Finding and Fixing Bugs in Liquid Haskell

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Overview

- Motivation
- Liquid Haskell
- Fault Localization
- Fault Localization Evaluation
- Predicate Discovery
- Predicate Discovery Evaluation
- Conclusion

Motivation: Bugs are Bad

Bugs are Bad

- Bugs are Expensive
 - Modifying code, correcting defects, and evolving code account for as much as 90% of the total cost of software projects.



Bugs are Bad

WIRED

- Bugs are Expensive
- Bugs are Dangerous

Science : DISCOVERIES S Sunk by Windows NT

GEAR SCIENCE ENTERTAINMENT

07.24.98

While Microsoft continues to trumpet the success of its NT op systems, the US Navy is having second thoughts about putting



Programming Languages to the Rescue!



George Orwell (1984)

"We shall make thoughtcrime literally impossible, because there will be no words to express it."

Presence of bugs ...is half the problem

Verification, Model Checking, and Type Systems

We can check the correctness of programs against formal specifications, which is information we can encode in Liquid Haskell type signatures.

- We still have to *find* the bug after we know it exists
- What about missing parts of the specification?

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A **fault localization** algorithm searches for a minimal unsatisfiable constraint set, whose constraints map to likely locations of the bug in the implementation.

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A **fault localization** algorithm searches for a minimal unsatisfiable constraint set, whose constraints map to likely locations of the bug in the implementation.

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A **predicate discovery** algorithm uses *disjunctive interpolation* to automatically expand the abstract domain by inferring predicate templates that serve as the refinement types of program expressions.

Liquid Haskell

Well-typed (Haskell) programs can go very wrong!

Divide-by-zero

Keys missing in Maps

Pattern-match failures

Non-termination

Functional Correctness / Assertions...

Solution:

Refinement Types

Simple Refinement Types

Refinement Types = Types + Predicates

Refinement Types

Types Refinements

b := Int | Bool | ... -- primitives t := {x:b | p} -- refined base | a, b, c -- variables | x:t -> t -- refined function

Predicates

Quantifier-Free Logic of Uninterpreted Functions & Linear Arithmetic

Uninterpreted Functions

$$\forall \overline{x}, \overline{y}. \ \overline{x} = \overline{y} \ \Rightarrow \ f(x) = f(y)$$

Predicates

Quantifier-Free Logic of Uninterpreted Functions & Linear Arithmetic

Given a Verification Condition (VC)

$$p_1 \Rightarrow p_2$$

SMT solvers can decide if VC is Valid ("always true")

An Example

1 sums :: k:Int -> { v:Int | k <= v } 2 sums 0 = 0 3 sums k = k + (sum (k-1))</pre>

```
0 \le v, k \le v
```

1 sum :: k:Int -> { v:Int | k <= v }
2 sum = go
3 where
4 go k
5 | k <= 0 = 0
6 | otherwise = let s = go (k-1) in s + k</pre>

 $0 \le v, k \le v$

4 5	90 K k <= 0	= (0					
4	go k							
3	where							
2	sum = go							
1	<pre>sum :: k:Int -> {</pre>	v:	Int	k	<=	v }		

Instantiate every element with a conjunction of the abstract domain

$$\begin{split} \mathsf{k}:\kappa_k,\mathsf{k} \leq 0 \vdash \{\nu=0\} <:\kappa_s\\ \mathsf{k}:\kappa_k, \neg(\mathsf{k} \leq 0), \mathsf{s}:\kappa_s[\mathsf{k}/\mathsf{k}-1] \vdash \{\nu=\mathsf{s}+\mathsf{k}\} <:\kappa_s\\ \emptyset \vdash \texttt{Int} <:\kappa_k\\ \mathsf{k}:\kappa_k \vdash \kappa_s <:\{\nu\geq\mathsf{k}\} \end{split}$$

```
0 \le v, k \le v
```

1 sum :: k:Int -> { v:Int | $k \le v$ } $\mathbf{2}$ sum = qo3 where 4 qo k | k <= 0 = 0 5 6 | otherwise = let s = go (k-1) in s + k $k: \kappa_k, k \le 0 \vdash \{\nu = 0\} <: \kappa_s$ $k: \kappa_k, \neg (k \le 0), s: \kappa_s[k/k - 1] \vdash \{\nu = s + k\} <: \kappa_s$ $\emptyset \vdash \text{Int} <: \kappa_k$ $\mathbf{k}: \kappa_k \vdash \kappa_s <: \{\nu \geq \mathbf{k}\}$

k	0 ≤ v	k ≤ v		
S	0 ≤ v	k ≤ v		

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Fault Localization

Fault Localization Overview



Constraint Minimization












What if neither half fails?

































