Introducing Latent Variables

• Define a K-dimensional binary random variable z.

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 (6)
 $\sum_k z_k = 1$ (7)

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$$z_k \in \{0, 1\}$$
 (6)
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 The marginal distribution over z is specified in terms of the mixing coefficients:

And, recall,
$$0 \le \pi_k \le 1$$
 and $\sum_k \pi_k = 1$.
(8)
Corso (SUNY at Buffalo)
Clustering / Unsupervised Methods

 Since z has a 1-of-K representation, we can also write this distribution as

$$p(\mathbf{z}) = \prod_{k=1}^{K} \pi_k^{z_k}$$

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 So, given our latent variable z, the marginal distribution of x is a Gaussian mixture.

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- So, given our latent variable z, the marginal distribution of x is a Gaussian mixture.
- If we have N observations $\mathbf{x}_1, \ldots, \mathbf{x}_N$, then because of our chosen representation, it follows that we have a latent variable \mathbf{z}_n for each observed data point \mathbf{x}_n .

 \bullet We need to also express the conditional probability of z given x.

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$$(\gamma(z_k)) \doteq p(z_k = 1 | \mathbf{x}) = \frac{p(z_k = 1)p(\mathbf{x} | z_k = 1)}{\sum_{j=1}^{K} p(z_j = 1)p(\mathbf{x} | z_j = 1)} .$$

$$(16)$$

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- View π_k as the prior probability of $z_k = 1$ and the quantity $\gamma(z_k)$ as the corresponding posterior probability once we have observed \mathbf{x} .
- γ(z_k) can also be viewed as the responsibility that component k takes
 for explaining the observation x.

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Sampling from the GMM

• To sample from the GMM, we can first generate a value for z from the marginal distribution $p(\mathbf{z})$. Denote this sample $\hat{\mathbf{z}}$.

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- The figure below-left shows samples from a three-mixture and colors the samples based on their z. The figure below-middle shows samples from the marginal $p(\mathbf{x})$ and ignores \mathbf{z} . On the right, we show the $\gamma(z_k)$ for each sampled point, colored accordingly.

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- Similarly, the corresponding latent variables define an $N \times K$ matrix \mathbf{Z} with rows $\mathbf{z}_n^{\mathsf{T}}$.

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- Similarly, the corresponding latent variables define an $N \times K$ matrix **Z** with rows $\mathbf{z}_n^{\mathsf{T}}$.
- The log-likelihood of the corresponding GMM is given by

$$\ln p(\mathbf{X}|\boldsymbol{\pi},\boldsymbol{\mu},\boldsymbol{\Sigma}) = \sum_{n=1}^{N} \ln \left(\sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k,\boldsymbol{\Sigma}_k) \right).$$
(18)
• Ultimately, we want to find the values of the parameter $\boldsymbol{\pi},\boldsymbol{\mu},\boldsymbol{\Sigma}$ that maximize this function.

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• However, maximizing the log-likelihood terms for GMMs is much more complicated than for the case of a single Gaussian. Why?

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- However, maximizing the log-likelihood terms for GMMs is much more complicated than for the case of a single Gaussian. Why?
- The difficulty arises from the sum over k inside of the log-term. The log function no longer acts directly on the Gaussian, and no closed-form solution is available.

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- This term contributes

$$\mathcal{N}(\mathbf{x}_n | \mathbf{x}_n, \sigma_j^2 \mathbf{I}) = \frac{1}{(2\pi)^{(1/2)} \sigma_j}$$
(19)

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- Consider the limit σ_j → 0 to see that this term goes to infinity and hence the log-likelihood will also go to infinity.
- Thus, the maximization of the log-likelihood function is not a well posed problem because such a singularity will occur whenever one of the components collapses to a single, specific data point.



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• Expectation-Maximization or EM is an elegant and powerful method for finding MLE solutions in the case of missing data such as the latent variables z indicating the mixture component.

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- Expectation-Maximization or EM is an elegant and powerful method for finding MLE solutions in the case of missing data such as the latent variables z indicating the mixture component.
- Recall the conditions that must be satisfied at a maximum of the likelihood function.
- For the mean μ_k , setting the derivatives of $\ln p(\mathbf{X}| \pi, \mu, \Sigma)$ w.r.t. μ_k to zero yields

$$0 = -\sum_{n=1}^{N} \frac{\pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^{K} \pi_j \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)} \boldsymbol{\Sigma}_k(\mathbf{x}_n - \boldsymbol{\mu}_k)$$
(20)
$$= -\sum_{n=1}^{N} \gamma(z_{nk}) \boldsymbol{\Sigma}_k(\mathbf{x}_n - \boldsymbol{\mu}_k)$$
(21)

Note the natural appearance of the responsibility terms on the RHS.





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• Multiplying by $\mathbf{\Sigma}_k^{-1}$, which we assume is non-singular, gives

$$\boldsymbol{\mu}_{k} = \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma(z_{nk}) \mathbf{x}_{n}$$

where

$$N_k = \sum_{n=1}^N \gamma(z_{nk}) \tag{23}$$

 We see the kth mean is the weighted mean over all of the points in the dataset.

