Decision Trees An Early Classifier

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# Introduction to Non-Metric Methods

- We cover such problems involving **nominal data** in this chapter—that is, data that are discrete and without any natural notion of similarity or even ordering.
  - For example (DHS), some teeth are small and fine (as in baleen whales) for straining tiny prey from the sea; others (as in sharks) come in multiple rows; other sea creatures have tusks (as in walruses), yet others lack teeth altogether (as in squid). There is no clear notion of similarity for this information about teeth.

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- Most of the other methods we study will involve real-valued feature vectors with clear metrics.
- We may also consider problems involving data tuples and data strings. And for recognition of these, decision trees and string grammars, respectively.

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- How did you ask the questions?
- What underlying measure led you the questions, if any?
- Most importantly, iterative yes/no questions of this sort require no metric and are well suited for nominal data.

These sequence of questions are a decision tree...



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- Decision trees have a particularly high degree of interpretability.

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# When to Consider Decision Trees

- Instances are wholly or partly described by attribute-value pairs.
- Target function is discrete valued.
- Disjunctive hypothesis may be required.
- Possibly noisy training data.
- Examples
  - Equipment or medical diagnosis.
  - Credit risk analysis.
  - Modeling calendar scheduling preferences.

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- Unfortunately, this rarely happens and we have to decide between whether to stop splitting and accept an imperfect decision or instead to select another property and grow the tree further.

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  - 6 How should missing data be handled?

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- So, DHS focuses on only binary tree learning.
- But, we note that in certain circumstances for learning and inference, the selection of a test at a node or its inference may be computationally expensive and a 3- or 4-way split may be more desirable for computational reasons.

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• The fundamental principle underlying tree creation is that of simplicity: we prefer decisions that lead to a simple, compact tree with few nodes.

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- In all cases, we want i(N) to be 0 if all of the patterns that reach the node bear the same category, and to be large if the categories are equally represented.
- Entropy impurity is the most popular measure:

$$i(N) = -\sum_{j} P(\omega_j) \log P(\omega_j) \quad . \tag{1}$$

It will be minimized for a node that has elements of only one class (pure).
• For the two-category case, a useful definition of impurity is that variance impurity:

$$i(N) = P(\omega_1)P(\omega_2) \tag{2}$$

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• Its generalization to the multi-class is the **Gini impurity**:

$$i(N) = \sum_{i \neq j} P(\omega_i) P(\omega_j) = \frac{1}{2} \left[ 1 - \sum_j P^2(\omega_j) \right]$$
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which is the expected error rate at node N if the category is selected randomly from the class distribution present at the node.

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• The misclassification impurity measures the minimum probability that a training pattern would be misclassified at N:

$$i(N) = 1 - \max_{j} P(\omega_j) \tag{4}$$



For the two-category case, the impurity functions peak at equal class frequencies.

• Key Question: Given a partial tree down to node *N*, what feature *s* should we choose for the property test *T*?

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where  $N_L$  and  $N_R$  are the left and right descendants, respectively,  $P_L$ is the fraction of data that will go to the left sub-tree when property T is used.

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- If the **entropy impurity** is used, this corresponds to choosing the feature that yields the highest **information gain**.

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  - In multi-class binary tree creation, we would want to use the twoing criterion. The goal is to find the split that best separates groups of the c categories. A candidate "supercategory"  $C_1$  consists of all patterns in some subset of the categories and  $C_2$  has the remainder. When searching for the feature s, we also need to search over possible category groupings.

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- This is a local, greedy optimization strategy.
- Hence, there is no guarantee that we have either the global optimum (in classification accuracy) or the smallest tree.
- In practice, it has been observed that the particular choice of impurity function rarely affects the final classifier and its accuracy.

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## A Note About Multiway Splits

• In the case of selecting a multiway split with branching factor B, the following is the direct generalization of the impurity gradient function:

$$\Delta i(s) = i(N) - \sum_{k=1}^{B} P_k i(N_k)$$
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- This direct generalization is biased toward higher branching factors.
  - To see this, consider the uniform splitting case.
- So, we need to normalize each:

$$\Delta i_B(s) = \frac{\Delta i(s)}{-\sum_{k=1}^B P_k \log P_k} \quad . \tag{7}$$

And then we can again choose the feature that maximizes this normalized criterion.

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- So, how to stop splitting?

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- Conversely, if we stop growing the tree too early, the error on the training data will not be sufficiently low and performance will again suffer.
- So, how to stop splitting?
- 1 Cross-validation...
- 2 Threshold on the impurity gradient.
- 3 Incorporate a tree-complexity term and minimize.
- 4 Statistical significance of the impurity gradient.

