An Augmented Lagrangian Method for Regularized MRI Reconstruction Using SENSE

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Introduction: Standard reconstruction methods for SENSitivity Encoding (SENSE) [1, 2] suffer from SNR degradation due to k-space undersampling and instability arising from correlation in sensitivity maps. Nonquadratic regularization can be used to improve reconstruction quality but demands computation intensive nonlinear optimization. We present a new algorithm for (nonquadratic) regularized reconstruction from sensitivity-encoded data—SENSE-reconstruction—using the augmented Lagrangian (AL) formalism that constitutes a powerful framework for solving large-scale constrained optimization problems. Based on numerical experiments with invivo human brain data, we demonstrate that the proposed AL algorithm converges faster compared to general-purpose algorithms such as nonlinear conjugate gradient (NCG) (that has been used for compressed sensing MRI [3]) and state-of-the-art Monotone Fast Iterative Shrinkage-Thresholding Algorithm (MFISTA) [4].

(e)

Problem Formulation: We employ a combination of TV and l_1 -regularization and formulate regularized SENSEreconstruction as **P0**: $\mathbf{x}_{recon} = arg \ min_x \ 1/2 \ \|\mathbf{d} - \mathbf{FSx}\|^2 + \lambda_1 \ \|\mathbf{Wx}\|_1 + \lambda_2 \ \text{TV}\{\mathbf{x}\}, \text{ where } \mathbf{d} \text{ represents undersampled}$ data from a coil-array, F and S represent the Fourier encoding and sensitivity-map matrices, respectively, W represents 2-levels of undecimated Haar-wavelet transform (excluding "scaling" coefficients), and $TV\{x\} = \sum_i (\sum_n a_n x^n + \sum_{i=1}^n a_n x^n +$ $\|\mathbf{R}_n \mathbf{x}\|_{2}^{2}$ is composed of matrices \mathbf{R}_n that correspond to finite-differences along the *n*-th spatial dimension of the image, n=1,2,...d, $[\mathbf{x}]_i$ denotes the *i*-th element of \mathbf{x} , and λ_1 , and λ_2 are regularization parameters. The above formulation can be used to deal with correlated noise after applying a suitable noise-decorrelation procedure [2].

Method: We write **P0** as an equivalent constrained optimization problem **P1:** $arg min_u f(u)$ subject to $u_0 = Sx$, $\mathbf{u}_{1} = \mathbf{R}\mathbf{u}_{2}$, and $\mathbf{u}_{2} = \mathbf{x}$, where $\mathbf{R} = [\mathbf{W}^{T} \mathbf{R}_{11}^{T} ... \mathbf{R}_{1d}^{T}]^{T}$, $\mathbf{u}_{1} = [\mathbf{u}_{10}^{H} \mathbf{u}_{11}^{H} ... \mathbf{u}_{1d}^{H}]^{H}$ whose components $\{\mathbf{u}_{1n}\}$ correspond to the block-rows of \mathbf{R} , $\mathbf{u} = [\mathbf{u}_{0} \mathbf{u}_{1} \mathbf{u}_{2} \mathbf{x}]$, and $f(\mathbf{u}) = 1/2 \|\mathbf{d} - \mathbf{F}\mathbf{u}_{0}\|^{2} + \lambda_{1} \|\mathbf{u}_{10}\|_{1} + \lambda_{2} \sum_{i} (\sum_{n} |[\mathbf{u}_{1n}]_{i}|^{2})^{1/2}$. This type of constrained reformulation is different from those in [5, 6]. We construct an AL function [7] for P1 using a Lagrange multiplier $\boldsymbol{\eta} = [\boldsymbol{\eta}_0 \ \boldsymbol{\eta}_1 \ \boldsymbol{\eta}_2]$ as $L(\mathbf{u}, \boldsymbol{\eta}, \mu) = f(\mathbf{u}) + \mu/2 \|\mathbf{u}_0 - \mathbf{S}\mathbf{x} - \boldsymbol{\eta}_0\|^2 + \mu v_1/2 \|\mathbf{u}_1 - \mathbf{R}\mathbf{u}_2 - \boldsymbol{\eta}_1\|^2 + \mu v_2/2 \|\mathbf{u}_2 - \mathbf{x} - \mathbf{u}_2\|^2 + \mu v_1/2 \|\mathbf{u}_1 - \mathbf{R}\mathbf{u}_2 - \mathbf{u}_1\|^2 + \mu v_2/2 \|\mathbf{u}_2 - \mathbf{x} - \mathbf{u}_2\|^2 + \mu v_1/2 \|\mathbf{u}_1 - \mathbf{u}_2\|^2 + \mu v_2/2 \|\mathbf{u}_2 - \mathbf{u}_1\|^2 + \mu v_2/2 \|\mathbf{u}_2 - \mathbf{u}_1\|^2 + \mu v_1/2 \|\mathbf{u}_1 - \mathbf{u}_2\|^2 + \mu v_1/2 \|\mathbf{u}_2\|^2 + \mu v_1/2 \|\mathbf{u}_1 - \mathbf{u}_2\|^2 + \mu v_1/2 \|\mathbf{u}_2\|^2 + \mu v_1/2 \|\mathbf{u}_1 - \mathbf{u}_2\|^2 + \mu v_1/2$ $|\eta_2|^2$, where $|\mu_1 v_1, v_2| > 0$ are scalars that do not affect the solution of **P1** (and **P0**). The traditional AL scheme [7] for solving P1 alternates between jointly minimizing L with respect to $\mathbf{u} = [\mathbf{u}_0 \ \mathbf{u}_1 \ \mathbf{u}_2 \ \mathbf{x}]$ for a fixed $\boldsymbol{\eta}$ and updating $\boldsymbol{\eta}$. The joint-minimization step can be computationally expensive, so we apply an alternating minimization scheme (that minimizes L alternatively with respect to \mathbf{u}_0 , \mathbf{u}_1 , \mathbf{u}_2 , and \mathbf{x} one at a time while holding the others at their most recent values). This simplifies the minimization leading to the following AL algorithm for solving P1 (and P0).

