty} = \frac{V_{\infty}}{R_L} = \frac{V_g}{R_g + R_L}$$

True for the Steady-State Response Only:
and DC source

Time-Domain Reflectometry

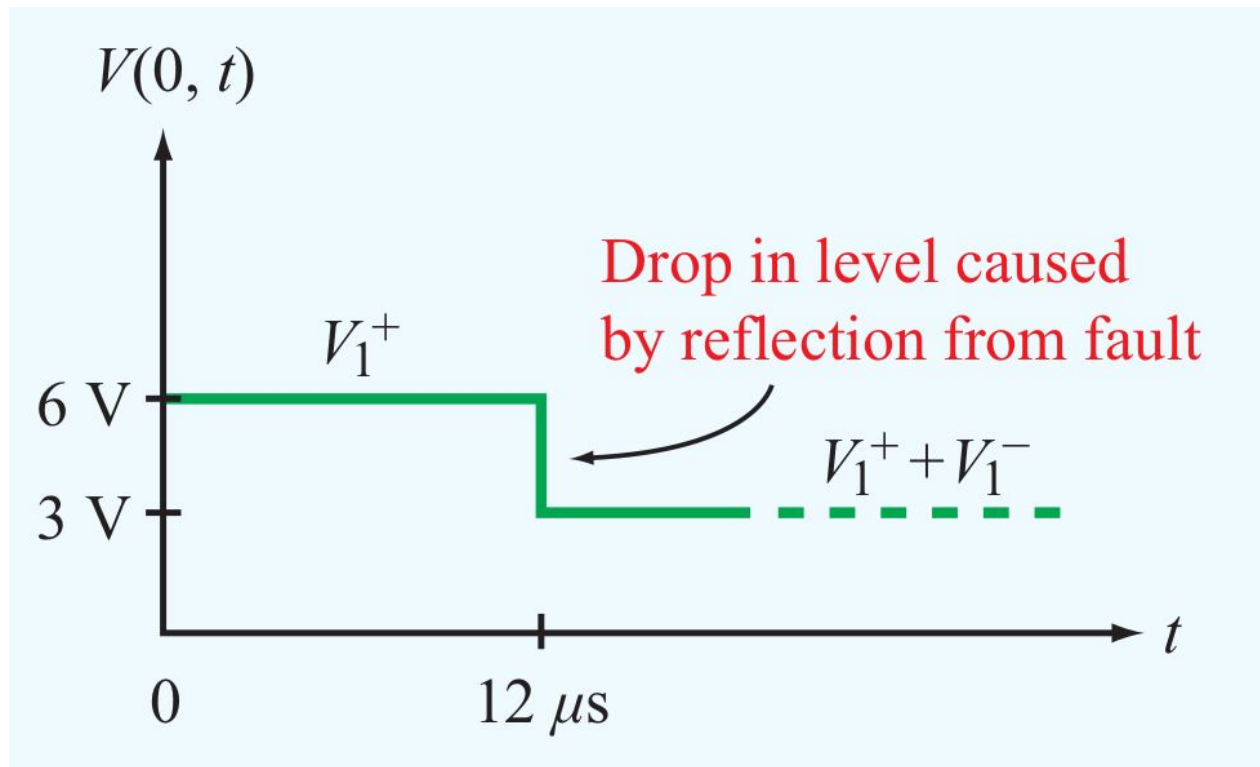
Given: A damaged undersea cable exhibits an "effective" resistance at the fault location.

Model of damaged cable:



Time-Domain Reflectometry

Send a pulse down the cable, get back:



With $Z_0 = 75 \Omega$, insulation: $\epsilon_r = 2.1$

Time-Domain Reflectometry

Find: (a) V_g
(b) d (fault distance from generator)
(c) R_f

Solution:

(a) Since the line was matched before the fault occurred:

$$R_g = R_L = Z_0$$

and the plot shows that: $V_1^+ = 6 \text{ V}$

Time-Domain Reflectometry

We know:

$$V_1^+ = \frac{V_g Z_0}{R_g + Z_0} = \frac{V_g Z_0}{2Z_0} = \frac{V_g}{2}$$

so:

$$V_g = 2V_1^+ = 12 \text{ V.}$$

(b) to get d , need u_p

$$u_p = \frac{c}{\sqrt{\epsilon_r}} = \frac{3 \times 10^8}{\sqrt{2.1}} = 2.07 \times 10^8 \text{ m/s}$$

Time-Domain Reflectometry

Expected round-trip time-delay of a fault at d :

$$\Delta t = \frac{2d}{u_p}$$

from the plot, $\Delta t = 12\mu\text{sec}$, so:

$$d = \frac{\Delta t}{2} u_p = \frac{12 \times 10^{-6}}{2} \times 2.07 \times 10^8 = 1,242 \text{ m}$$

Time-Domain Reflectometry

From the plot:

$$V_1^- = \Gamma_f V_1^+ = -3 \text{ V},$$

so:

$$\Gamma_f = \frac{-3}{6} = -0.5$$

where:

$$\Gamma_f = \frac{R_{Lf} - Z_0}{R_{Lf} + Z_0}$$

and R_{Lf} is NOT R_f , but the parallel combination of R_f and

$$Z_0: \quad \frac{1}{R_{Lf}} = \frac{1}{R_f} + \frac{1}{Z_0}$$

Time-Domain Reflectometry

Since:

$$R_{Lf} = Z_0 \frac{1 + \Gamma_f}{1 - \Gamma_f}$$

$$R_{Lf} = 75 \Omega \frac{1 + (-0.5)}{1 - (-0.5)}$$

$$R_{Lf} = 25 \Omega$$

then:

$$\frac{1}{R_f} = \frac{1}{R_{Lf}} - \frac{1}{Z_0}$$

$$R_f = \frac{R_{Lf} Z_0}{Z_0 - R_{Lf}} = \frac{(25 \Omega)(75 \Omega)}{75 \Omega - 25 \Omega} = 37.5 \Omega$$

Homework

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Homework 10 is due tomorrow at midnight.

submit to gradescope via the canvas site.

Next Time



Chapter 3:

Review of Vector Calculus, gradient, divergence, curl

Review of the 3 major coordinate systems:

 rectangular, cylindrical, spherical

how to use them

how to convert between them