Fault Localization Evaluation

Fault Localization Accuracy

- Every location reported by the algorithm that is in the ground truth set is a true positive.
- Every location reported by the algorithm that is not is a false positive.

• We measure false positives relative to some tolerance level n: if an algorithm returns fewer than n spurious bug locations for a file, then the algorithm is not counted as having a false positive for that file.

Fault Localization Accuracy

			False	False	False
		True	Positives	Positives	Positives
	Ground Truth	Positives	(t=0)	(t=1)	(t=2)
minimizeWCC	seeded	18	25	14	9
Vanilla	seeded	8	20	7	1
minimizeWCC	expert	21	24	13	9
Vanilla	expert	10	19	6	1

Fault Localization Efficiency

Algorithm	Min Time	Max Time	Avg Time
minimizeWCC	$0.004\mathrm{s}$	$43.64\mathrm{s}$	$3.73~\mathrm{s}$

Runtimes do not necessarily correlate with program sizes: processed the largest benchmark, red black trees, at around 6 seconds.

These numbers indicate reasonable scaling for larger programs: the time taken relates to the relevant partitions of the constraint graph, not the program overall.

Predicate Discovery

Craig's Interpolation Theorem

- If A, B mutually inconsistent, i.e., A \land B is unsatisfiable
- Exists an interpolant, I
- such that $\models A \rightarrow I$ and that I and B are mutually inconsistent
- where $atoms(I) \subseteq atoms(A) \cap atoms(B)$.

Disjunctive Interpolation

- If A, B mutually inconsistent, i.e., A \land B is unsatisfiable
- Exists an interpolant, I
- such that $\models A \rightarrow I$ and that I and B are mutually inconsistent
- where $atoms(I) \subseteq atoms(A) \cap atoms(B)$.

Rummer et al. generalize:

- Instead of pairs of formulas, one unsatisfiable formula
- Any number of labelled subformulas

Predicate Discovery Overview



Triangular numbers, again

- 1 sum :: k:Int -> { v:Int | k <= v }
- $2 \quad sum = go$
- 3 where
- 4 go k

5 | $k \le 0 = 0$ 6 | **otherwise** = **let** s = go (k-1) **in** s + k

Constraints

Constraint Generation

 $\mathbf{2}$

sum =

$$k: \kappa_k, k \leq 0 \vdash \{\nu = 0\} <: \kappa_s$$

$$k: \kappa_k, \neg (k \leq 0), s: \kappa_s [k/k - 1] \vdash \{\nu = s + k\} <: \kappa_s$$

$$\emptyset \vdash \text{Int} <: \kappa_k$$
sum = go
$$k: \kappa_k \vdash \kappa_s <: \{\nu \geq k\}$$
where
$$go k$$

$$k < 0 = 0$$

$$b \text{ otherwise = let } s = go (k-1) \text{ in } s + k$$

Horn Constraints $k: \kappa_k, k \leq 0 \vdash \{\nu = 0\} <: \kappa_s$

 $\mathbf{k}: \kappa_k, \neg (\mathbf{k} \le 0), \mathbf{s}: \kappa_s[\mathbf{k}/\mathbf{k} - 1] \vdash \{\nu = \mathbf{s} + \mathbf{k}\} <: \kappa_s$

 $\emptyset \vdash \text{Int} <: \kappa_k$

 $\mathbf{k}: \kappa_k \vdash \kappa_s <: \{\nu \ge \mathbf{k}\}$

 $\kappa_k(k) \wedge \mathbf{k} \le 0 \wedge \nu = 0 \to \kappa_s(\nu)$ $\kappa_k(k) \wedge \mathbf{k} > 0 \wedge \kappa_s(\mathbf{s})[\mathbf{k}/\mathbf{k} - 1] \wedge \nu = \mathbf{s} + \mathbf{k} \to \kappa_s(\nu)$

 $true \to \kappa_k(\nu)$

 $\kappa_s(\nu) \to \nu \ge \mathbf{k}$

$$\kappa_k(k) \wedge k \leq 0 \wedge \nu = 0 \rightarrow \kappa_s(\nu)$$

Horn Constraints
$$\kappa_k(k) \wedge k > 0 \wedge \kappa_s(s)[k/k-1] \wedge \nu = s + k \rightarrow \kappa_s(\nu)$$