AL algorithm:

Select $\mathbf{u}^{(0)}$, $\boldsymbol{\eta}^{(0)}$ and $\mu, v_1, v_2 > 0$; set iteration number m = 0; Repeat until stop criterion is met;

1. $\mathbf{u}_0^{(m+1)} = arg \min_{\mathbf{u}_0} 1/2 \|\mathbf{d} - \mathbf{F} \mathbf{u}_0^{(m)}\|^2 + \mu/2 \|\mathbf{u}_0 - \mathbf{S} \mathbf{x}^{(m)} - \boldsymbol{\eta}_0^{(m)}\|^2$; 2. $\mathbf{u}_{1}^{(m+1)} = arg \min_{\mathbf{u}_{1}} \lambda_{1} \|\mathbf{u}_{10}\|_{1} + \lambda_{2} \sum_{i} (\sum_{u} \|[\mathbf{u}_{1n}]_{i}|^{2})^{1/2} + \mu v_{1}/2 \|\mathbf{u}_{1} - \mathbf{R} \mathbf{u}_{2}^{(m)} - \boldsymbol{\eta}_{1}^{(m)}\|^{2};$ $\begin{aligned} & \mathbf{a.s.} & \min_{\mathbf{u}} \sum_{l} \|\mathbf{u}_{10}\|_{l} + \alpha_{l} \|\mathbf{u}_{10}\|_{l} + \alpha_{l} \sum_{l} \|\mathbf{u}_{10}\|_{l} \|\mathbf{u}_{1}\|_{l} \|\mathbf{u}_{1}\|_{l} \|\mathbf{u}_{1}\|_{l} \\ & 3. \ \mathbf{u}_{2}^{(m+1)} = \arg\min_{\mathbf{u}_{2}} v_{1}/2 \ \|\mathbf{u}_{1}^{(m+1)} - \mathbf{R}\mathbf{u}_{2} - \boldsymbol{\eta}_{1}^{(m)}\|_{l}^{2} + v_{2}/2 \ \|\mathbf{u}_{2} - \mathbf{x}^{(m)} - \boldsymbol{\eta}_{2}^{(m)}\|_{l}^{2} \\ & 4. \ \mathbf{x}^{(m+1)} = \arg\min_{\mathbf{u}_{1}} 1/2 \ \|\mathbf{u}_{0}^{(m+1)} - \mathbf{S}\mathbf{x} - \boldsymbol{\eta}_{0}^{(m)}\|_{l}^{2} + v_{2}/2 \ \|\mathbf{u}_{2}^{(m+1)} - \mathbf{x} - \boldsymbol{\eta}_{2}^{(m)}\|_{l}^{2} \\ & 5. \ \boldsymbol{\eta}_{0}^{(m+1)} = \boldsymbol{\eta}_{0}^{(m)} - (\mathbf{u}_{0}^{(m+1)} - \mathbf{S}\mathbf{x}^{(m+1)}); \\ & 6. \ \boldsymbol{\eta}_{1}^{(m+1)} = \boldsymbol{\eta}_{1}^{(m)} - (\mathbf{u}_{1}^{(m+1)} - \mathbf{R}\mathbf{u}_{2}^{(m+1)}); \\ & 7. \ \boldsymbol{\eta}_{2}^{(m+1)} = \boldsymbol{\eta}_{2}^{(m)} - (\mathbf{u}_{2}^{(m+1)} - \mathbf{x}^{(m+1)}); \end{aligned}$ 8. m = m + 1;

