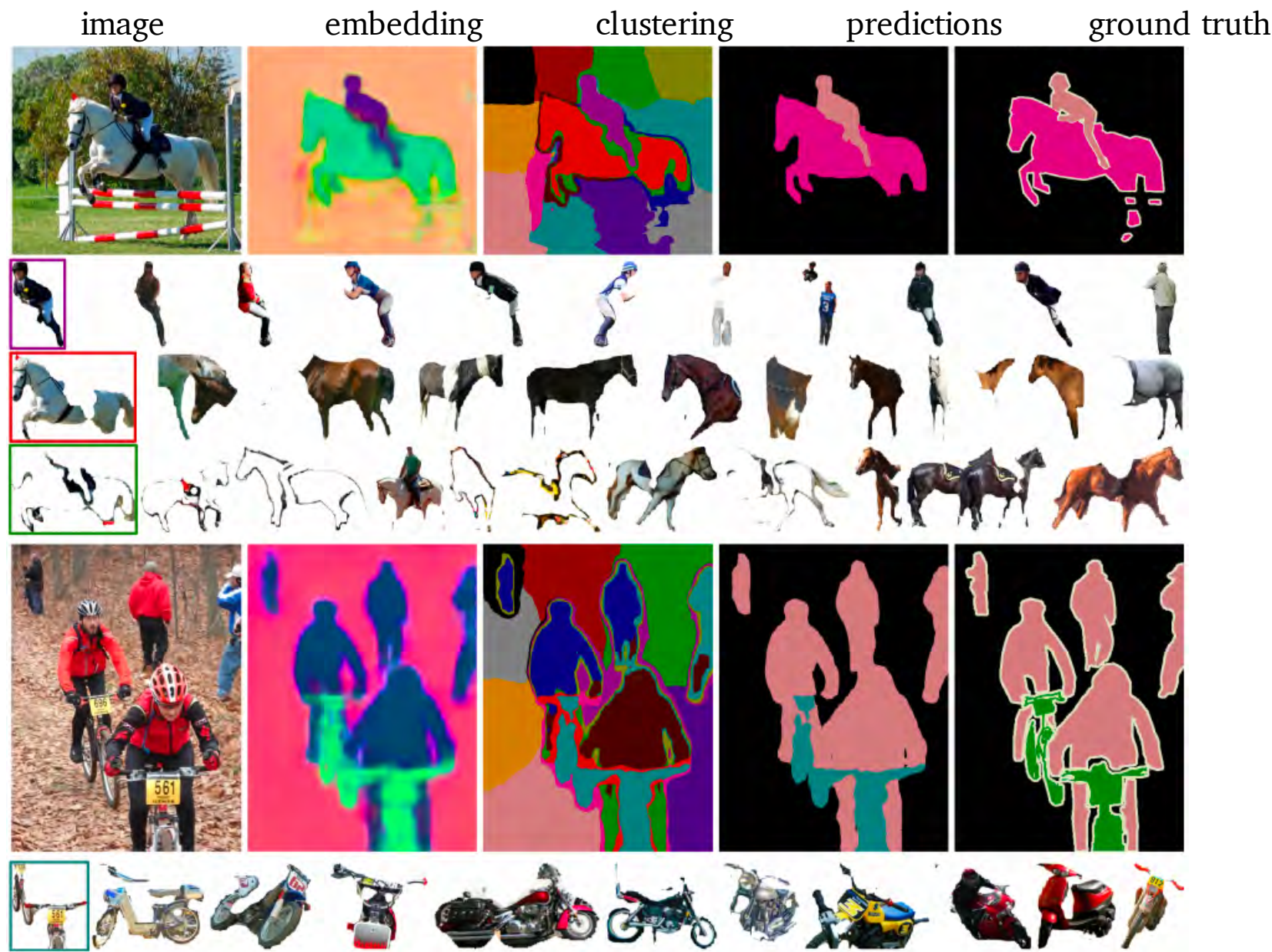
