

Grouping with Directed Relationships

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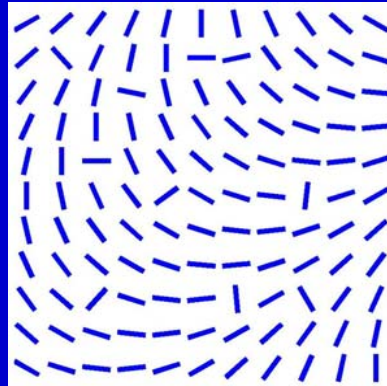
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Carnegie Mellon University
Center for the Neural Basis of Cognition

Grouping: finding global structures



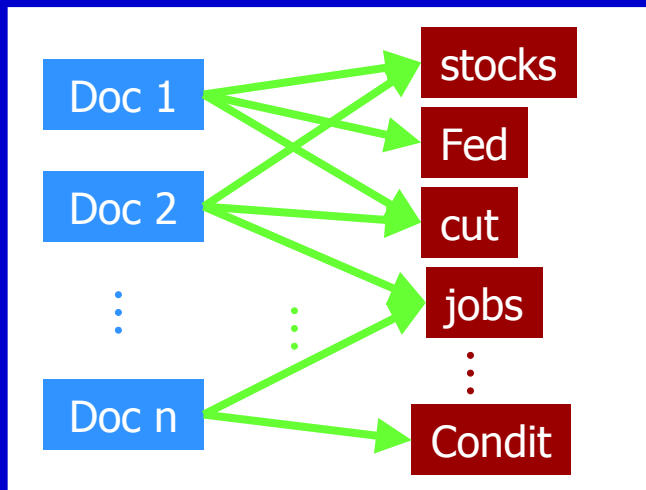
coherence



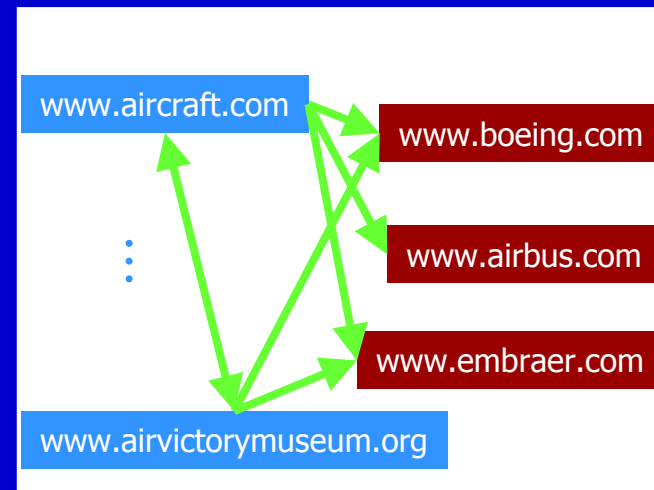
saliency



figure-ground



document clustering

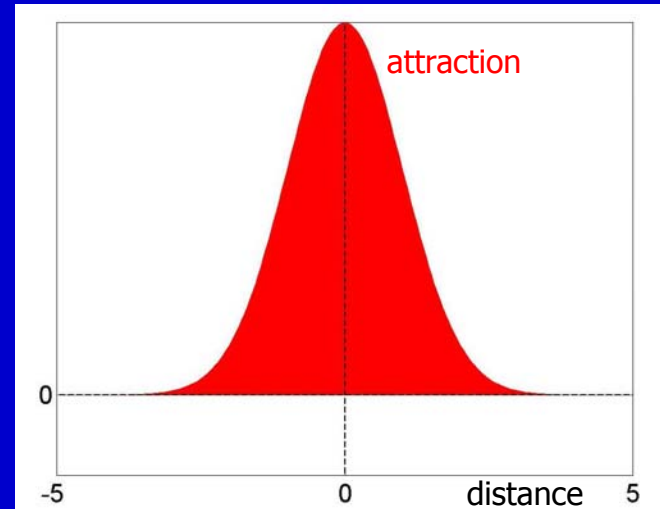
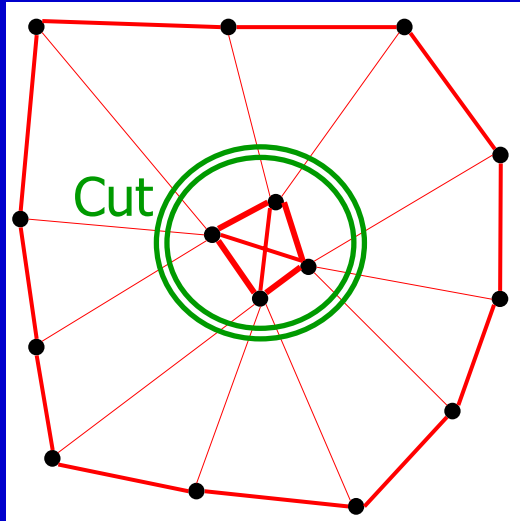


