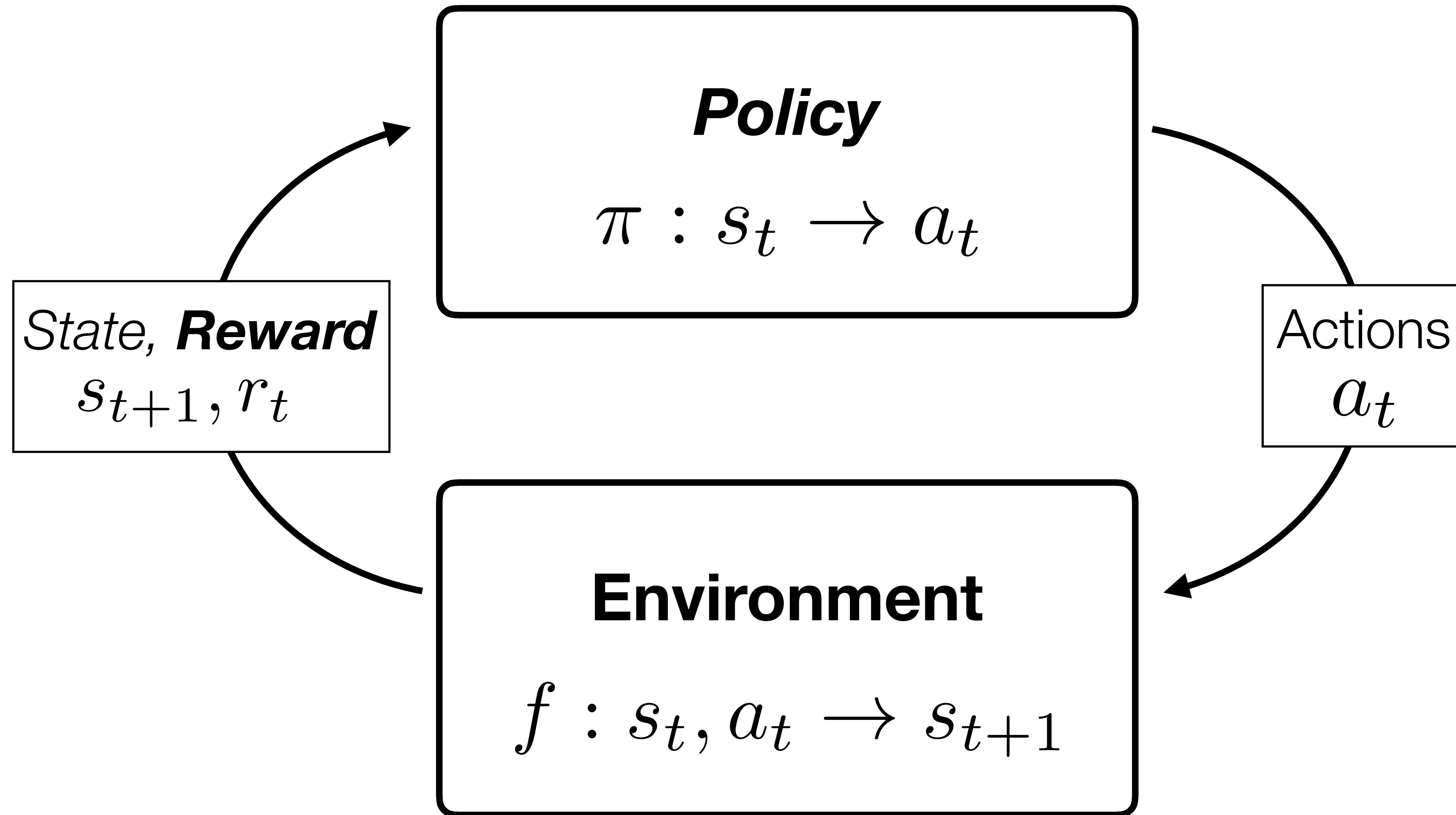


Lecture 26: More embodied learning + Ethics in computer vision (part 1)

Today

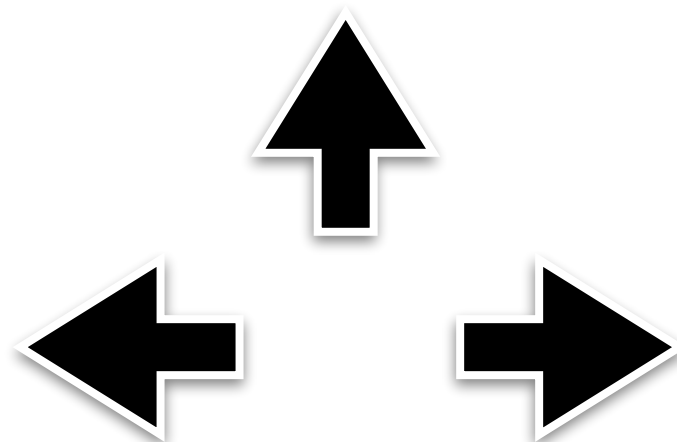
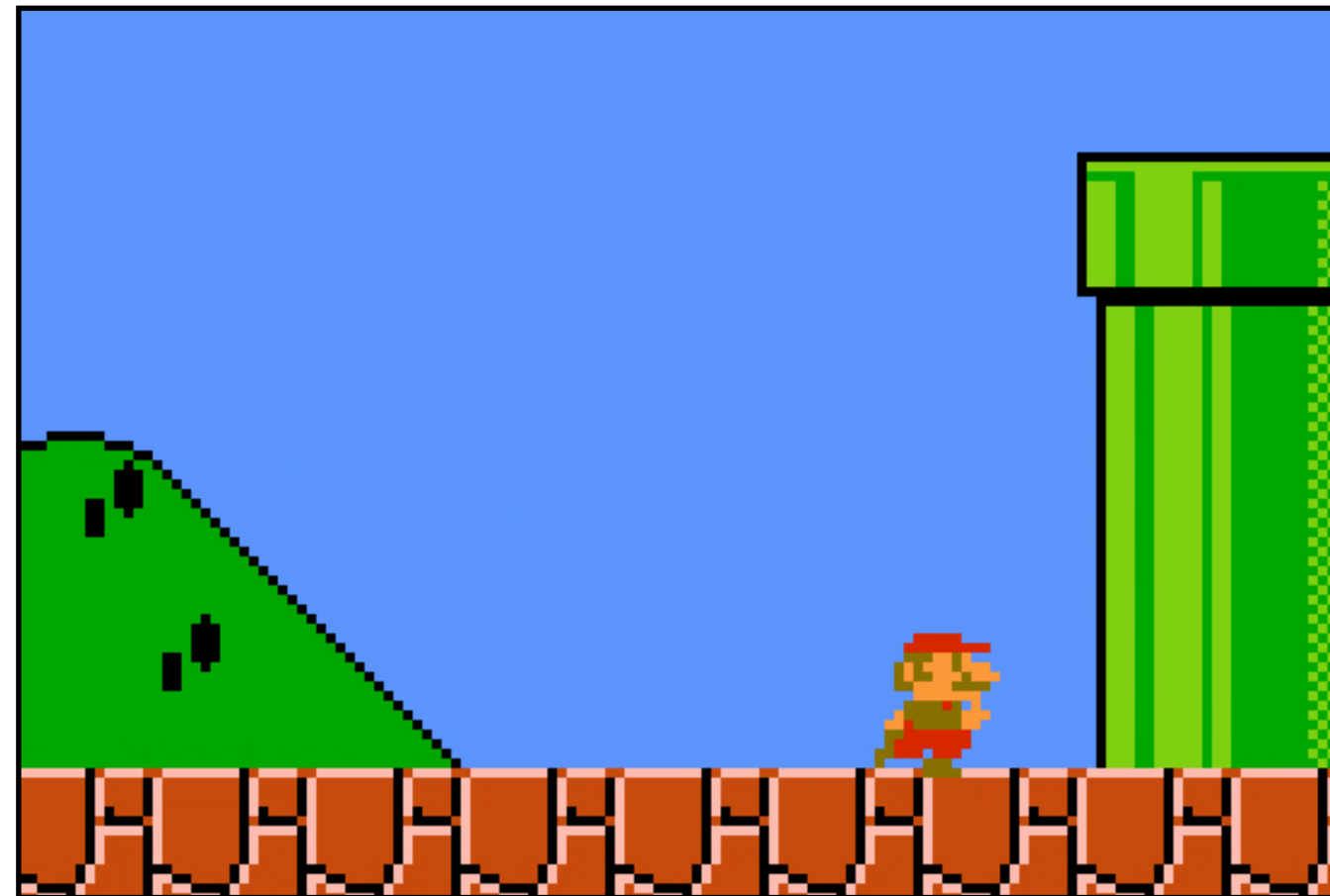
- Embodied learning
 - Q-learning
 - Playing games
 - Model-based reinforcement learning
- Ethics in computer vision (part 1)
 - Detecting fake images