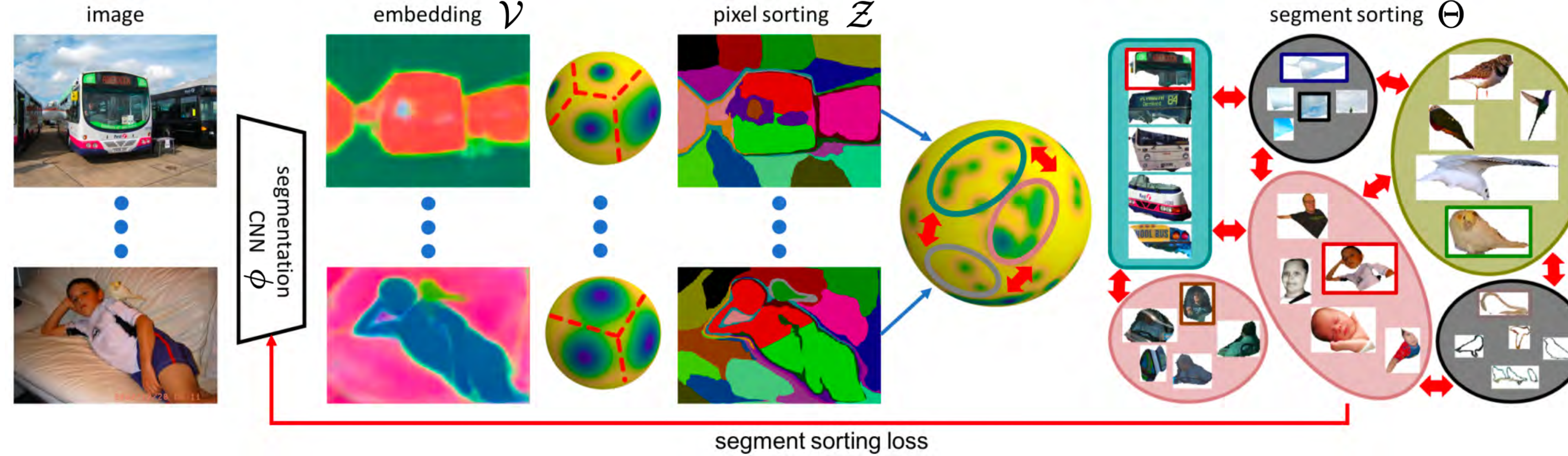