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- > Interpret N_k as the number of points assigned to component k.
 - We find a similar result for the cogariance matrix:

$$\boldsymbol{\Sigma}_{k} = \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma(z_{nk}) (\boldsymbol{x}_{n} - \boldsymbol{\mu}_{k}) (\boldsymbol{x}_{n} - \boldsymbol{\mu}_{k})^{\mathsf{T}}$$
(24)

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• We also need to maximize $\ln p(\mathbf{X}|\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma})$ with respect to the mixing coefficients π_k .

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- We also need to maximize ln p(X|π, μ, Σ) with respect to the mixing coefficients π_k.
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$$\ln p(\mathbf{X}|\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}) + \lambda \left(\sum_{k=1}^{K} \pi_k - 1\right)$$
(25)

• Maximizing it yields:

$$0 = \frac{1}{N_k} \sum_{n=1}^{\infty} \gamma(z_{nk}) + \lambda$$
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• Eliminate λ and rearrange to obtain: $\pi_{k} = N_{k} \qquad (28)$ J. Corso (SUNY at Buffalo)
Clustering / Unsupervised Methods 33 / 41

 So, we're done, right? We've computed the maximum likelihood solutions for each of the unknown parameters.

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- So, we're done, right? We've computed the maximum likelihood solutions for each of the unknown parameters.
- Wrong!

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- So, we're done, right? We've computed the maximum likelihood solutions for each of the unknown parameters.
- Wrong!
- The responsibility terms depend on these parameters in an intricate way:

$$\gamma(z_k) \doteq p(z_k = 1 | \mathbf{x}) = \frac{\pi_k \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$

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- But, these results do suggest an iterative scheme for finding a solution to the maximum likelihood problem.
 - **①** Chooce some initial values for the parameters, $m{\pi}, m{\mu}, m{\Sigma}$.
 - Our contract of the set of the
 - Output the second se
 - Bepeat 2 and 3 until convergence.

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Expectation-Maximization for GMMs



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Expectation-Maximization for GMMs



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- EM generally tends to take more steps than the K-Means clustering algorithm.
- Each step is more computationally intense than with K-Means too.
- So, one commonly computes K-Means first and then initializes EM from the resulting clusters.
- Care must be taken to avoid singularities in the MLE solution.
- There will generally be multiple local maxima of the likelihood function and EM is not guaranteed to find the largest of these.

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Given a GMM, the goal is to maximize the likelihood function with respect to the parameters (the means, the covarianes, and the mixing coefficients).

1 Initialize the means, μ_k , the covariances, Σ_k , and mixing coefficients, π_k . Evaluate the initial value of the log-likelihood.

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- 2 E-Step Evaluate the responsibilities using the current parameter values:

$$\gamma(z_k) = \frac{\prod_{j=1}^{K} \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^{K} \pi_j \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$

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M-Step Update the parameters using the current responsibilities

$$\boldsymbol{\mu}_{k}^{\mathsf{new}} \neq \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma(z_{nk}) \mathbf{x}_{n}$$

$$\boldsymbol{\Sigma}_{k}^{\mathsf{new}} = \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma(z_{nk}) (\mathbf{x}_{n} - \boldsymbol{\mu}_{k}^{\mathsf{new}}) (\mathbf{x}_{n} - \boldsymbol{\mu}_{k}^{\mathsf{new}})^{\mathsf{T}}$$

$$(30)$$

$$\stackrel{\text{ew}}{=} \frac{N_k}{N} \tag{31}$$

where

$$N_k = \sum_{n=1}^N \gamma(z_{nk}) \tag{32}$$

Clustering / Unsupervised Methods

Evaluate the log-likelihood

$$\ln p(\mathbf{X}|\boldsymbol{\mu}^{\mathsf{new}}, \boldsymbol{\Sigma}^{\mathsf{new}}, \boldsymbol{\pi}^{\mathsf{new}}) = \sum_{n=1}^{N} \ln \left[\sum_{k=1}^{K} \pi_{k}^{\mathsf{new}} \mathcal{N}\left(\mathbf{x}_{n} | \boldsymbol{\mu}_{k}^{\mathsf{new}}, \boldsymbol{\Sigma}_{k}^{\mathsf{new}} \right) \right]$$
(33)

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(33)

One of the convergence of either the parameters of the log-likelihood. If the convergence is not satisfied, set the parameters:

$$\boldsymbol{\mu} = \boldsymbol{\mu}^{\mathsf{new}} \tag{34}$$

$$\Sigma = \Sigma^{\text{new}}$$
 (35)

$$\pi = \pi^{\text{new}}$$
 (36)

and goto step 2.

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• The goal of EM is to find maximum likelihood solutions for models having latent variables.

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- Denote the set of all model parameters as heta, and so the log-likelihood function is

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 - Even if the joint distribution $p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\theta})$ belongs to the exponential family, the marginal $p(\mathbf{X}|\boldsymbol{\theta})$ typically does not.
- If, for each sample \mathbf{x}_n we were given the value of the latent variable \mathbf{z}_n , then we would have a **complete** data set, $\{\mathbf{X}, \mathbf{Z}\}$, with which maximizing this likelihood term would be straightforward.

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- This posterior is used to define the **expectation of the complete-data log-likelihood**, denoted $Q(\theta, \theta^{old})$, which is given by

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• Note that the log acts directly on the joint distribution $p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\theta})$ and so the M-step maximization will likely be tractable. ▲□→ ▲ □ → ▲ □ → □

J. Corso (SUNY at Buffalo)

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