Step 2 of the AL algorithm is a denoising problem (that can further be decoupled in terms of the individual elements of \mathbf{u}_1) whose solution is obtained using shrinkage operations [5]. Steps 1, 3, and 4 involve quadratic costs and therefore have closed-form updates with simple matrix-inverses that can be computed efficiently. We adjust μ , v_1 , and v_2 based on easily computed condition numbers of these matrix-inverses for fast convergence of the proposed AL algorithm.

Results: We used a 3-D in-vivo human brain data-set (256x144 uniformly-spaced samples in the phase-encode plane, and 128 samples along the read-out direction) acquired from a GE 3T scanner ($T_R = 25 \text{ ms}$, $T_E = 5.172 \text{ ms}$, and voxel-size = 1x1.35x1 mm³), with a 8-channel head-coil. Figure 1a shows one slice of the iFFT-reconstruction of fully-sampled data collected with a body-coil for comparison. To estimate the sensitivity maps S, we separately optimized a quadratic-regularized least-squares criterion that encouraged smooth maps that "closely" fit a low-

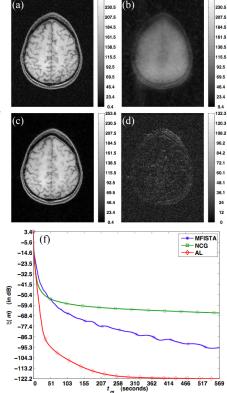


Fig. 1 Experiment with a 2-D slice of a in-vivo human brain data-set: (a) Body-coil image; (b) Zero-filled iFFT reconstruction; (c) Regularized SENŠE-reconstruction x*; (d) Absolute difference between (a) and (c); (e) Poisson-disk-based undersampling pattern (on a Cartesian grid); (f) *Plot of* $\xi(m)$ *versus* t_m *for* **AL**, *NCG and MFISTA*.

resolution version of the body-coil image in Figure 1a to low-resolution head-coil images, all obtained from iFFT-reconstruction of corresponding central 32x32 phaseencodes. We estimated the inverse of noise covariance matrix from data collected during a dummy scan where only the static magnetic-field (and no RF excitations) was applied and carried out noise-decorrelation of data as described in [2]. We then performed regularized SENSE-reconstruction of the 2-D slice (corresponding to Figure 1a) from undersampled phase-encodes where we applied the Poisson-disk-based undersampling pattern (with a reduction factor of ≈ 6) in Figure 1e in the phaseencode plane. We obtained the reconstruction x* (that represents a solution of P0) numerically by running thousands of iterations of MFISTA. Figure 1c shows x* where aliasing artifacts and noise have been suppressed considerably compared to the conventional (square-root of sum-of-squares) zero-filled iFFT-reconstruction in Figure 1b. We compared the proposed AL algorithm to NCG and MFISTA in terms of speed of convergence to the reconstruction x* by computing the normalized l2distance $\xi(m)$ between the estimate $\mathbf{x}^{(m)}$ and \mathbf{x}^* as $\xi(m) = 20 \log_{10}(\|\mathbf{x}^{(m)} - \mathbf{x}^*\|_2/\|\mathbf{x}^*\|_2)$. We evaluated $\xi(m)$ for all algorithms and plotted it as a function of algorithm runtime t_m (time elapsed from start until iteration m) in Figure 1f. It is seen that AL converges faster than NCG and MFISTA. We obtained promising results (not shown) similar to that in Figure 1 for experiments with several slices of the above human brain data-set and with various synthetic data-sets and a real breast-phantom data-set.

Conclusions: The augmented Lagrangian (AL) formalism combined with alternating minimization can be used for solving large-scale unconstrained optimization problems effectively by posing them as equivalent constrained tasks. We adopted such an approach for regularized SENSE-reconstruction and developed an AL algorithm that converges faster than NCG and MFISTA, is simple to implement and can also be easily extended to handle (combinations of) several nonquadratic regularization criteria.

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