Recall: Reinforcement learning

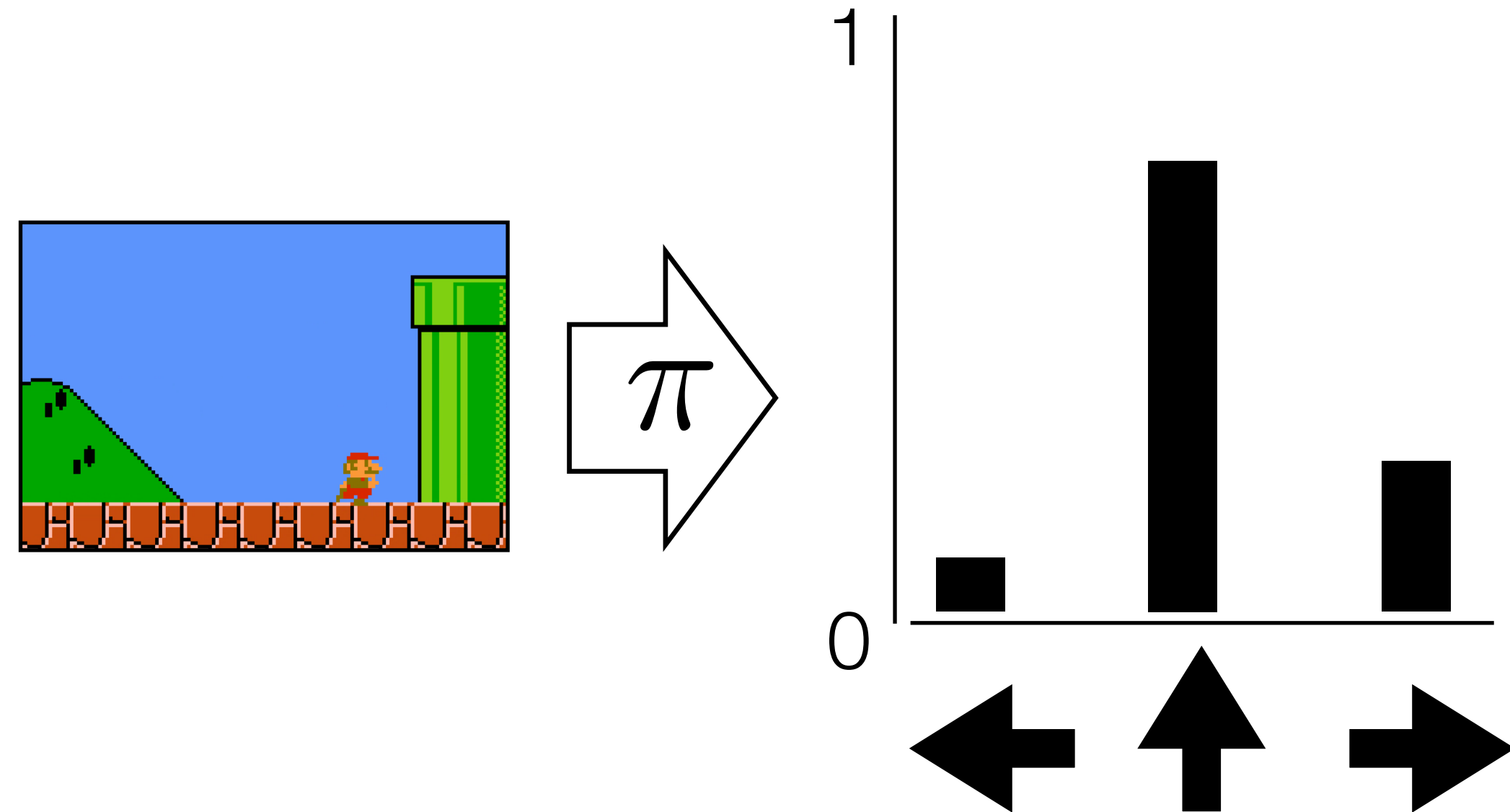


Recall: Reinforcement learning

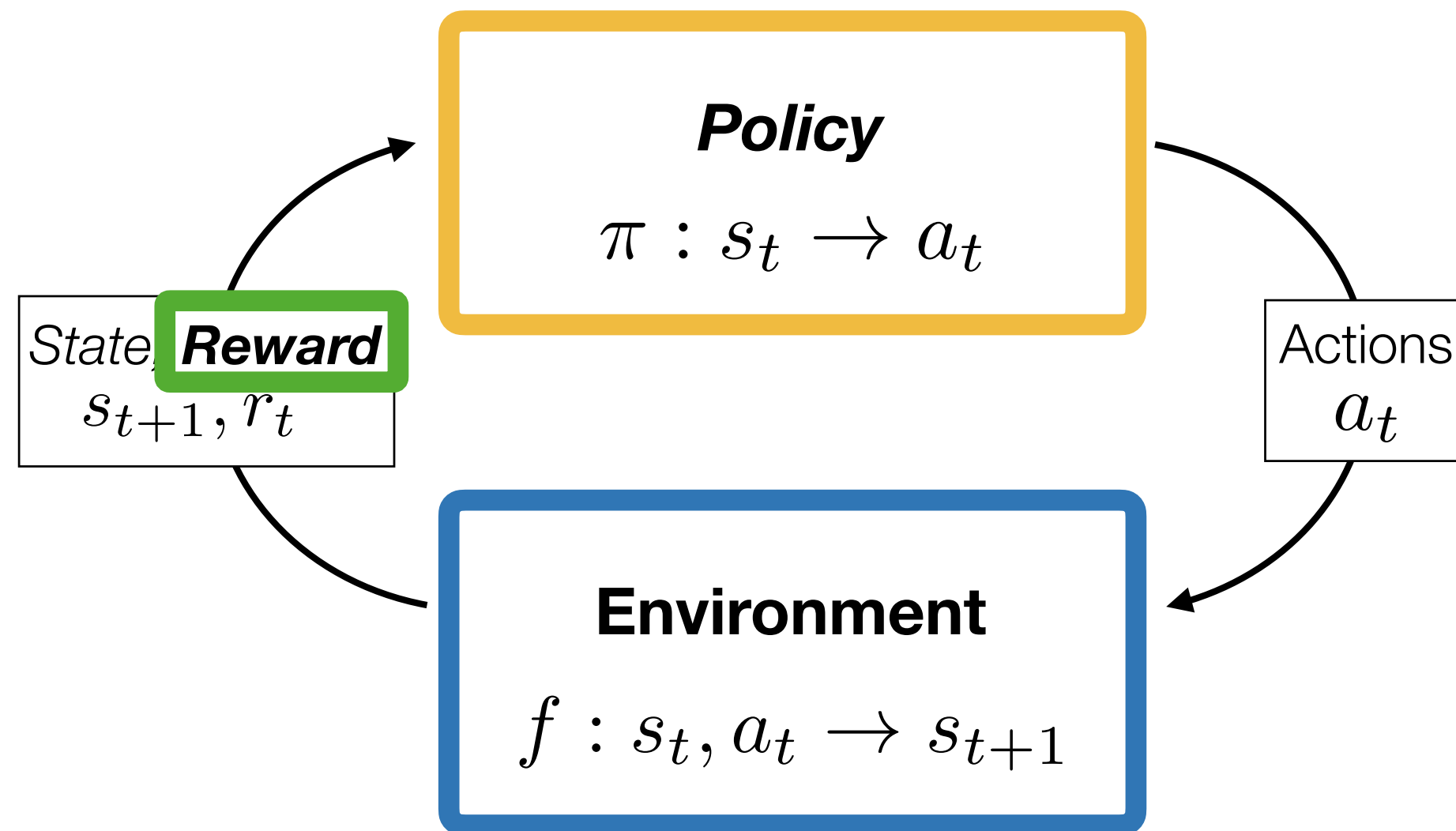
state: pixels!



policy: action classifier

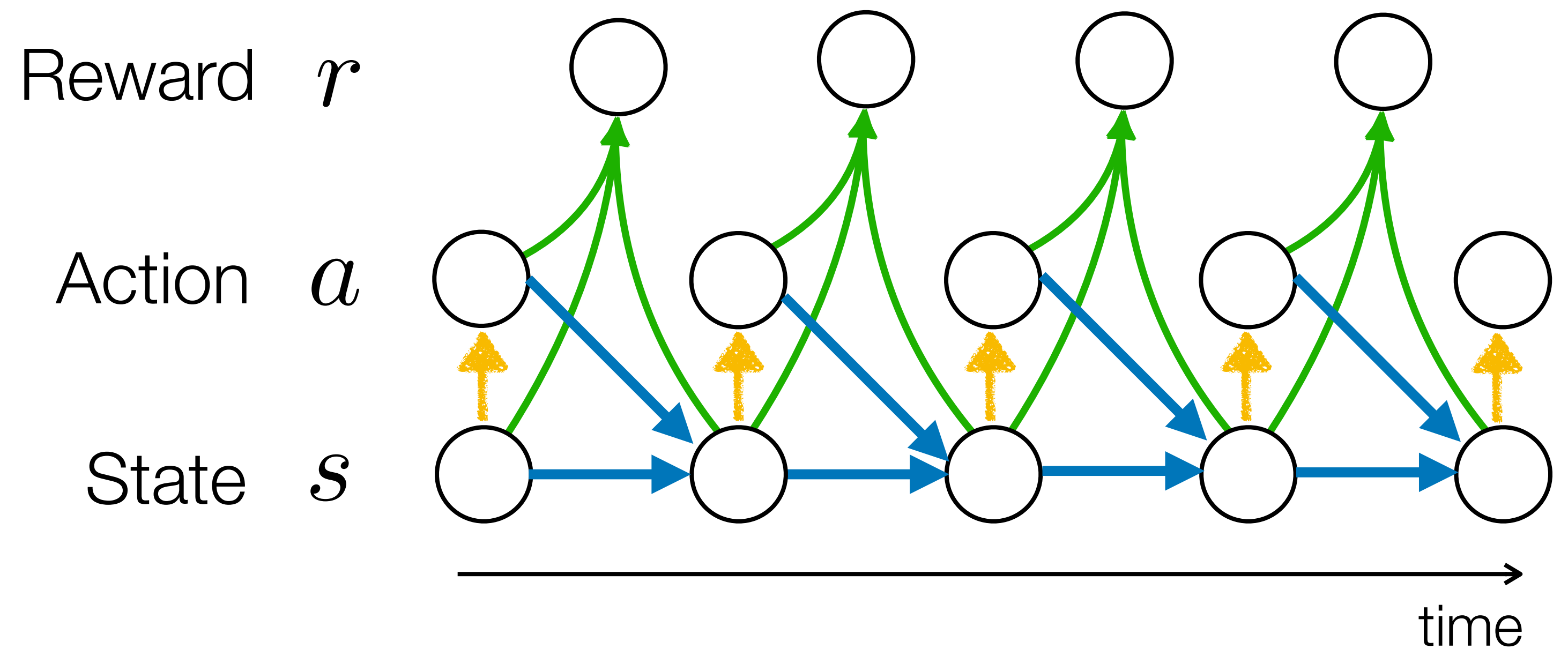


Reinforcement learning



Markov decision process (MDP)