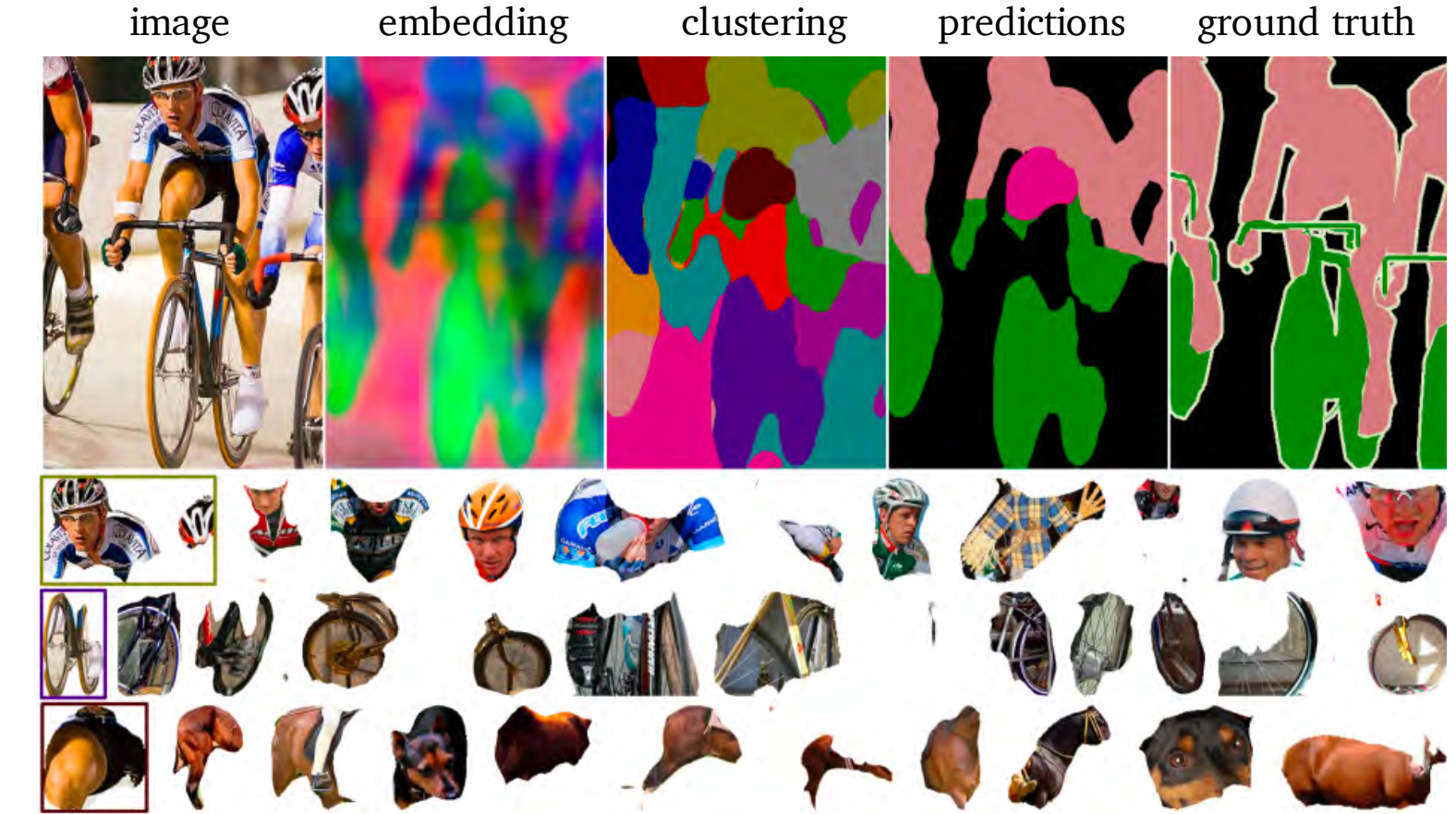
Supervised Segmentation



SegSort: Unified Metric Learning Framework for Segmentation



Unsupervised Segmentation



- Basic idea: Assuming independent normal distributions for individual segments, we seek a maximum likelihood estimation of the feature mapping \mathcal{V} , so that the feature induced partitioning \mathcal{Z} in the image and Θ clustering across images provide maximum discrimination among segments.

- von-Mises Fisher distribution: $f(\mathbf{v} | \boldsymbol{\mu}, \kappa) = C_d(\kappa) \exp(\kappa \boldsymbol{\mu}^\top \mathbf{v})$

- Single MLE objective: $\min_{\phi, \mathcal{Z}, \Theta} -\log P(\mathcal{V}, \mathcal{Z} | \Theta) = \min_{\phi, \mathcal{Z}, \Theta} -\sum_i \log f_{z_i}(\mathbf{v}_i | \theta_{z_i})$

- Optimize in a two-stage EM: $[\mathcal{Z} \leftrightarrow \Theta] \leftrightarrow \mathcal{V}$