 $true \to \kappa_k(\nu)$

 $\kappa_s(\nu) \to \nu \ge \mathbf{k}$



 $\nu \geq \mathbf{k}$

$$\kappa_k(k) \wedge k \leq 0 \wedge \nu = 0 \rightarrow \kappa_s(\nu)$$

Horn Constraints
$$\kappa_k(k) \wedge k > 0 \wedge \kappa_s(s)[k/k-1] \wedge \nu = s + k \rightarrow \kappa_s(\nu)$$

 $true \to \kappa_k(\nu)$

 $\kappa_s(\nu) \to \nu \ge \mathbf{k}$

$$u < \mathrm{k}$$
 = ¬ ($\nu \geq \mathrm{k}$)



Unrolling Constraints

Unrolling Constraints

 $\nu < \mathbf{k}$


Unrolling Constraints $\nu < k$





Unrolling Constraints $\nu < k$



Interpolation



 $\nu < k$





Interpolation $\nu < k$ $I(L_1) = \nu \ge k \land k \le 0$ $\overline{L_1}$ $I(L_2) = s \ge k - 1$ $\mathbf{k} \leq \mathbf{0} \wedge \nu = \mathbf{0}$ $\mathbf{k} > \mathbf{0} \wedge \nu = \mathbf{s} + \mathbf{k}$ $I(L_3) = s' = 0$ $\overline{L_2}$ k - 1 > 0 $k - 1 \le 0$ $\wedge s = 0 \qquad \wedge s = s' + (k - 1)$ $\overline{L_3}$ $(k-1) - 1 \le 0 \land s' = 0$

Predicate Discovery Evaluation

Predicate Discovery on k-bounded Programs

- Considered 21 microbenchmarks.
- All 21 successful
 - including instances where Liquid Haskell alone would not have been able to verify the program.
- Median runtime of 0.1 seconds and a maximum of 7.1 seconds.

Predicate Discovery in General

• 23 microbenchmarks

- programs that were not k-bounded for any
- programs that were k-bounded, but for which we only permitted our algorithm i < k unrolling
- Unroll depth of 2
- In 22 of 23 cases, enough predicates to prove correctness
- The one failing case involved a constraint that was not k-bounded for any k in an implementation of merge sort; in this case the domain expansion was missing only one qualifier (out of ~100).
- Our algorithm took a median of 0.1 seconds and a maximum of 7.2 seconds.

Conclusion

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Our fault localization algorithm produces minimal false positives (almost half of which are a single spurious location) and is efficient enough to be used at compiletime. It is much more effective at fault localization than the Liquid Haskell type checker, localizing twice as many bugs overall and finding six times more "hard" bugs than the type checker.

Our predicate discovery algorithm is correct by construction on k-bounded instances, finding annotations that admit program verification. Together, our two algorithms significantly reduce the barrier to entry for using refinement types systems. **Questions?**

Extra Slides

Key Insights

- 1. A bug captured at the type checking level can be seen as an inconsistency.
- 2. The locations reported to the user should be minimal to prevent implicating spurious program locations as faults.
- 3. Minimal explanations implicate relevant locations.

Central Insight



Related Work

The SEMINAL tool by Lerner et al. [20] uses the OCaml type checker as an oracle in a search procedure to find well-typed programs that are syntactically similar to an input program that fails to type check, which are then used to construct helpful error messages. Our fault localization algorithm likewise uses the type checker as an oracle, but works on the set of constraints generated from the input program instead. Since the space of constraints is much smaller than the space of possible edits for a program, our algorithm can be more efficient than the SEMINAL tool without sacrificing the ability to find bugs.

Pavlinovic et al. [24] reduce fault localization into an instance of the MaxSAT problem by generating a set of assertions from the input program that are weighted by a ranking measure provided by the compiler. An SMT solver is used to find a minimum set of error clauses that can be mapped back to possible bug locations.

Thesis

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Predicates

Quantifier-Free Logic of Uninterpreted Functions & Linear Arithmetic

- -- variables
- -- constants
- -- arithmetic
- -- uninterpreted function

Find the bug

This code doesn't compile. At a glance, can you find why?

(actual code written by a student)
1 randomElt :: Vector a -> Rand StdGen (Maybe a)
2 randomElt vector = case (V.length vector) of
3 0 -> liftM (_ -> Nothing) (getRandom)
4 1 -> liftM (vector !?) (getRandomR (0,(1-1)))

Find the "bug"

This code doesn't compile. At a glance, can you find why?

(actual code written by a student)
1 randomElt :: Vector a -> Rand StdGen (Maybe a)
2 randomElt vector = case (V.length vector) of
3 0 -> liftM (_ -> Nothing) (getRandom :: Int)
4 1 -> liftM (vector !?) (getRandomR (0,(1-1)))