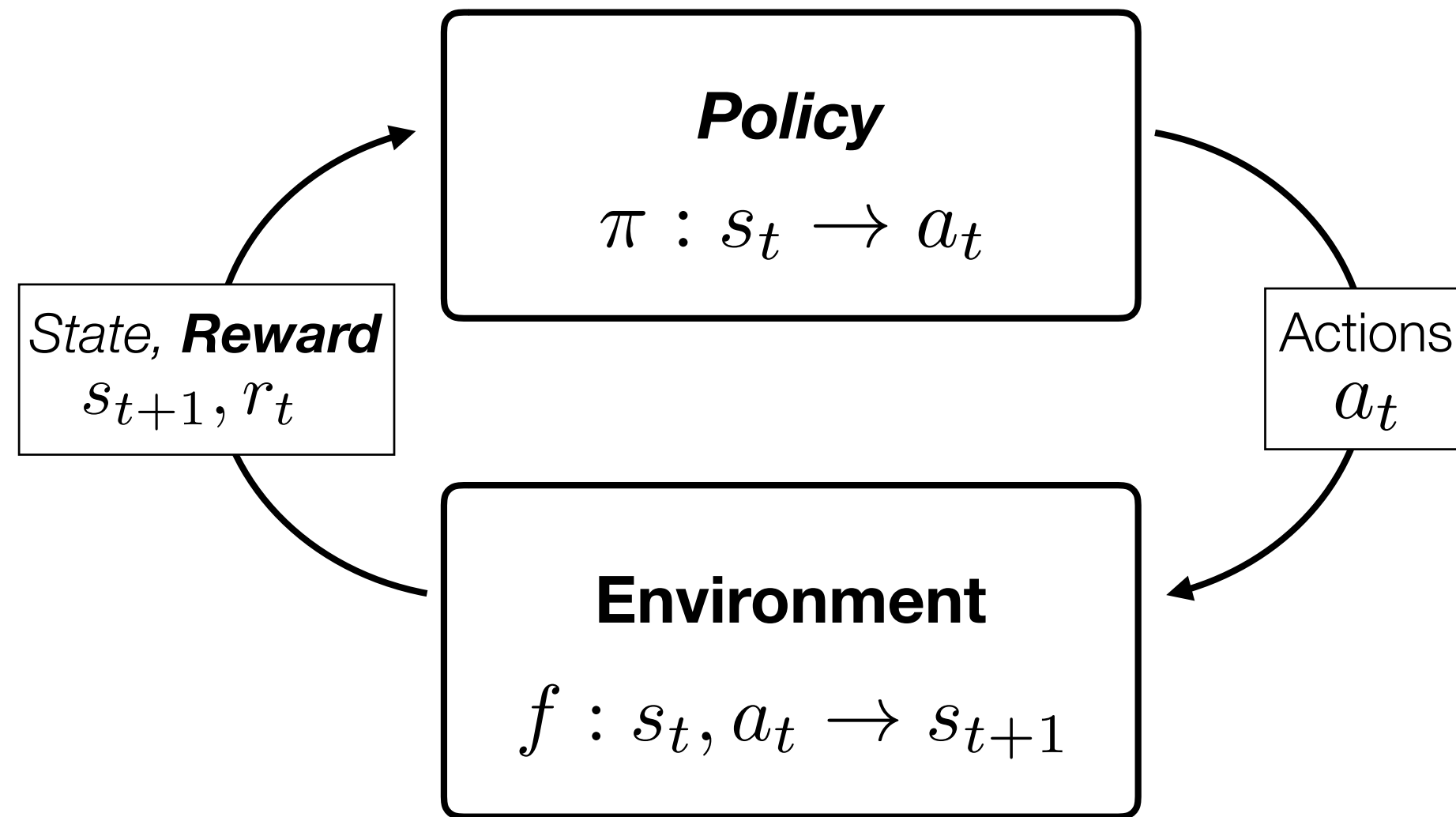
Learned



A sample from the MDP is called a **Trajectory**

$$\tau = (s_0, a_0, r_0, s_1, a_1, r_1, \dots)$$

Recall: Reinforcement learning

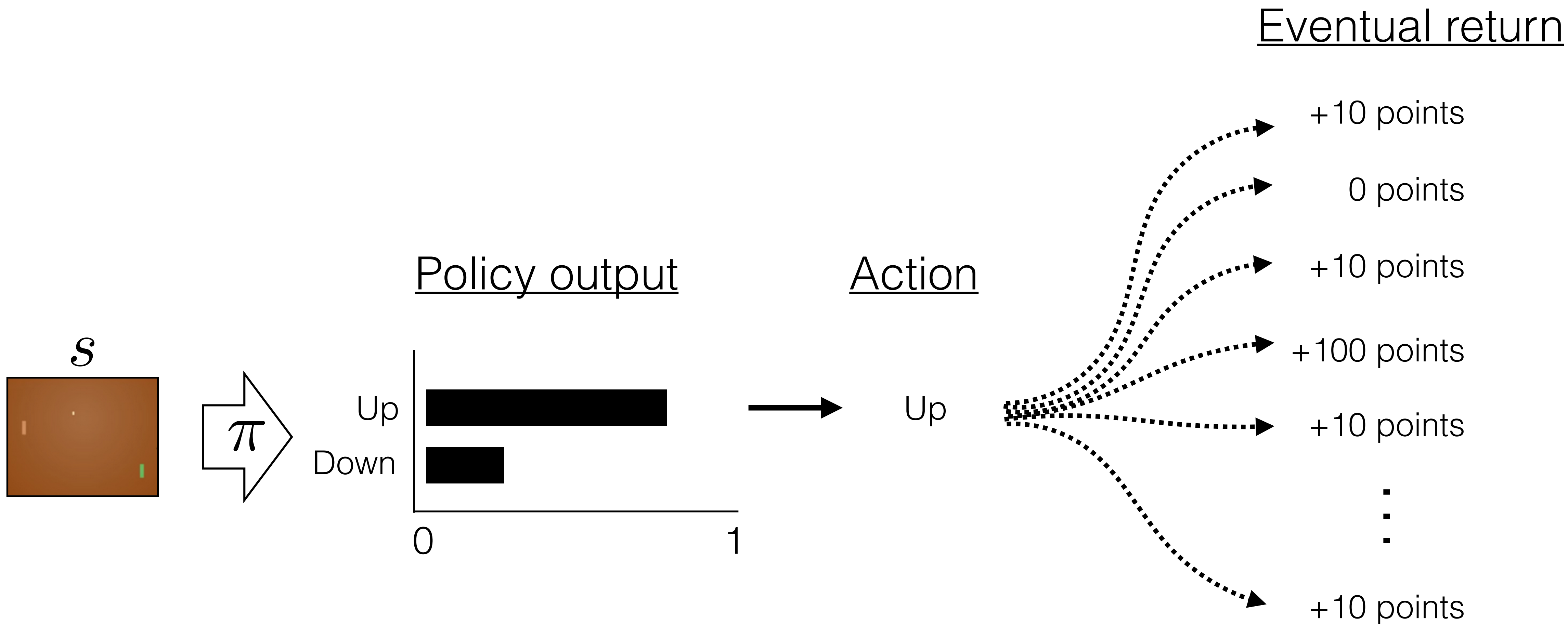


Trajectory $\tau = (s_0, a_0, r_0, s_1, a_1, r_1, \dots)$

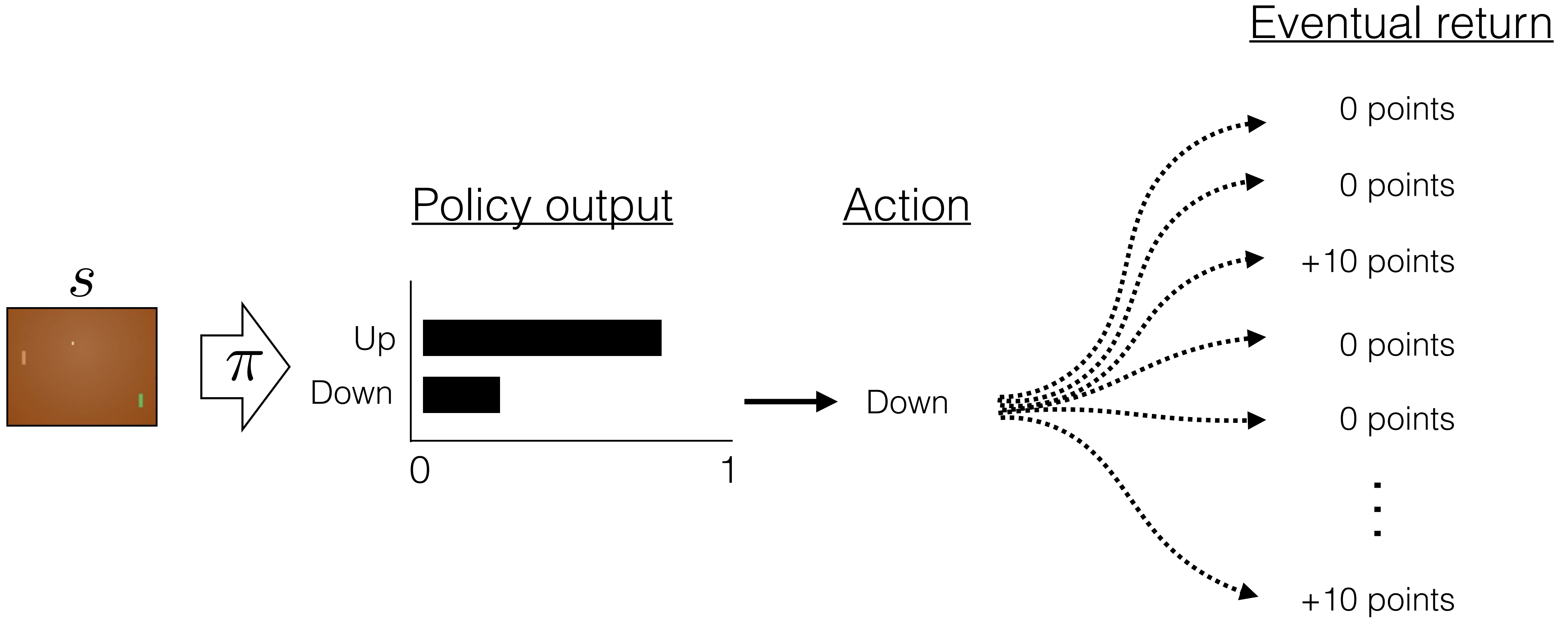
Discounted Returns $R(\tau) = \sum_{t=0}^{\infty} \gamma^t r_t, \quad \gamma \in (0, 1)$

Learn a policy that takes actions that maximize expected reward

$$\pi^* = \arg \max_{\pi} \mathbb{E}_{\tau \sim \pi} [R(\tau)]$$

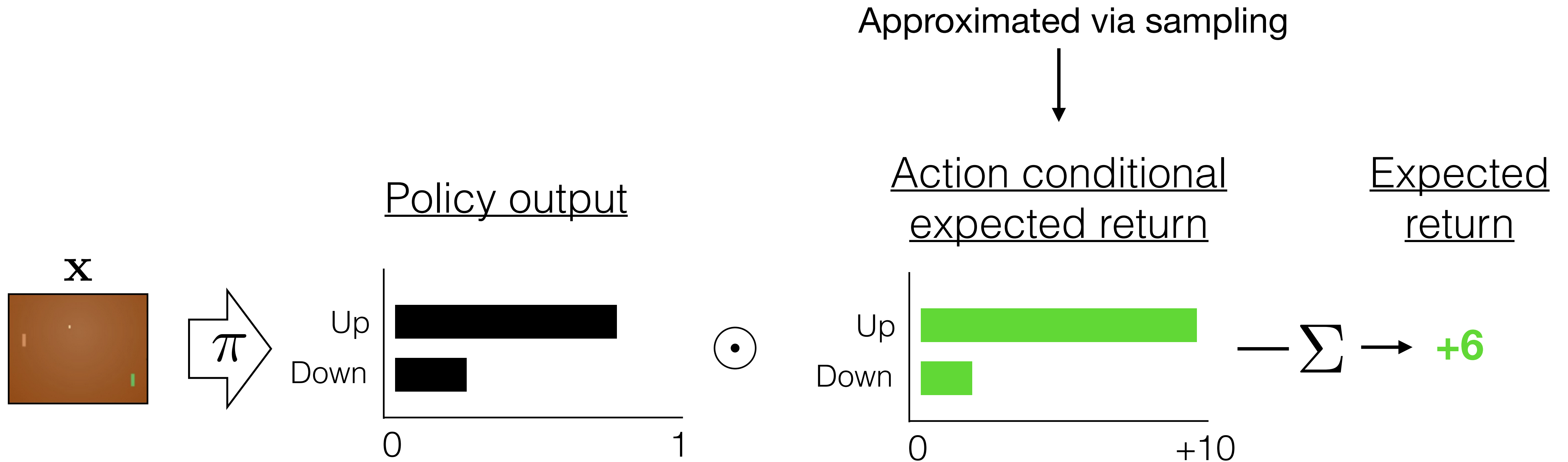


$\pi(a|s)$ = probability of choosing action a given state s



$\pi(a|s)$ = probability of choosing action a given state s

Recall: Policy gradient

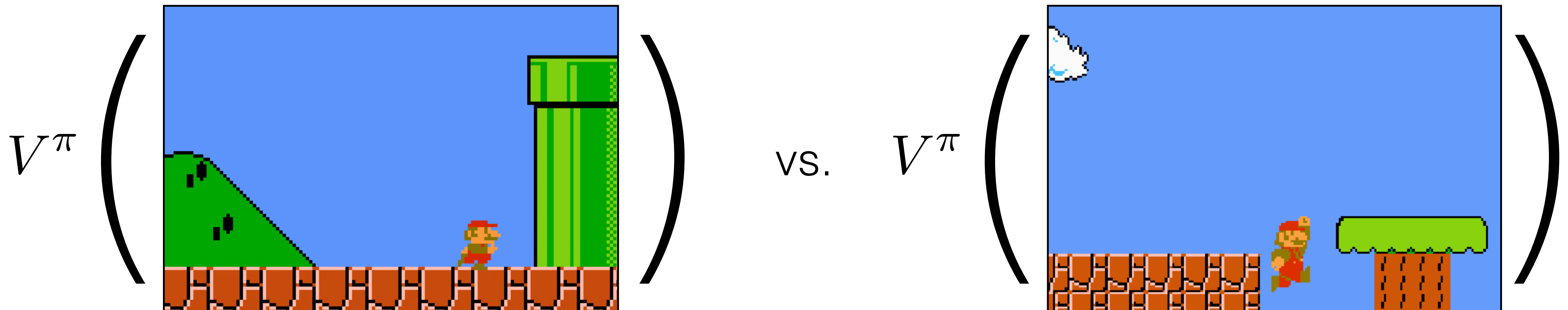


$$\nabla_{\theta} \mathbb{E}_{\tau \sim \pi_{\theta}} [R(\tau)] = \mathbb{E}_{\tau \sim \pi_{\theta}} [R(\tau) \nabla_{\theta} \log \pi_{\theta}] \quad \leftarrow \text{Estimate gradient using REINFORCE and do gradient descent on policy}$$

How good is a state?

Value function: expected future reward from starting in s .

$$V^{\pi}(s) = \mathbb{E} \left[\sum_{t \geq 0} \gamma^t r_t \mid s_0 = s, \pi \right]$$



- One advantage is *credit assignment*. We know which state/action was useful.
- Often more sample efficient, and updates have less variance.

How good is a state-action pair?

