

# A Temporal Model for Task-based Functional MRI Reconstruction

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## Introduction

- Goal: better identify task-activated brain regions in task-based fMRI.
- Model: to separate task-correlated signal from non-task background.
- Novelty: use a priori knowledge of activation waveform shape, and temporal smoothness assumption of background.

• Merit: advance model-based **reconstruction** from undersampled *k*-space.

## **Problem Formulation**

**Reconstruct** MR image series from undersampled *k*-space data:

## Results

**Simulated task**: resting-state fMRI with 2 activated Gaussian regions of interest (ROI) in *k*-space, 32 coils,  $N_v = 100 \times 100$ ,  $N_t = 300$ ,  $4 \times$  undersampling



# $\underset{X}{\operatorname{argmin}} \frac{1}{2} \|\mathbf{E}X - d\|_2^2 + \lambda R(X)$

 $\begin{array}{lll} \mathbf{E}: \mathbb{C}^{N_v \times N_t} \to \mathbb{C}^{N_s} & \text{data acquisition operator (where } N_v = \text{number of voxels,} \\ & N_t = \text{number of time frames, } N_s = \text{number of } k \text{-space samples)} \\ & X \in \mathbb{C}^{N_v \times N_t} & \text{desired image series} \\ & d \in \mathbb{C}^{N_s} & \text{undersampled } k \text{-space data} \\ & R(\cdot) & \text{regularizer with parameter } \lambda \end{array}$ 

### **Existing Models**

• Low-Rank Plus Sparse Decomposition (L+S) [1], [2]

 $\underset{L,S}{\operatorname{argmin}} \frac{1}{2} \| \mathbf{E}(L+S) - d \|_{2}^{2} + \lambda_{L} \| L \|_{*} + \lambda_{S} \| \mathbf{T}S \|_{1}$ 

 $L \in \mathbb{C}^{N_v \times N_t}$ non-task background $S \in \mathbb{C}^{N_v \times N_t}$ pseudo-periodic task signal $\mathbf{T} : \mathbb{C}^{N_v \times N_t} \to \mathbb{C}^{N_v N_t}$ temporal Fourier transform operator

• Low-Rank Plus Task-Based Decomposition (L+UV) [3]

 $\underset{L,U}{\operatorname{argmin}} \frac{1}{2} \| \mathbf{E}(L + UV) - d \|_{2}^{2} + \lambda_{L} \| L \|_{*}$ 

**Figure 1:** Left: task waveforms and activation maps by all reconstruction results. Right: B+UV timeseries of two task-activated voxels and a non-task voxel.



Figure 2: Receiver operating characteristic (ROC) curves across activation thresholds with Area Under Curve (AUC).

Finger Tapping Task: 3D task fMRI, 32 coils,  $N_v = 72 \times 48 \times 10$ ,  $N_t = 235$ ,  $4 \times$  undersampling



 $L \in \mathbb{C}^{N_v \times N_t}$  **non-task** background  $U \in \mathbb{C}^{N_v \times N_r}$  estimated **task** spatial map  $V \in \mathbb{C}^{N_r \times N_t}$  temporal basis with activation waveform

## **Proposed Model**

Smooth Background Plus Spatial-Temporal Decomposition (B+UV)

$$\underset{B,U}{\operatorname{argmin}} \frac{1}{2} \| \mathbf{E}(B + UV) - d \|_{2}^{2} + \lambda_{B} \| \mathbf{D}B \|_{2}^{2}$$
(1)

 $B \in \mathbb{C}^{N_v \times N_t}$ temporally smooth non-task background $U \in \mathbb{C}^{N_v \times N_r}$ estimated task spatial map $V \in \mathbb{C}^{N_r \times N_t}$ temporal basis with activation waveform and scanner drift $\mathbf{D} : \mathbb{C}^{N_v \times N_t} \to \mathbb{C}^{N_v N_t}$ temporal finite difference operator

### **Optimization Algorithm**

• Compatibility of vectorization with Kronecker product:  $vec(UV) = (V^{\top} \otimes I)vec(U)$ 

• Write  $\mathbf{E}(UV) = \mathbf{E}_v U$ ,  $\widetilde{\mathbf{E}} = [\mathbf{E} \ \mathbf{E}_v]$ ,  $\widetilde{X} = [B \ U]$ ,  $\widetilde{\mathbf{D}} = [\mathbf{D} \ \mathbf{0}]$ , then (1) becomes

 $\min_{\widetilde{X}} \frac{1}{2} \|\widetilde{\mathbf{E}}\widetilde{X} - d\|_2^2 + \frac{\lambda_B}{2} \|\widetilde{\mathbf{D}}\widetilde{X}\|_2^2$ 

Figure 3: Task waveform and activation maps.

Figure 4: ROC curves with AUC values.

## Conclusion

- Proposed B+UV model improves activation detection compared with existing fMRI models, as seen by higher AUC values.
- B+UV components separate task signal and non-task background.
- Solving B+UV is computationally advantageous with simple CG updates.

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#### • Practical implementation: conjugate gradient (CG) method

#### Advantage over existing models:

- L+S: incoherence between L and S might not apply, and temporal Fourier sparsity assumption of S might not capture activation
- L+UV: both terms are low rank, might not separate signal from background
- B+UV: incoherence between smooth background signal B and task UV

## References

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