cyber community

Outline of the talk

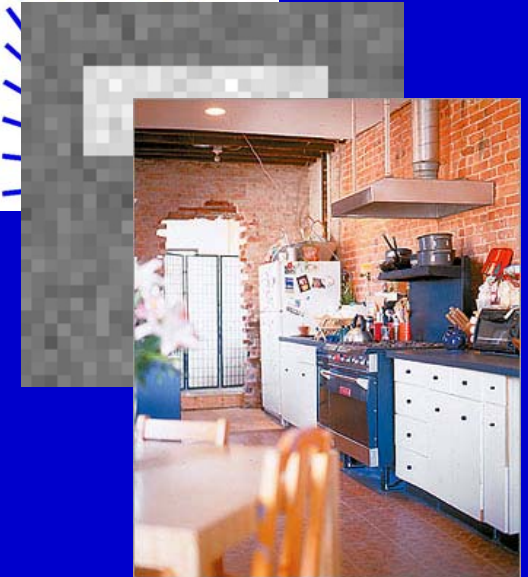
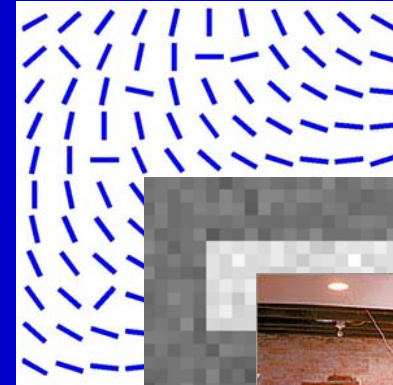
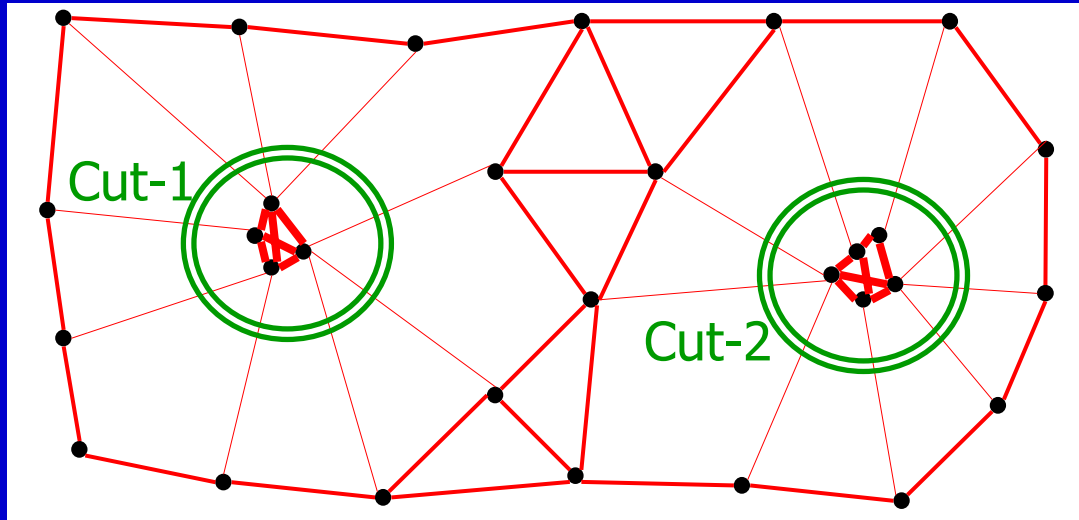
- Motivation
- Model
- Examples
- Conclusions