- Could we *learn* the value function and use it to choose actions?
 - Doesn't quite work. You'd also need to know the dynamics, i.e. what state you'd end up with if you took each action.
- Instead, learn **action-value function** (or **Q function**).

$$Q(s, a) = \mathbb{E} \left[\sum_{t \geq 0} R_t \mid s_0 = s, a_t = a \right]$$

- Optimal action for a state: $\operatorname{argmax}_a Q(s, a)$

Finding a good Q function

- Good Q function should satisfy a recurrence relation called the Optimal Bellman Equation:

Quality of state/action pair Where will I end up? What if I take the *very best* next action?

$$Q^*(s, a) = r(s, a) + \gamma \mathbb{E}_{p(s'|s, a)} \left[\max_{a'} Q^*(s_{t+1}, a') \mid s_t = s, a_t = a \right]$$

Finding a good Q function

- Measuring the Bellman error for Q:

$$r(s_t, a_t) + \gamma \max_a Q(s_{t+1}, a) - Q(s_t, a_t)$$

- Approximate Q with a neural net $Q(s, a; \theta)$. For each episode i :

1. Do the policy induced by Q and get a trajectory:

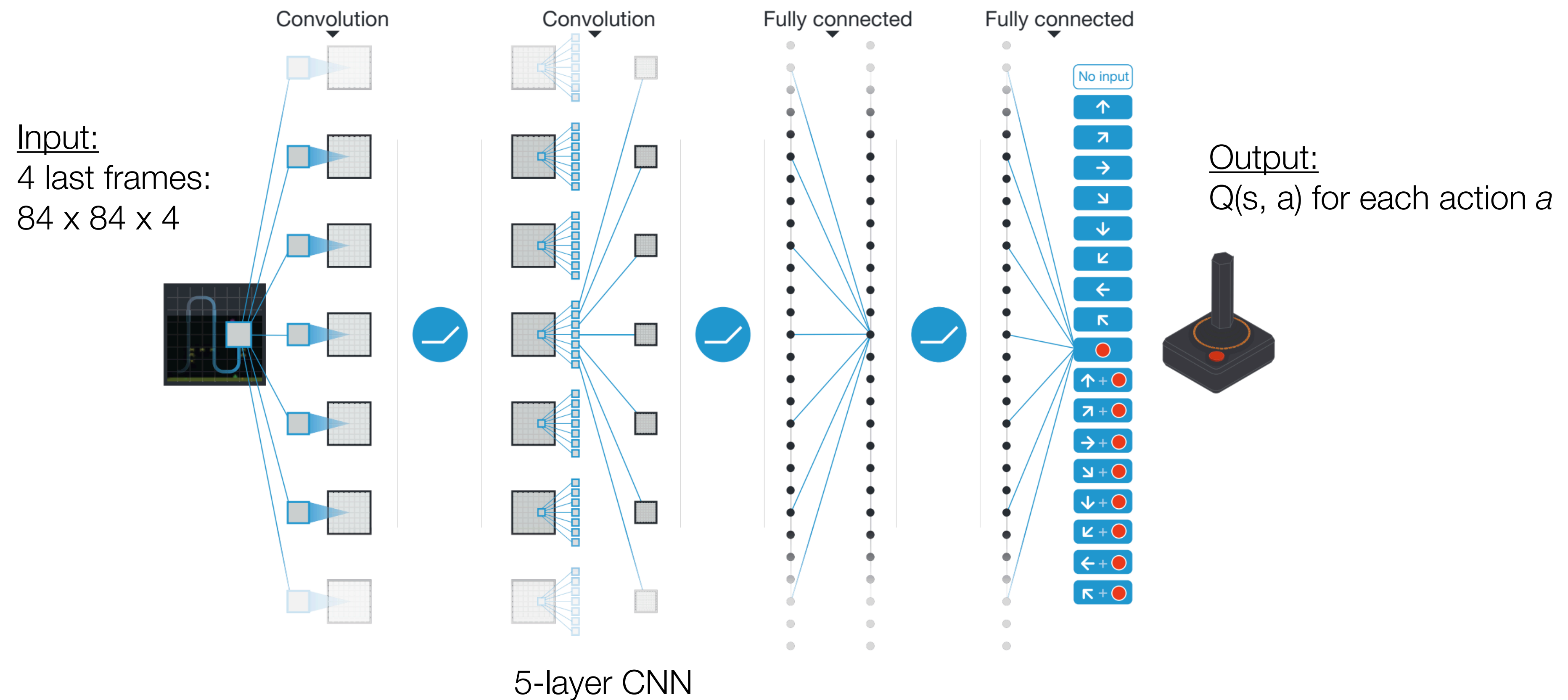
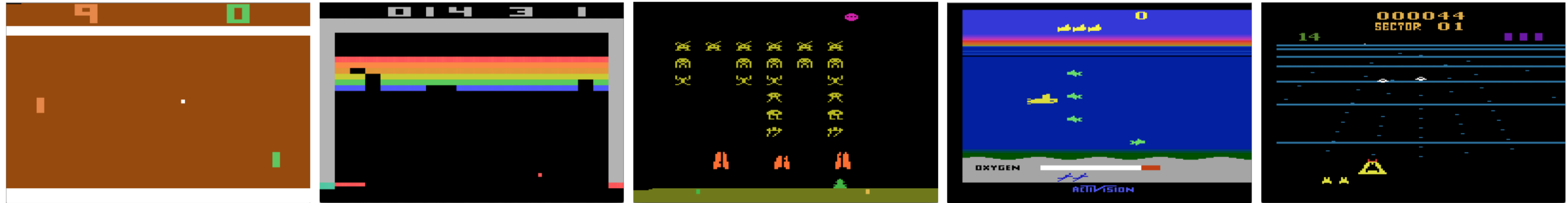
$$\tau = (s_0, a_0, r_0, s_1, a_1, r_1, \dots)$$

2. Update the parameters using backprop, minimizing approximation error:

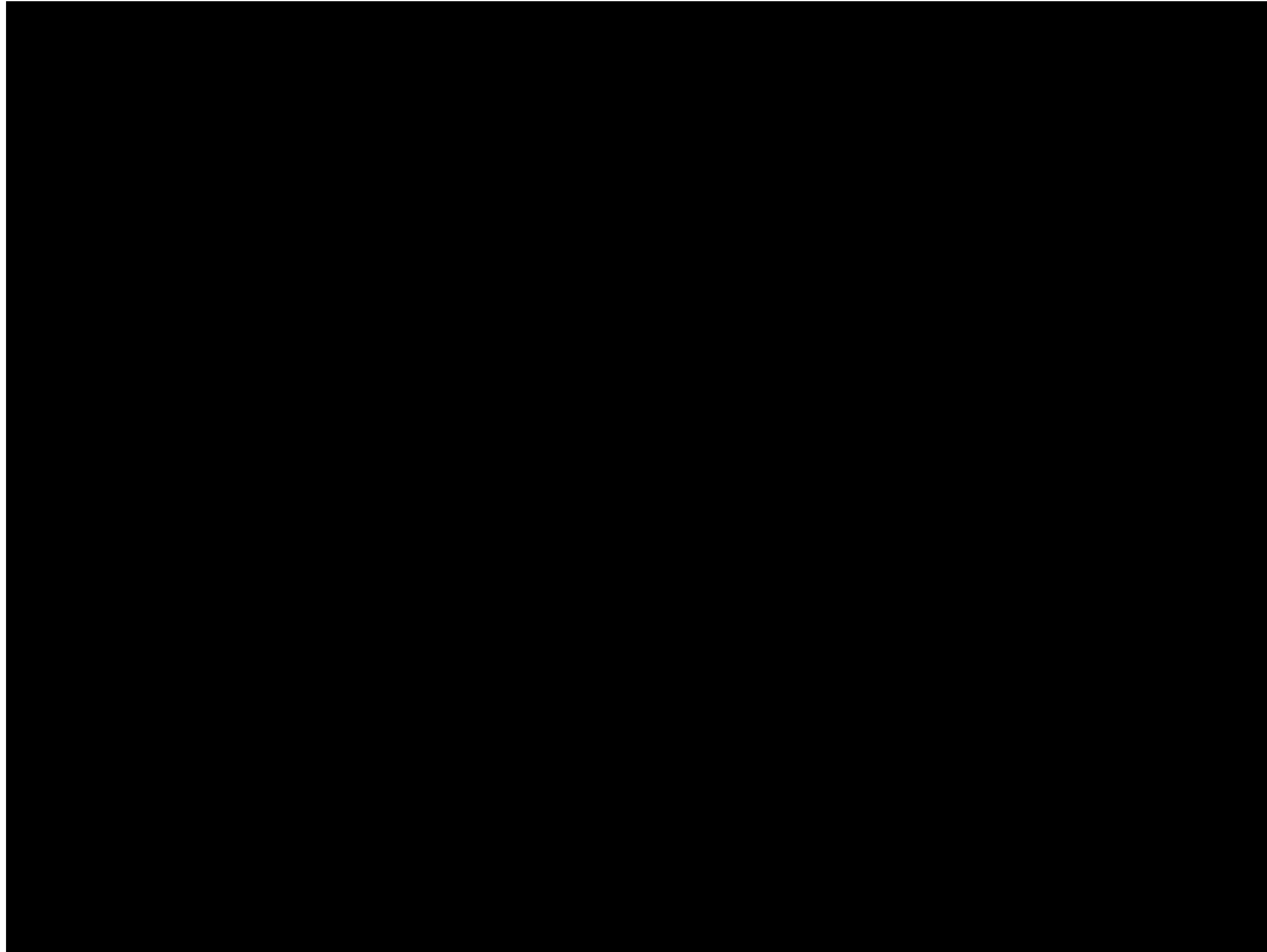
$$t_i = r(s_t, a_t) + \gamma \max_a Q(s_{t+1}, a; \theta_{i-1})$$

$$L(\theta_i) = (t_i - Q(s_t, a_t; \theta_i))^2$$

Playing Atari games



Playing Atari games

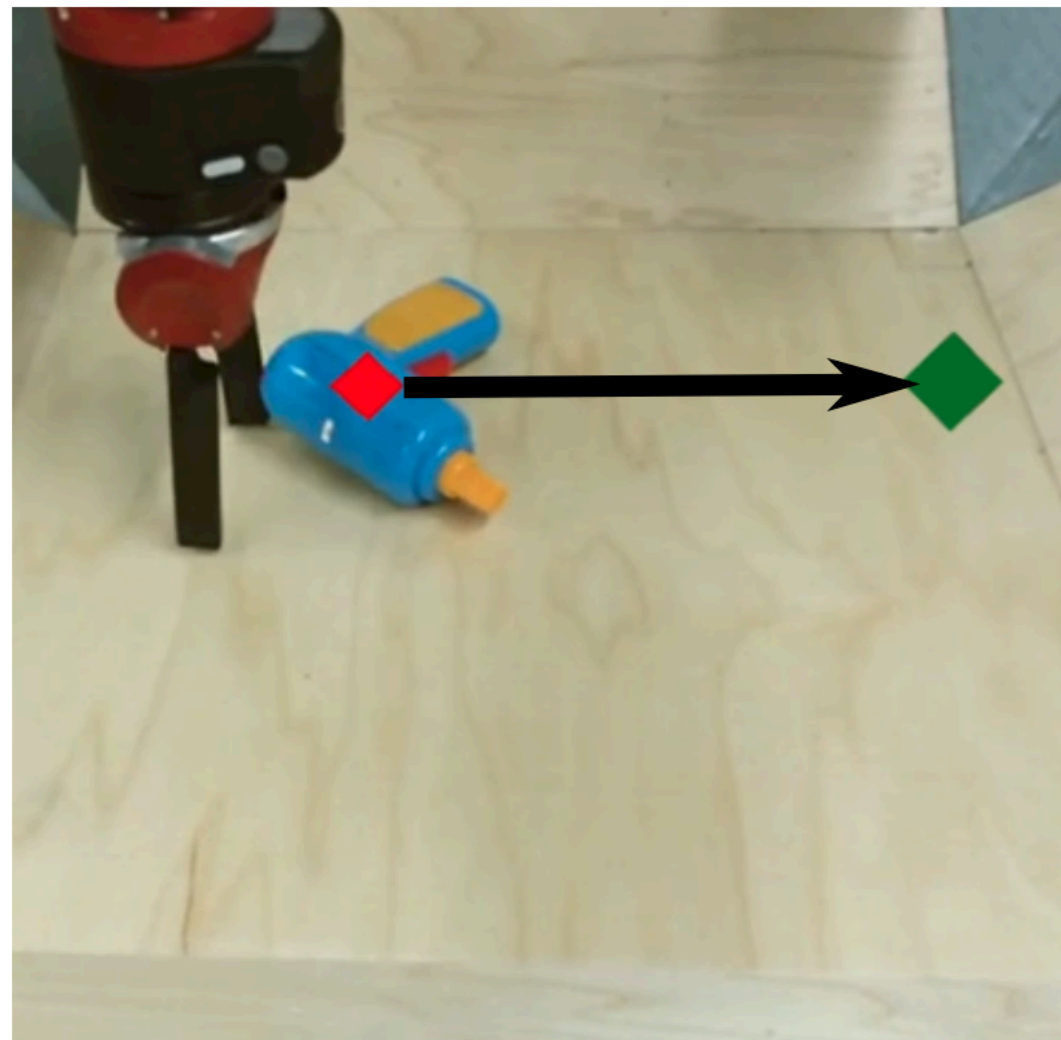


Model-based control

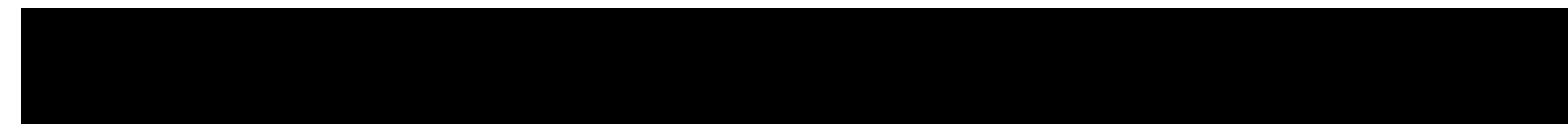
- Learn the **dynamics** of the environment: $p(s_{t+1} \mid s_t, a_t)$
- You can learn that through exploration, without an explicit reward.
- If states = images, we want to **predict the future** after you do an action