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# **Stopping by Thresholding the Impurity Gradient**

• Splitting is stopped if the best candidate split at a node reduces the impurity by less than the preset amount,  $\beta$ :

$$\max_{s} \Delta i(s) \le \beta \quad . \tag{8}$$

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- Benefit 2: Leaf nodes can lie in different levels of the tree, which is desirable whenver the complexity of the data varies throughout the range of values.
- Drawback: But, how do we set the value of the threshold  $\beta$ ?

# Stopping with a Complexity Term

• Define a new global criterion function

$$\alpha \cdot \mathsf{size} + \sum_{\mathsf{leaf nodes}} i(N)$$
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- But, again, how do we set the constant  $\alpha$ ?

• During construction, estimate the distribution of the impurity gradients  $\Delta i$  for the current collection of nodes.

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- More generally, we can consider a hypothesis testing approach to stopping: we seek to determine whether a candidate split differs significantly from a random split.
- Suppose we have n samples at node N. A particular split s sends Pn patterns to the left branch and (1-P)n patterns to the right branch. A random split would place  $P_{n_1}$  of the  $\omega_1$  samples to the left,  $P_{n_2}$  of the  $\omega_2$  samples to the left and corresponding amounts to the right.

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• The chi-squared statistic calculates the deviation of a particular split *s* from this random one:

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- When it is greater than a critical value (based on desired significance bounds), we reject the null hypothesis (the random split) and proceed with *s*.
• Tree construction based on "when to stop splitting" biases the learning algorithm toward trees in which the greatest impurity reduction occurs near the root. It makes no attempt to *look ahead* at what splits may occur in the leaf and beyond.

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- Unbalanced trees often result from this style of pruning/merging.
- Pruning avoids the "local"-ness of the earlier methods and uses all of the training data, but it does so at added computational cost during the tree construction.

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#### CART

## Assignment of Leaf Node Labels

- This part is easy...a particular leaf node should make the label assignment based on the distribution of samples in it during training. Take the label of the maximally represented class.
- We will see clear justification for this in the next chapter on Decision Theory.

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CART

#### Instability of the Tree Construction



J. Corso (SUNY at Buffalo)

#### CART

#### **Importance of Feature Choice**

- The selection of features will ultimately play a major role in accuracy, generalization, and complexity.
- This is an instance of the Ugly Duckling principle.



• Furthermore, the use of multiple variables in selecting a decision rule may greatly improve the accuracy and generalization.



Trees

• ID3 is another tree growing method.

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- ID3 is another tree growing method.
- It assumes nominal inputs.
- Every split has a branching factor  $B_j$ , where  $B_j$  is the number of discrete attribute bins of the variable j chosen for splitting.

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- The number of levels in the trees are equal to the number of input variables.
- The algorithm continues until all nodes are pure or there are no more variables on which to split.
- One can follow this by pruning.

C4.5

### C4.5 Method (in brief)

#### • This is a successor to the ID3 method.

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## C4.5 Method (in brief)

- This is a successor to the ID3 method.
- It handles real valued variables like CART and uses the ID3 multiway splits for nominal data.

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# C4.5 Method (in brief)

- This is a successor to the ID3 method.
- It handles real valued variables like CART and uses the ID3 multiway splits for nominal data.
- Pruning is performed based on statistical significance tests.

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# Example from T. Mitchell Book: PlayTennis

Day	Outlook	Temperature	Humidity	Wind	PlayTennis
D1	Sunny	Hot	High	Weak	No
D2	Sunny	Hot	High	Strong	No
D3	Overcast	Hot	High	Weak	Yes
D4	Rain	Mild	High	Weak	Yes
D5	Rain	Cool	Normal	Weak	Yes
D6	Rain	Cool	Normal	Strong	No
D7	Overcast	Cool	Normal	Strong	Yes
D8	Sunny	Mild	High	Weak	No
D9	Sunny	Cool	Normal	Weak	Yes
D10	Rain	Mild	Normal	Weak	Yes
D11	Sunny	Mild	Normal	Strong	Yes
D12	Overcast	Mild	High	Strong	Yes
D13	Overcast	Hot	Normal	Weak	Yes
D14	Rain	Mild	High	Strong	No

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#### Which attribute is the best classifier?





Which attribute should be tested here?

 $S_{sunnv} = \{D1, D2, D8, D9, D11\}$ 

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Hypothesis Space Search by ID3



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#### Learned Tree



**Overfitting Instance** 

• Consider adding a new, noisy training example #15:

Sunny, Hot, Normal, Strong, PlayTennis = No

• What effect would it have on the earlier tree?

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