Motivation: grouping with pairwise similarity



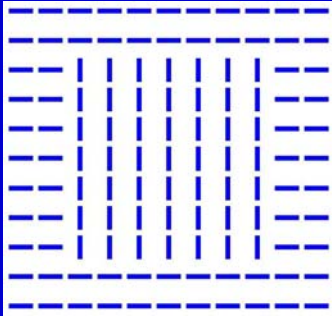
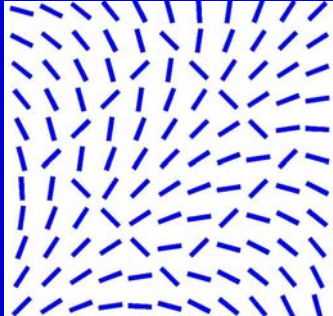
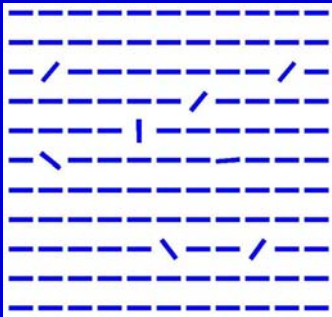
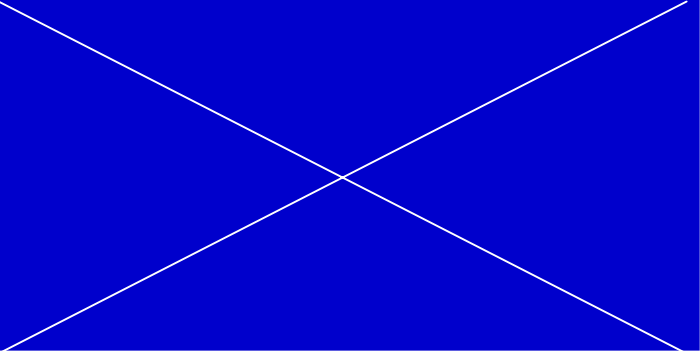
- Separation cost: pairwise similarity = attraction
- Attraction unites elements who have **common friends**

Motivation: similarity grouping is not enough

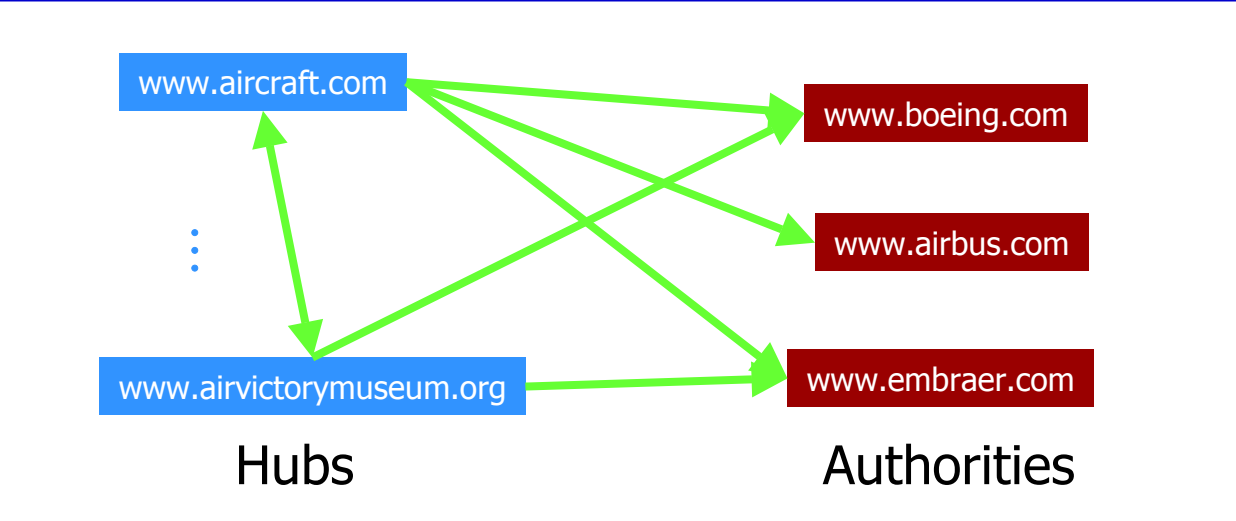
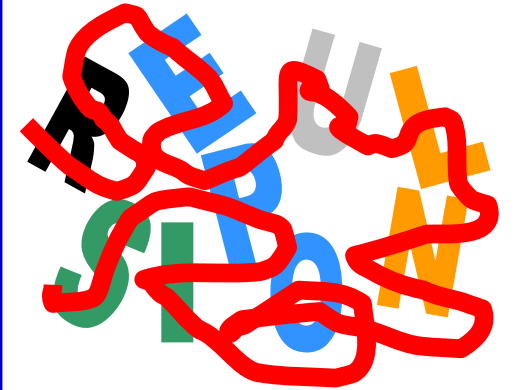