Model-based control

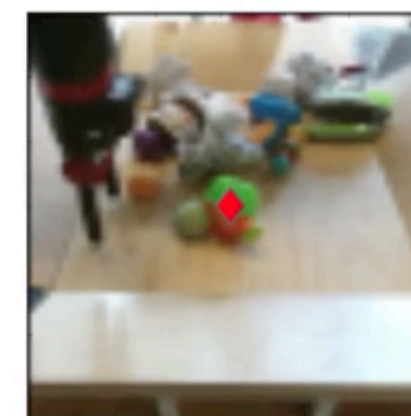
- Learn the **dynamics** of the environment: $p(s_{t+1} \mid s_t, a_t)$
- You can learn that through exploration, without an explicit reward.
- If states = images, we want to **predict the future** after you do an action



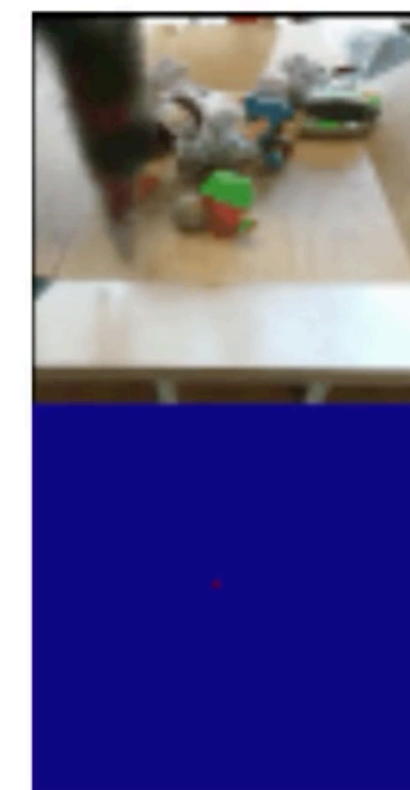
Pushing task



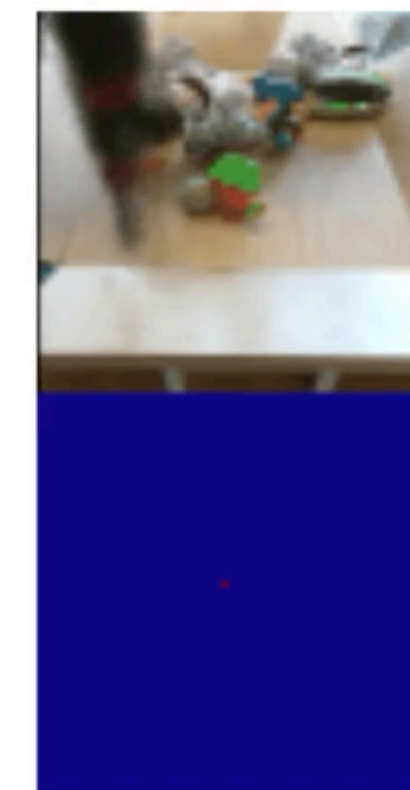
Occlusion Handling



Designated Pixel ♦



Finn et al.



SNA (Ours)



Video prediction

Image forensics

Image manipulation



From Forrest Gump, 1994

Malicious image manipulation



Malicious image manipulation



Malicious image manipulation

Fonda Speaks To Vietnam Veterans At Anti-War Rally



Actress And Anti-War Activist Jane Fonda Speaks to a crowd of Vietnam Veterans as Activist and former Vietnam Vet John Kerry (LEFT) listens and prepares to speak next concerning the war in Vietnam (AP Photo)



Malicious image manipulation



his associates simply found photos of athletes on the Internet and either used those photos or used software such as PhotoShop to insert the applicants' faces onto the bodies of legitimate athletes. For example, as set forth in greater detail below, CW-1 explained to McGLASHAN that he would create a falsified athletic profile for McGLASHAN's son, something he told McGLASHAN he had "already done ... a million times," and which would involve him using "Photoshop and stuff" to deceive university admissions officers.

FBI affidavit on college admissions scandal

Malicious image manipulation



Malicious image manipulation

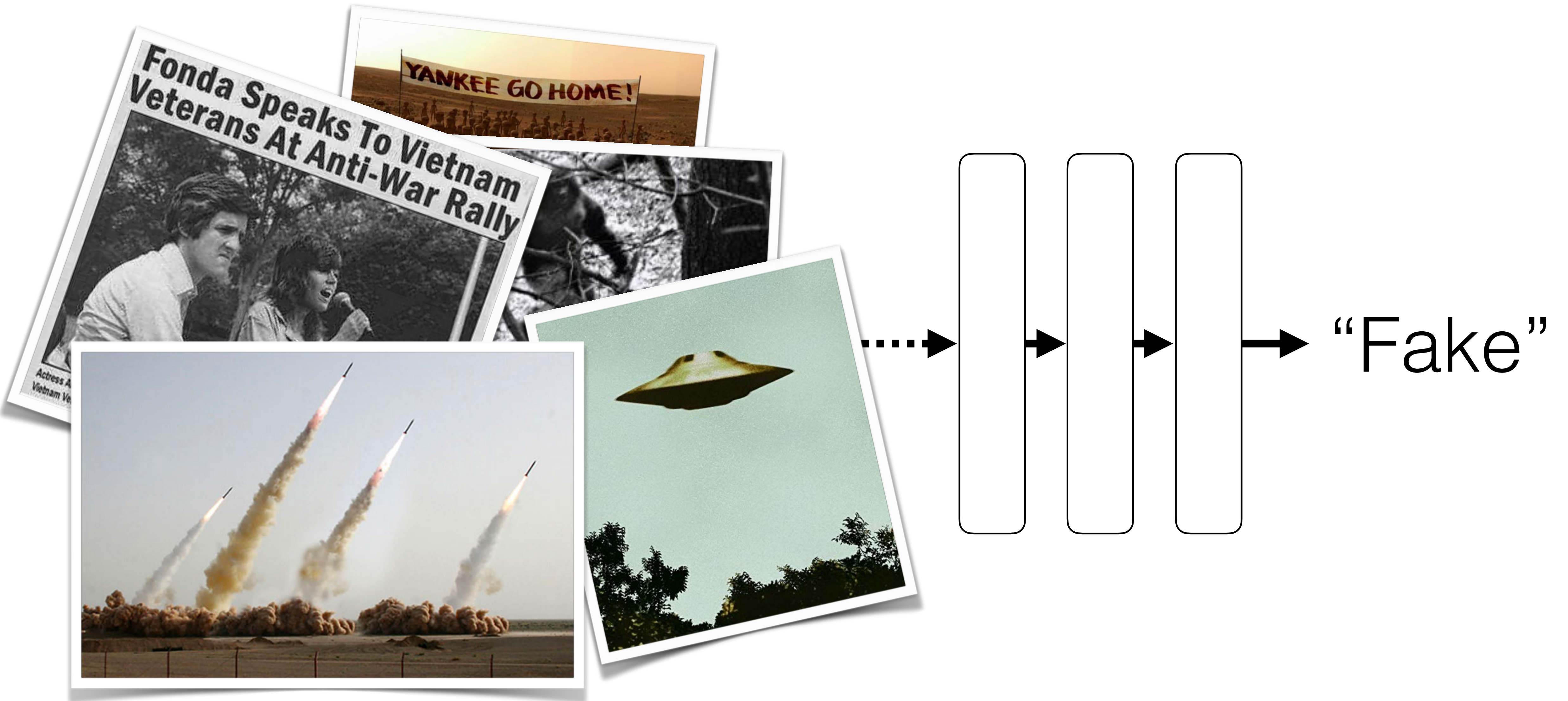


Image forensics: detecting fake images



Hany Farid

Hard to use supervised learning!



Strategy #1: use hard-to-fake physical cues

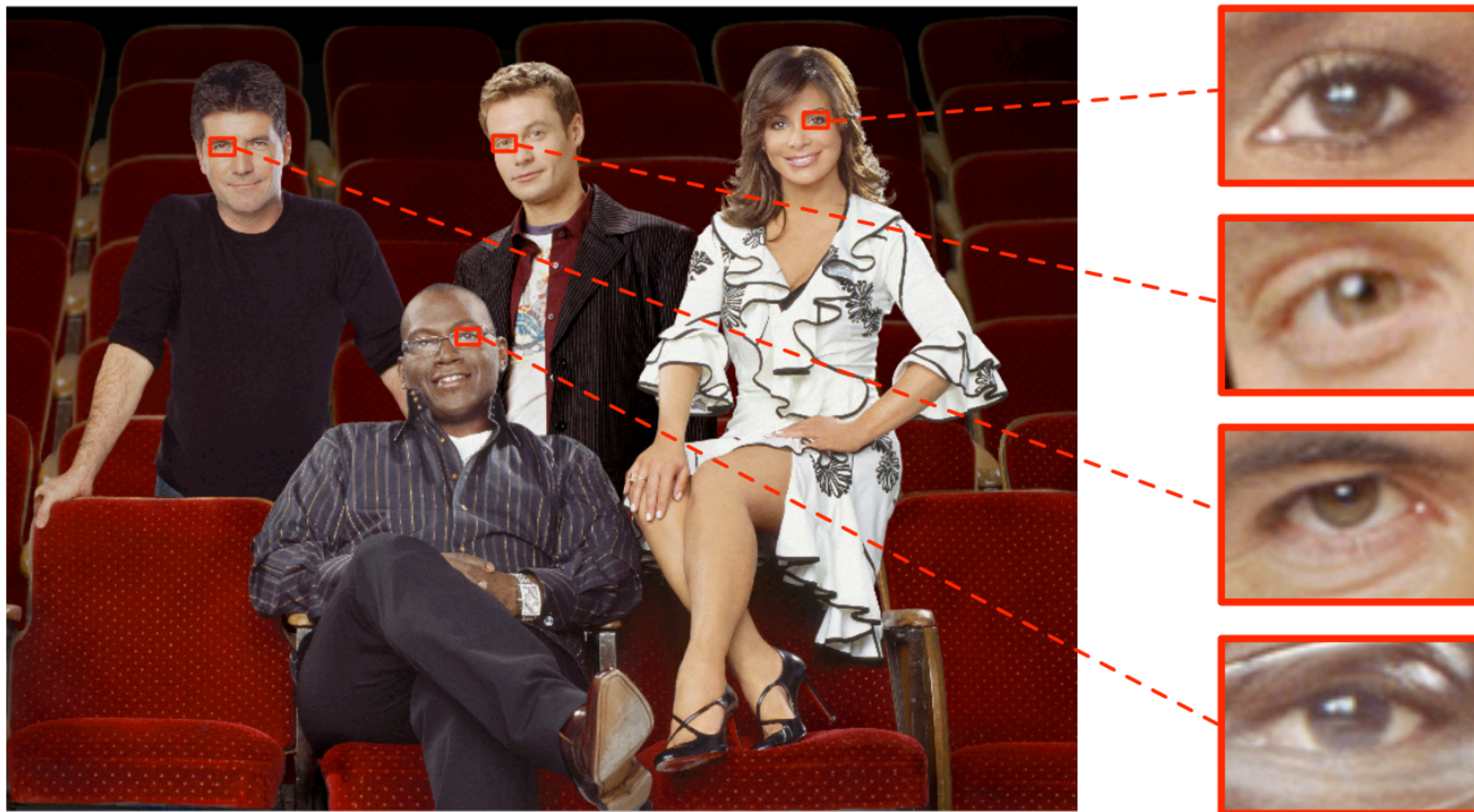
Real photo



Fake photo



Strategy #1: use hard-to-fake physical cues



[Johnson and Farid, 2007]

