Estimating 3D Respiratory Motion from Orbiting Views

Rongping Zeng, Jeffrey A. Fessler, James M. Balter The University of Michigan

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Motivation

- Free-breathing radiotherapy
 - Incorporating motion into treatment requires a model of geometric changes during breathing
- Existing 4D imaging uses conventional CT scanners (multiple phases @ each couch position)
 - Insufficient spatial coverage to image entire volume during one breathing cycle
 - Assumes reproducibility of internal motion related to "phase" of external monitoring index

Example of conventional 4D CT



Courtesy of Dr. Paul Keall (Virginia Commonwealth University)



Sampling motion continuously using cone-beam projection views

- + large volume coverage
- + high temporal sampling rate
 (3-15 projection views per second)
- -- limited angular range per breathing cycle
 (20-40 degrees for radiotherapy systems)

Possible solutions:

- Assume periodicity, apply cone-beam reconstruction ?
- Couple with prior model of anatomy

Deformation from Orbiting Views (DOV)

- Acquire a high resolution static prior model for anatomy *f* (e.g., conventional breath-hold planning CT)
- Acquire projection views P_t during free breathing from a slowly rotating, high temporal resolution, cone-beam CT system (linac, 1 min per rotation)
- Model motion as deformation of prior through time
- Estimate motion parameters by optimizing the similarity between modeled and actual projection views

"tomographic image registration"

Theory of DOV



• B-spline motion model \mathcal{T}_{θ}

– Controlled by knot distribution and the knot coefficients θ

$$\mathcal{T}^{x}_{\theta}(\vec{x},t) = \sum_{j} \sum_{i} \theta_{i,j} \beta\left(\frac{\vec{x} - \vec{x}_{i}}{h_{x}}\right) \beta\left(\frac{t - \tau_{j}}{h_{t}}\right)$$



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- Cone-beam scanner system model \mathcal{A}
 - distance-driven forward and backward projection method



- Cost function
 - Penalized sum of squared differences



Optimization



- Conjugate gradient descent algorithm
- Multi-resolution technique

*Aperiodicity penalty:

Regularize

 Regularize

 to encourage similarity between the deformations that correspond to similar breathing phases (to help overcome the limited angular range for each breathing cycle)

 Temporal correspondence found from estimated respiratory phase from cone-beam views

Estimating respiratory phase: from the SI position change of the diaphragm

1. Gradient filter each projection image along Cranial-Caudal (CC) direction



2. Project each absolute-valued gradient image onto CC axis



3. Calculate the centroid of each of the projected 1D signal *S*:



4. Smooth the centroid signal



Simulation and results

- Data setup
 - Reference volume:
 192 x 160 x 60 breath-hold thorax CT volume (end of exhale) (voxel size 0.2 x 0.2 x 0.5 cm³)







Axial View

Coronal View

Sagittal View

Synthetic motion for generating simulated projection views

1. Find the deformations between 3 breath-hold CTs at different breathing phases (0%, 20%, 60% tidal volumes) and resample the deformations using a temporal motion function^{*}

2. Simulated four breathing cycles, each with different breathing periods



*A. E. Lujan et.al., "A method for incorporating organ motion due to breathing into 3D dose calculation", Med. Phys., 26(5):715-20, May 1999.

- Cone-beam projection views:
- > Detector size 66 cm x 66 cm, source to detector / isocenter distance 150/100c
- > 70 views over a 180° rotation (2.33 frames/sec)
- > Addition of modelled scatter and Poisson noise:

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N: # of detector elements in one view b_n : a constant related to the incident X-ray intensity $r_{t,n}$: Simulated scatter distribution



- Estimation setup
 - Knot distribution:
 - Spatial knots were evenly spaced by 16,16 and 10 pixels along LR, AP, SI direction respectively
 - Temporal knots were non-uniformly distributed along temporal axis but evenly spaced in each active breathing period (Simulation 1: assumed respiratory phase signal known)
 - > Knot coefficients were initialized to zero for coarse-scale optimization



- Results
 - Minimization took about 50 iterations of Conjugate Gradient Descent, with total computation time about 10 hours on a 3GHz Pentium4 CPU.
 - Motion estimation accuracy (*averaged over entire* volume and through time)

	LR	AP	SI
Mean error (<i>mm</i>)	0.129	0.091	0.112
STD deviation (<i>mm</i>)	0.683	0.826	1.790
RMS error (<i>mm</i>)	0.643	0.758	1.664

Accuracy plot of 20 points

Points projected on central SI slice



Points projected on central LR slice



Points projected on central AP slice





Comparison of the true and estimated 4D CT image



True

Estimated

Difference



• Simulation 2: In practice, we would place temporal knots according to the estimated respiratory phase signal



- Preliminary Results (non-ideal knot locations)
 - Motion estimation accuracy (*averaged over entire* volume and through time)

	LR	AP	SI
Mean error (<i>mm</i>)	0.171	-0.010	0.145
STD deviation (<i>mm</i>)	0.774	1.092	2.014
RMS error (<i>mm</i>)	0.740	0.995	1.875

Accuracy plot of 20 points



Larger motion discrepancies comparing with those with idea temporal knot placement

Need **more investigation** on temporal kn placement and regularization..

Conclusion and future work

- A new method for estimating respiratory motion from slowly rotating cone-beam projection views
- Simulation results validate the feasibility of the method
- Future work
 - More investigation of temporal regularization
 - Application to real CBCT data