- $\text{Cost-1} + \text{Cost-2} > \min(\text{Cost-1}, \text{Cost-2})$
- Cannot unite elements who have common enemies

Motivation: similarity vs. dissimilarity

	Coherent ground	Incoherent ground
Coherent figure	 Yes	 Bad
Incoherent figure	 No	

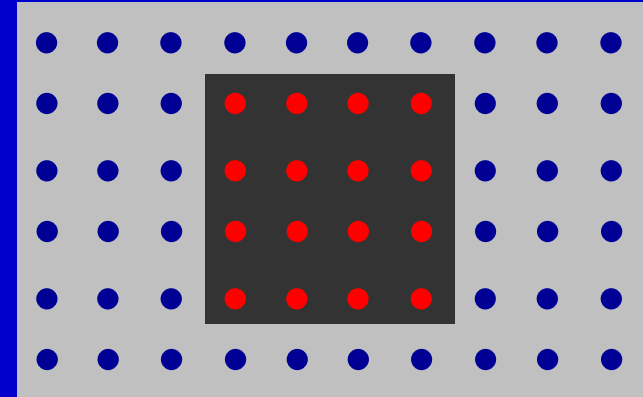
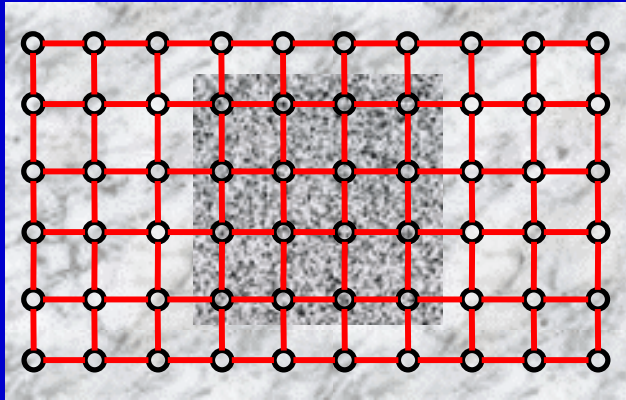
Motivation: grouping with ordering



Model

- Goal
 - Similarity grouping, dissimilarity grouping, figure-ground in one step
- Representation
 - A pair of directed graphs for any pairwise relationships
- Criteria
 - Generalized normalized cuts
- Energy formulation
 - Rayleigh quotients of Hermitian matrices
- Solution
 - Phase plane partitioning

Review: segmentation in a graph framework



- $G=(V, E, W)$
 - V: each node denotes a pixel
 - E: each edge denotes a pixel-pixel relationship
 - W: each weight measures pairwise similarity
- Segmentation = node partitioning
 - break V into disjoint sets V_1, V_2