Strategy #2: subtle signals in imaging pipeline

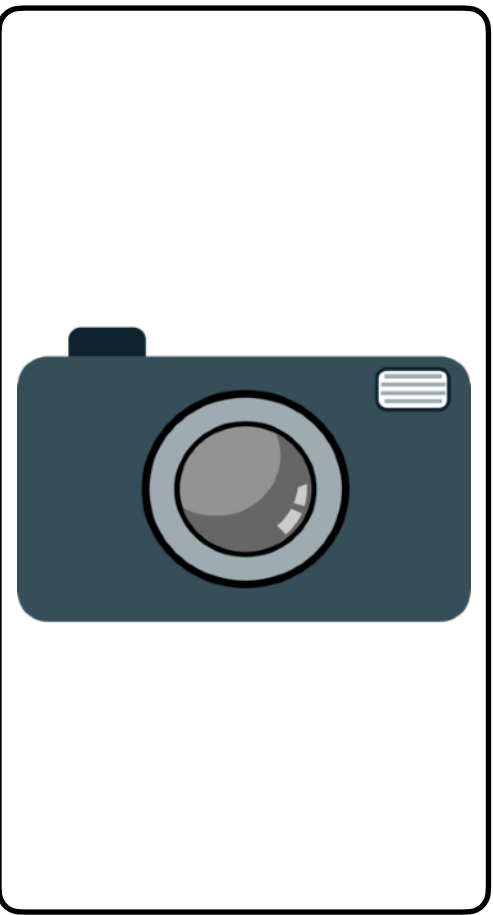
- Cameras compress images differently.
- During quantization, some do `round()`, others do `floor()` or `ceil()`
- Use knowledge of cameras to detect quantization type
- If a photo seems to have **both** kinds of quantization, it's probably a composite from different cameras!



Strategy #3: learned anomaly detection

- Instead of hand-crafting cues, can we learn to detect “anomalous” images, and flag suspicious images?







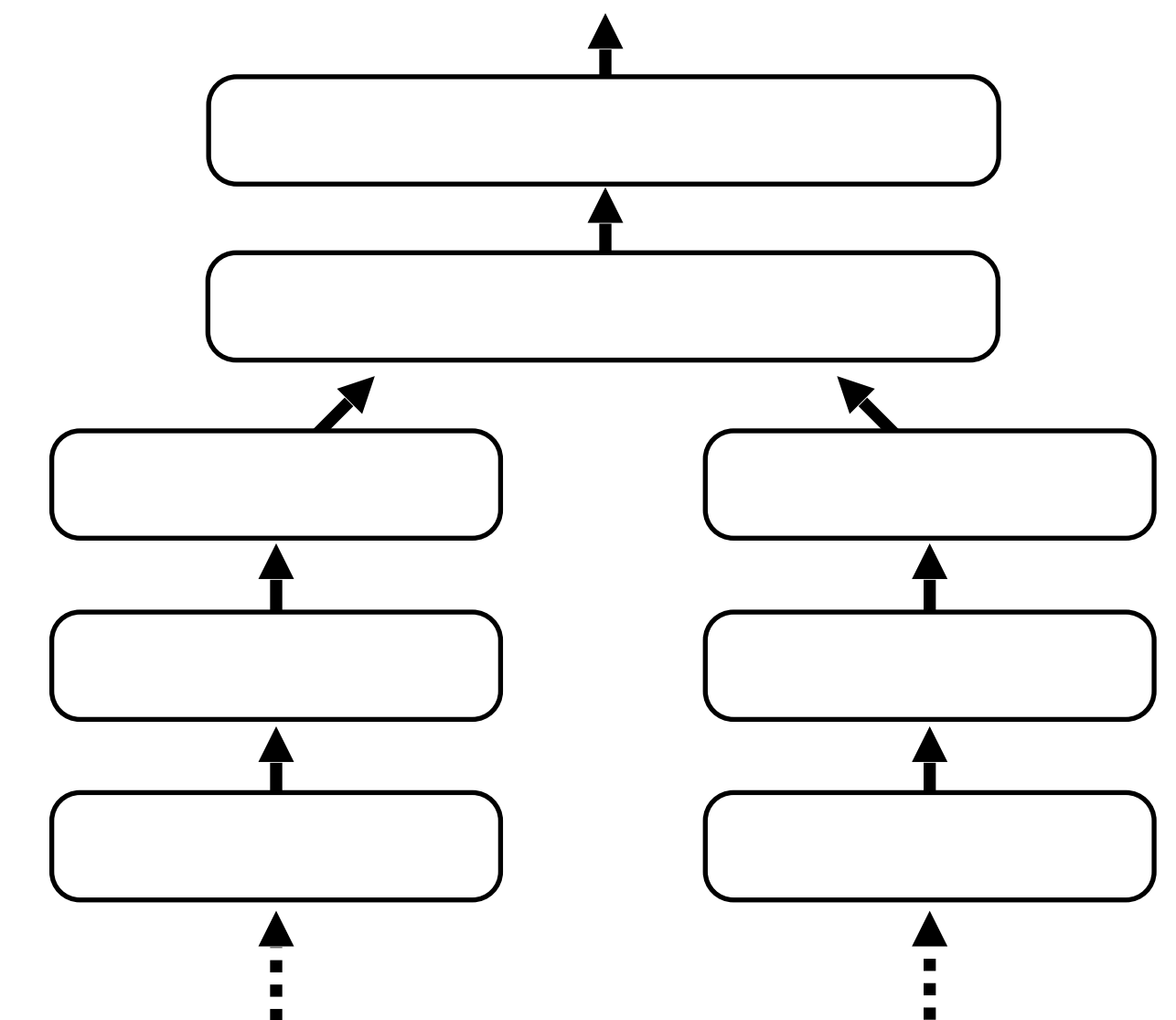
Inconsistent

Consistent

Predicting metadata consistency

Same camera model?

Different



CameraMake: Apple
CameraModel: iPhone 4s
ColorSpace: sRGB
ExifImageLength: 2448
ExifImageWidth: 3264
Flash: Flash did not fire
FocalLength: 107/2
WhiteBalance: Auto
ExposureTime: 1/2208
...



CameraMake: NIKON CORPORATION
CameraModel: NIKON D90
ColorSpace: sRGB
ExifImageLength: 2848
ExifImageWidth: 4288
Flash: Flash did not fire
FocalLength: 18/796
WhiteBalance: Auto
ExposureTime: 1/30
...

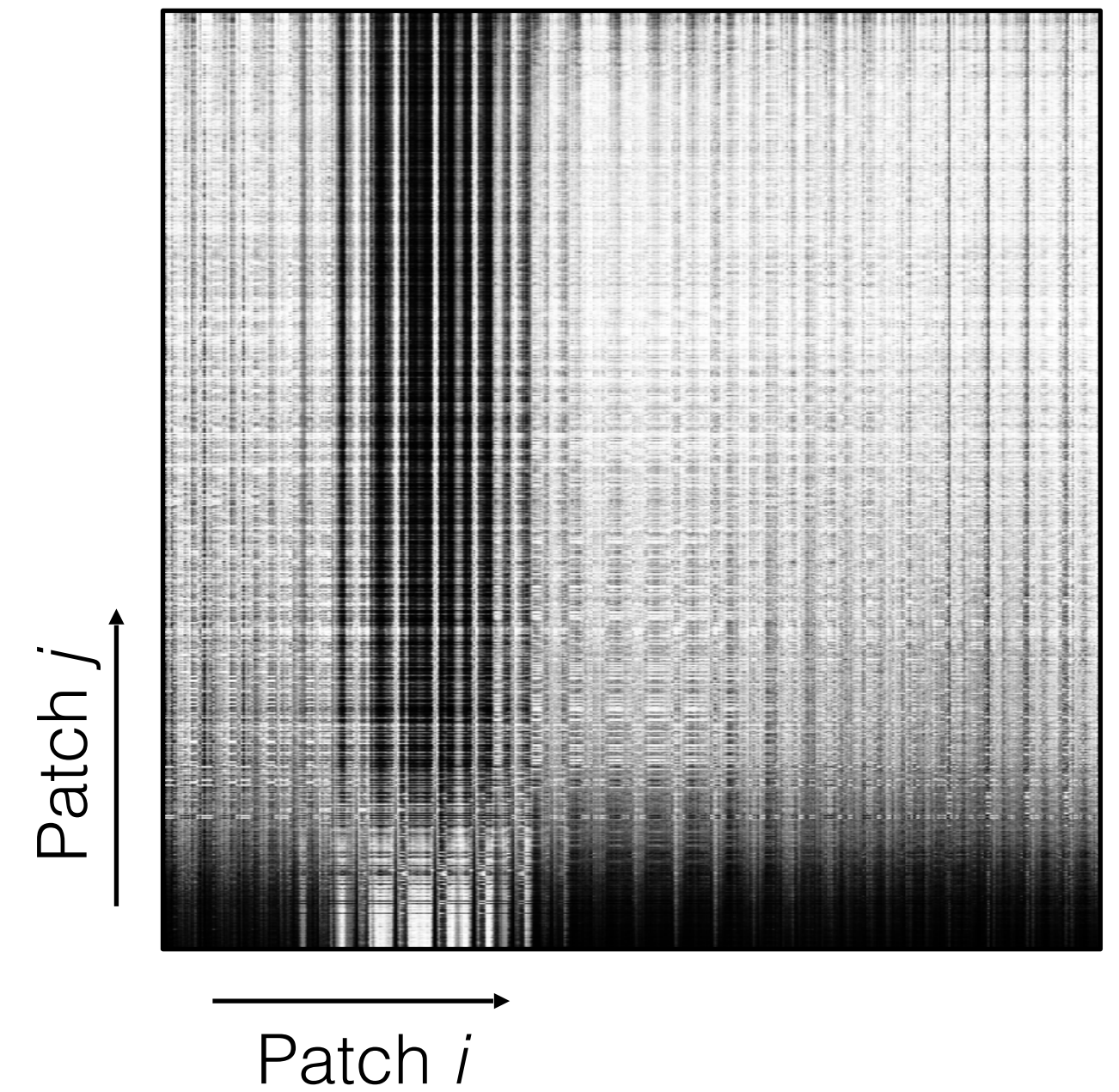
Photo source:
[reddit.com/user/jjrosado](https://www.reddit.com/user/jjrosado)



Photo source:
[reddit.com/user/jjrosado](https://www.reddit.com/user/jjrosado)