Pixel Sorting: Partition Each Image

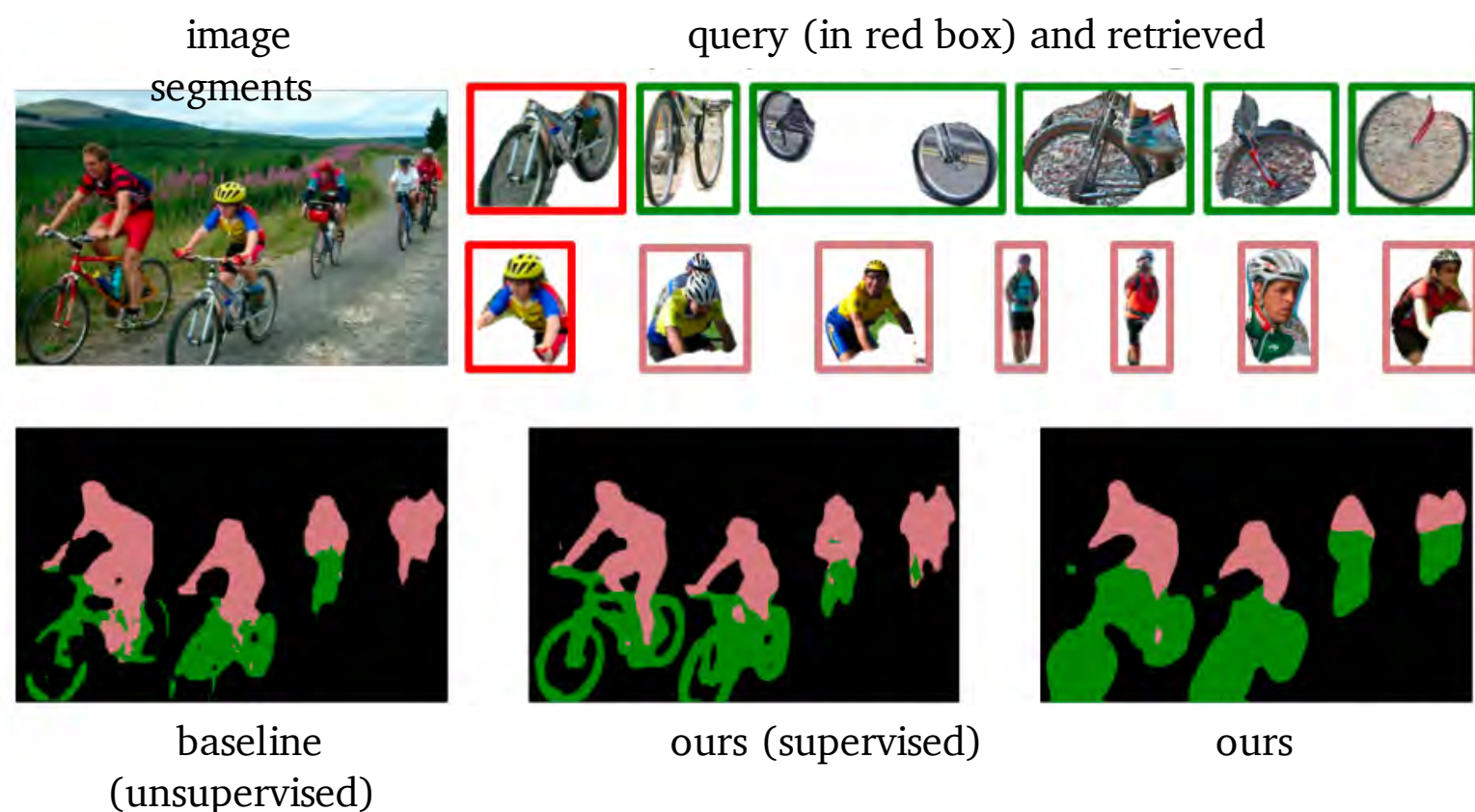
- EM for K-mean clustering based on \mathcal{V} for each image
- Update \mathcal{Z} : $p(z_i = s | \mathbf{v}_i, \Theta) = \frac{f_s(\mathbf{v}_i | \Theta)}{\sum_{l=1}^k f_l(\mathbf{v}_i | \Theta)}$
- Update Θ : $\hat{\boldsymbol{\mu}}_c = \frac{\sum_i \mathbf{v}_i p(z_i = c | \mathbf{v}_i, \Theta)}{\|\sum_i \mathbf{v}_i p(z_i = c | \mathbf{v}_i, \Theta)\|} = \frac{\sum_{i \in \mathcal{R}_c} \mathbf{v}_i}{\|\sum_{i \in \mathcal{R}_c} \mathbf{v}_i\|}$
- Alternative for unsupervised semantic segmentation:



Segment Sorting: Organize All Segments

- Unsupervised vMF Loss:
 - Maximize discrimination among segments.
 - $L_{\text{vMF}}^i = -\log p_\phi(c | \mathbf{v}_i, \Theta) = -\log \frac{\exp(\kappa \boldsymbol{\mu}_c^\top \mathbf{v}_i)}{\sum_{l=1}^k \exp(\kappa \boldsymbol{\mu}_l^\top \mathbf{v}_i)}$
- Supervised vMF-NCA Loss:
 - Maximize discrimination between *different-class* segments.
 - $L_{\text{vMF-N}}^i = -\log \sum_{s \in \mathcal{C}_i^+} p'_\phi(z_i = s | \mathbf{v}_i, \Theta) = -\log \frac{\sum_{s \in \mathcal{C}_i^+} \exp(\kappa \boldsymbol{\mu}_s^\top \mathbf{v}_i)}{\sum_{l \neq c} \exp(\kappa \boldsymbol{\mu}_l^\top \mathbf{v}_i)}$
- Memory bank caching segment prototypes across batches.

Contributions



1. First deep end-to-end non-parametric segmentation
2. First deep unsupervised semantic segmentation
3. Interpretability from retrieved segments