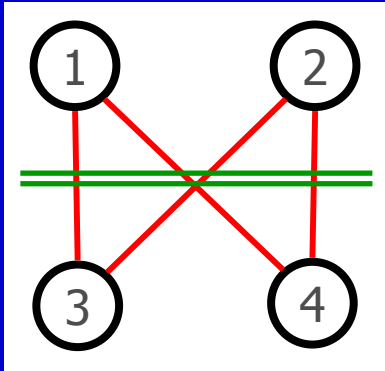
[Shi & Malik, 97]

[Puzicha et al, 98]

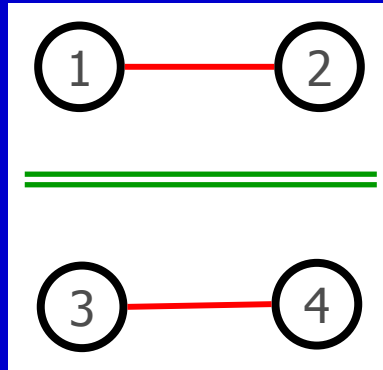
[Perona & Freeman, 99]

⋮

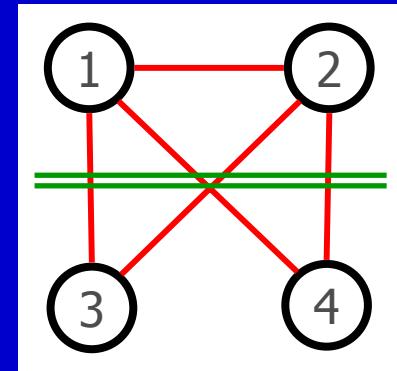
Review: cuts, associations, degrees



Cuts:
between-group similarity



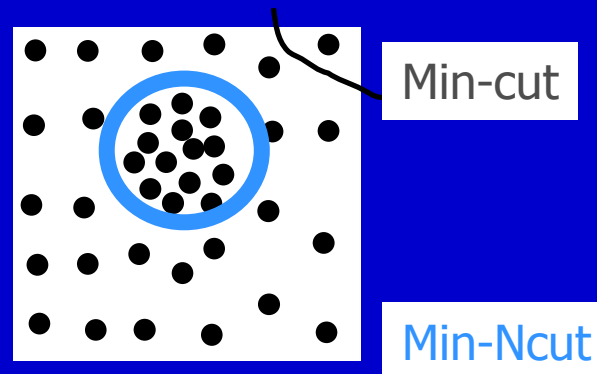
Associations:
within-group similarity



Degrees:
total similarity

Review: criteria and properties

- Two goals
 - Maximize normalized associations
 - Minimize normalized cuts
- Duality to achieve both goals at the same time
- Normalization for larger structures



Review: energy formulation

$$X_l(u) = \begin{cases} 1, & u \in V_l \\ 0, & u \notin V_l \end{cases} \quad X_1 = \begin{bmatrix} 1_{n_1 \times 1} \\ 0_{n_2 \times 1} \end{bmatrix}, \quad X_2 = \begin{bmatrix} 0_{n_1 \times 1} \\ 1_{n_2 \times 1} \end{bmatrix}$$