Affinity matrix



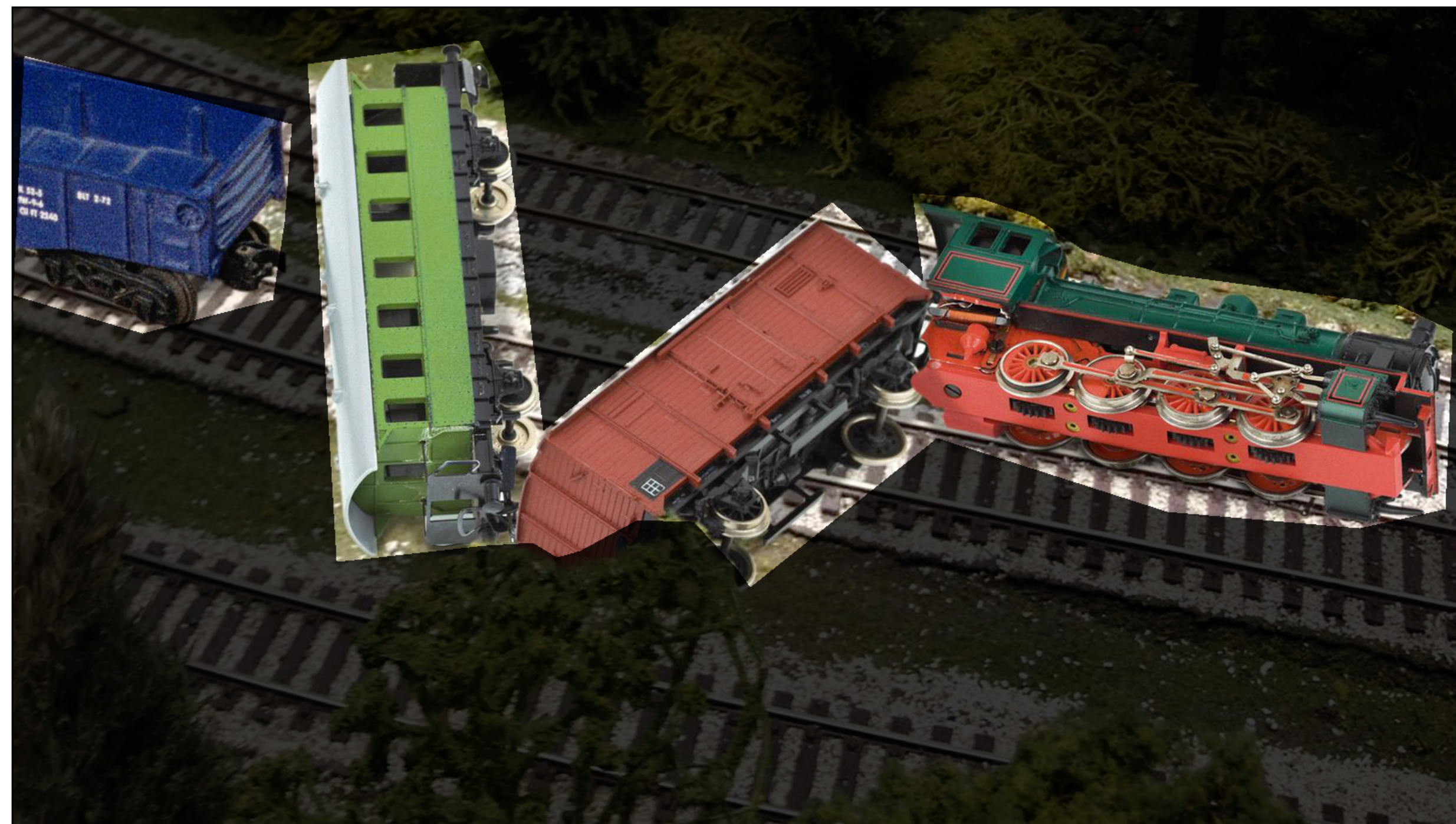


Input

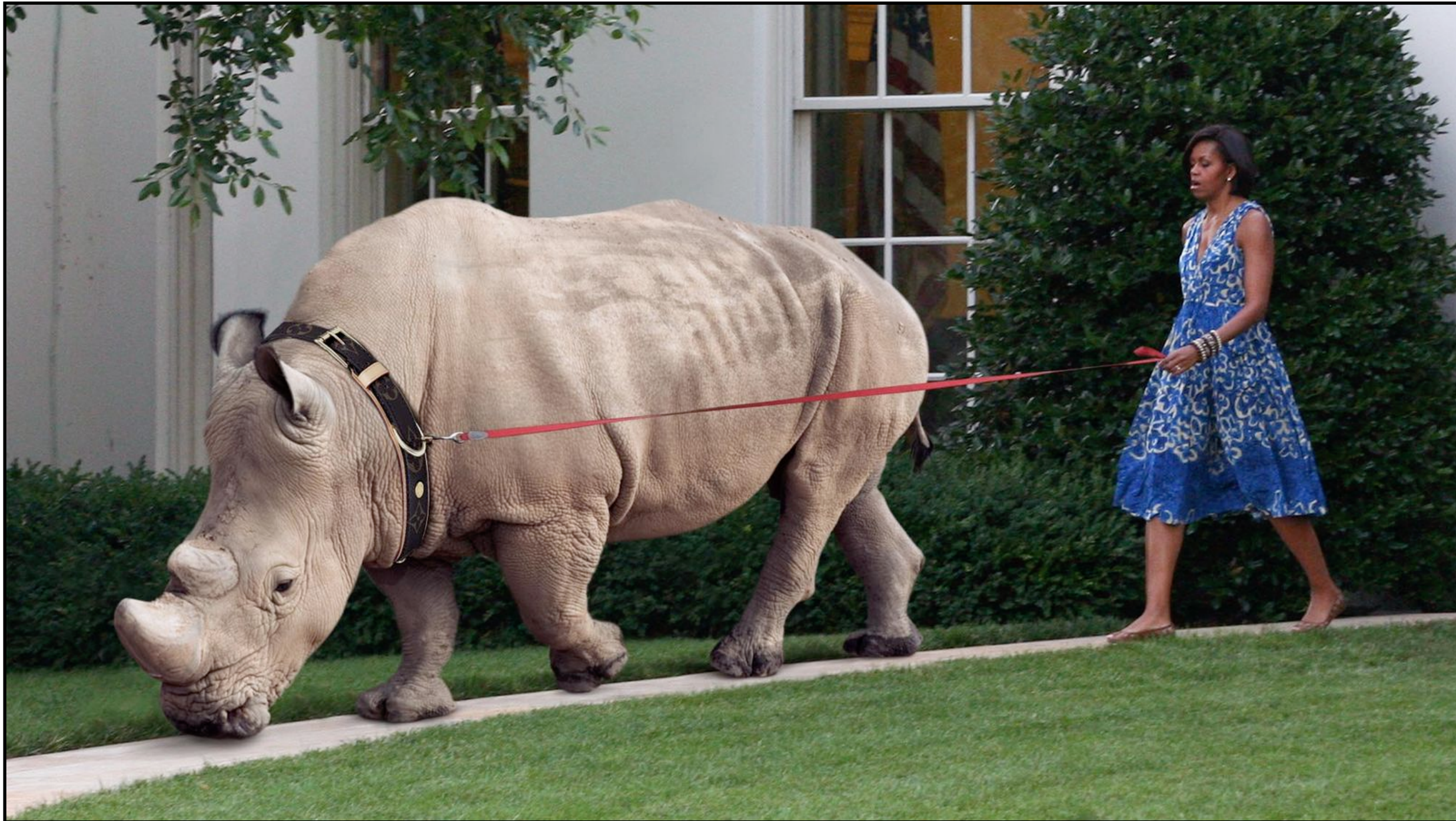
Photo source: TheOnion.com



Prediction

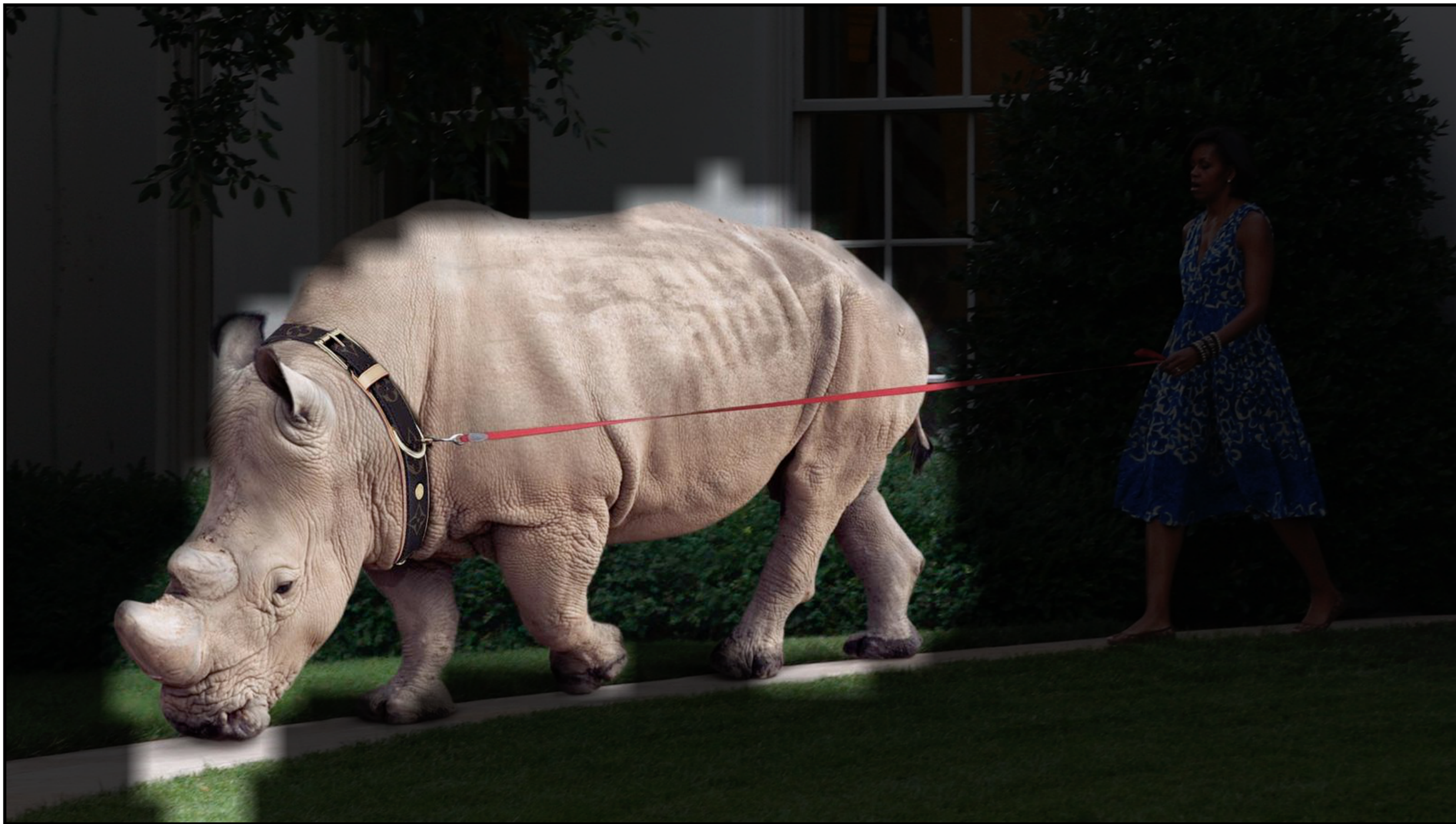


Ground truth

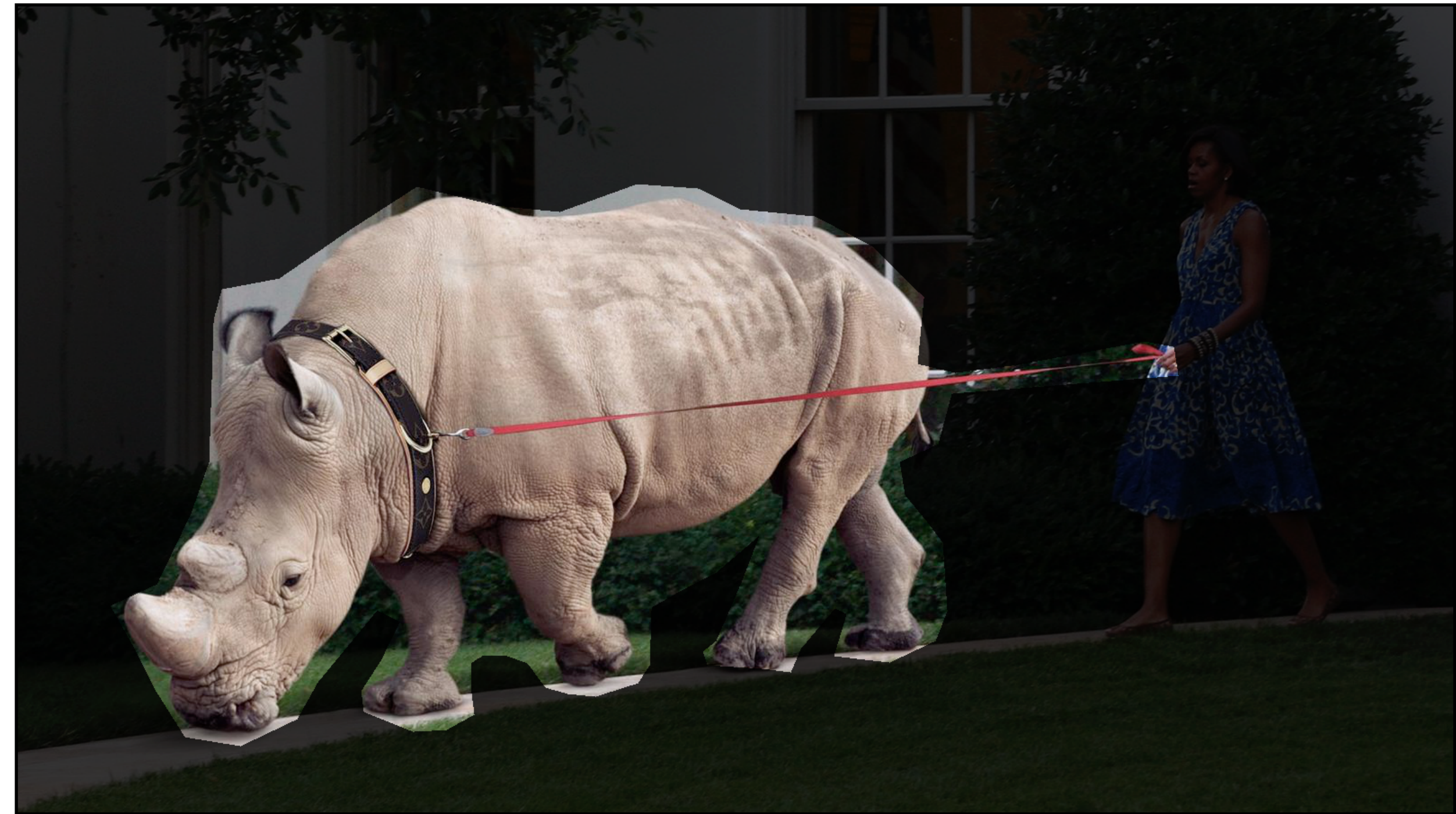


Input

Photo source: TheOnion.com



Prediction

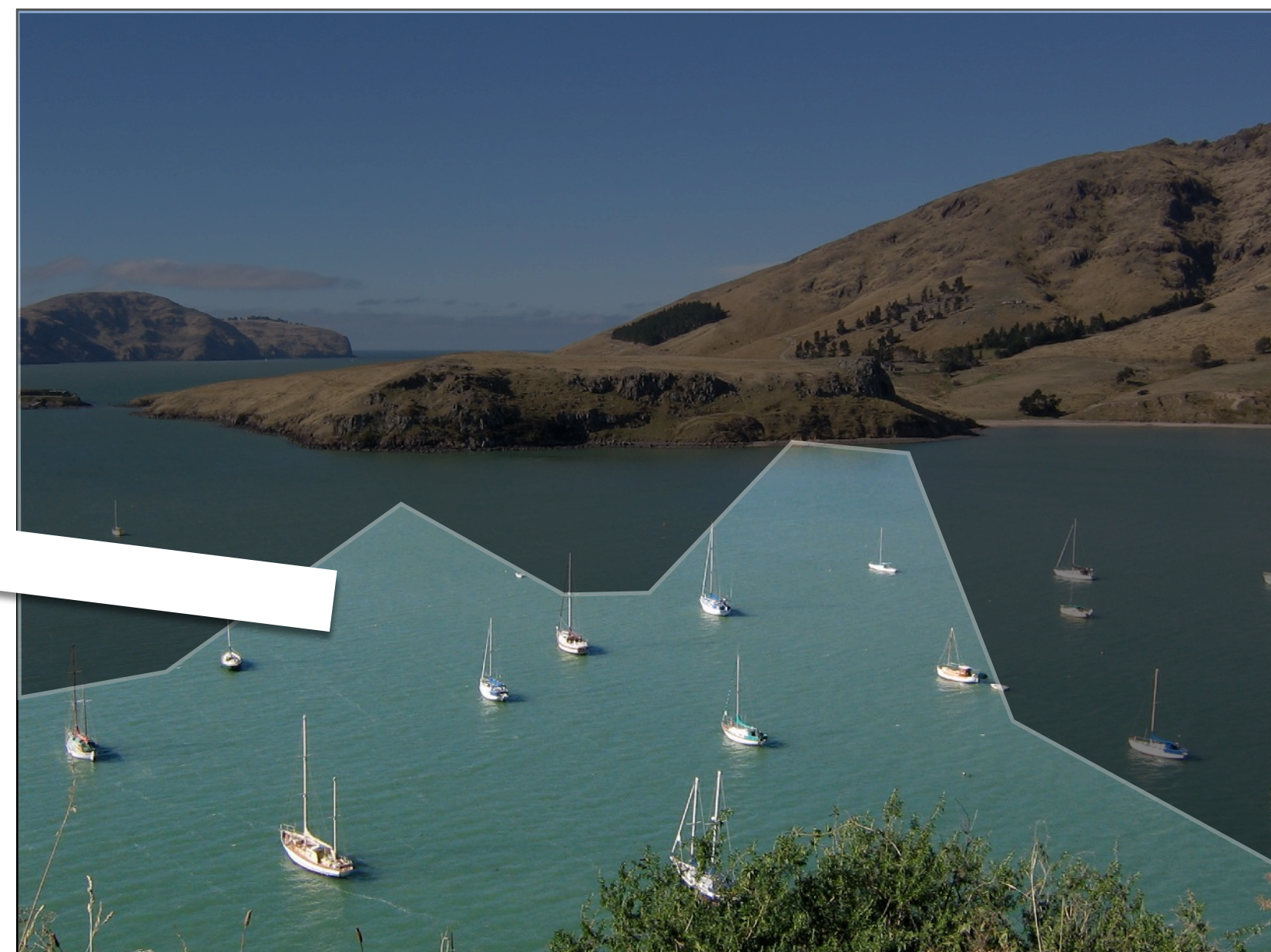


Ground truth

Photo source: TheOnion.com



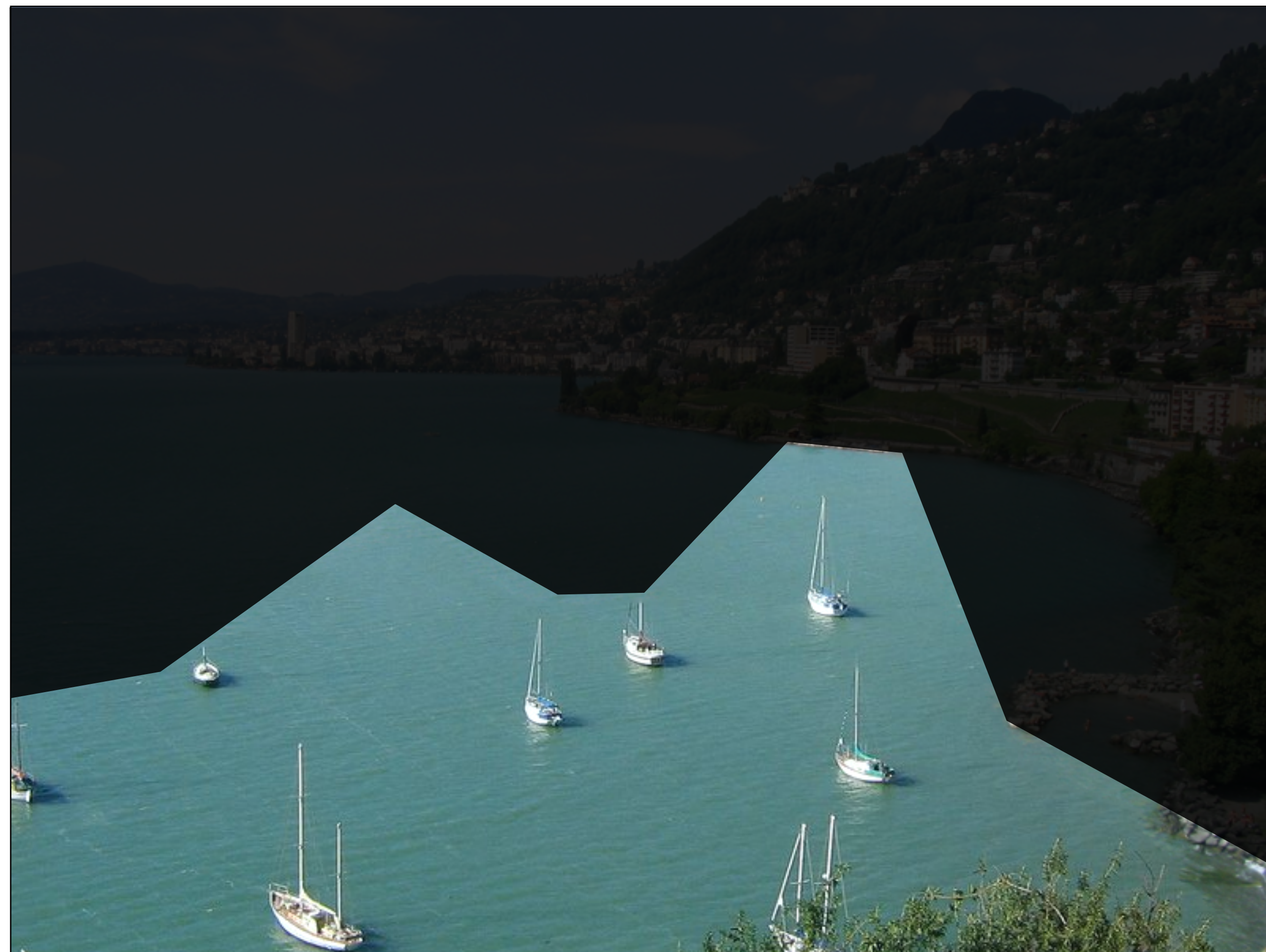
Input



(Hays & Efros 2009)



Prediction



Ground truth

Strategy #4: supervised learning

- Malicious image editors often use the same tools, e.g. Photoshop
- Can we “overfit” to these tools and detect them well?





Make random fakes by scripting Photoshop.

```
def make_random_fakes():  
    detect and crop face;  
    open Photoshop;  
    open Face-Aware Liquify;  
    move mouth keypoint 1;  
    ...  
    save(warped image);
```



Manipulated Photo



Warp Prediction



Suggested “Undo”



Original Photo



Suggested “Undo”



Manipulated Photo

New challenges on the horizon

Celeb-DF: A New Dataset for DeepFake Forensics

Yuezun Li¹, Xin Yang¹, Pu Sun², Honggang Qi² and Siwei Lyu¹

¹University at Albany, State University of New York, USA

²University of Chinese Academy of Sciences, China

“Deepfakes”

New challenges on the horizon

- Any internet troll can make a fake video!
- They don't look *that* convincing yet, but of course quickly improving!
- Supervised learning methods can detect “known” deepfake algorithms
- But what about methods we've never seen before?
- Getting harder to tell what's real vs. fake

What's real and what's fake?



[“The suspicious video that helped spark an attempted coup in Gabon” Washington Post. 2020]

<https://www.youtube.com/watch?v=F5vzKs4z1dc>

What's real and what's fake?



["The suspicious video that helped spark an attempted coup in Gabon" Washington Post. 2020]

What's real and what's fake?



[“The suspicious video that helped spark an attempted coup in Gabon” Washington Post. 2020]

Next class: ethics in computer vision (part 2)