$$Nassoc(X_1, X_2) = \sum_{t=1}^2 \frac{X_t^T W X_t}{X_t^T D X_t}$$



$$y = (1 - \alpha) X_1 - \alpha X_2, \quad \alpha = \frac{\deg(V_1)}{\deg(V)}$$

$$Nassoc(y) = \frac{y^T W y}{y^T D y}, \quad s.t. \quad y^T D \mathbf{1} = 0$$

$$W y_{opt} = \lambda_2 D y_{opt}$$

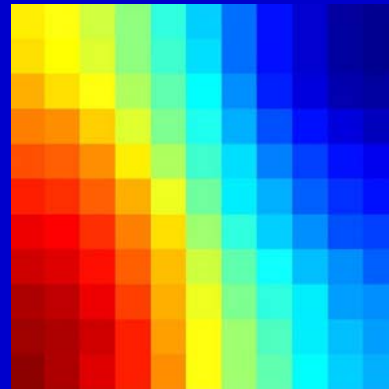
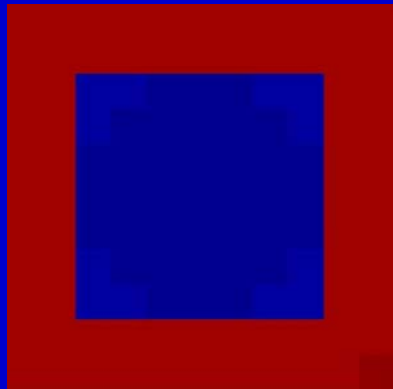
- Variables: indicators
- Energy functions
- Change of variables
- Rayleigh quotient
- Solution: eigenvector

Review: interpretation of the eigensolution

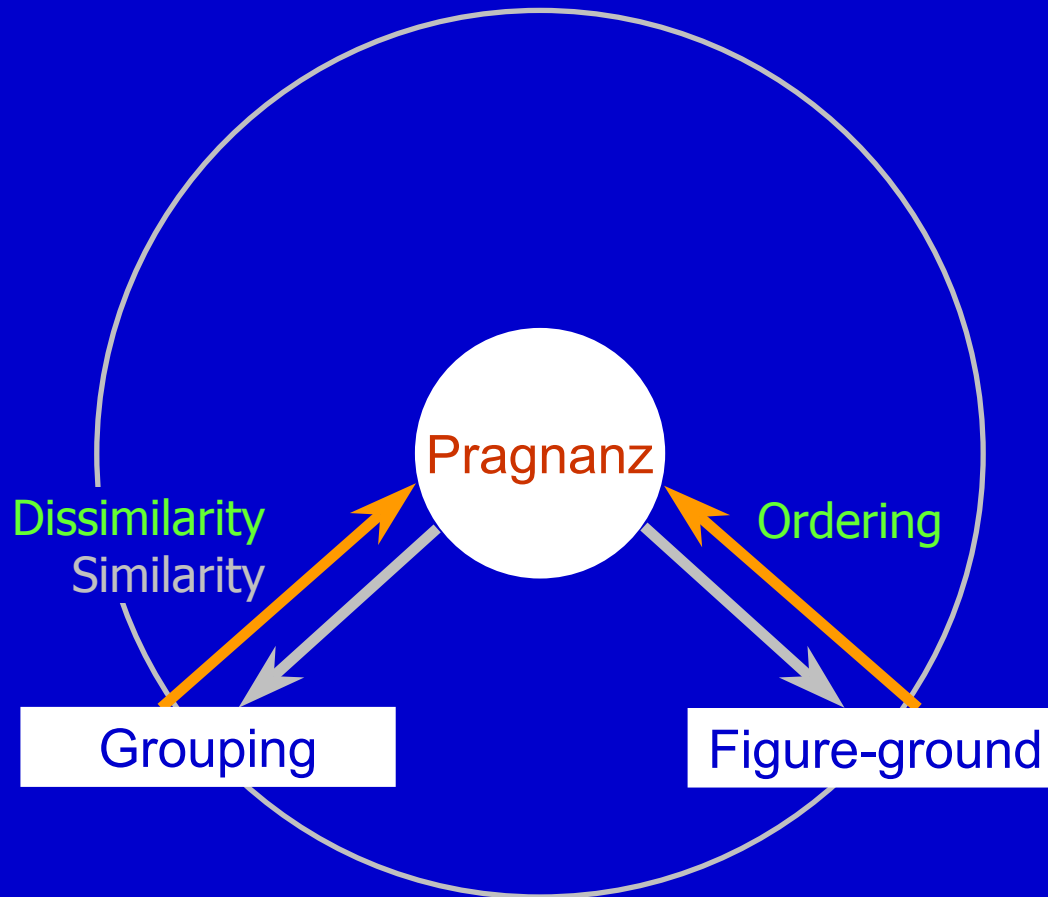
- The derivation holds so long as $X_1 + X_2 = 1$

$$y = X_1 - \alpha$$

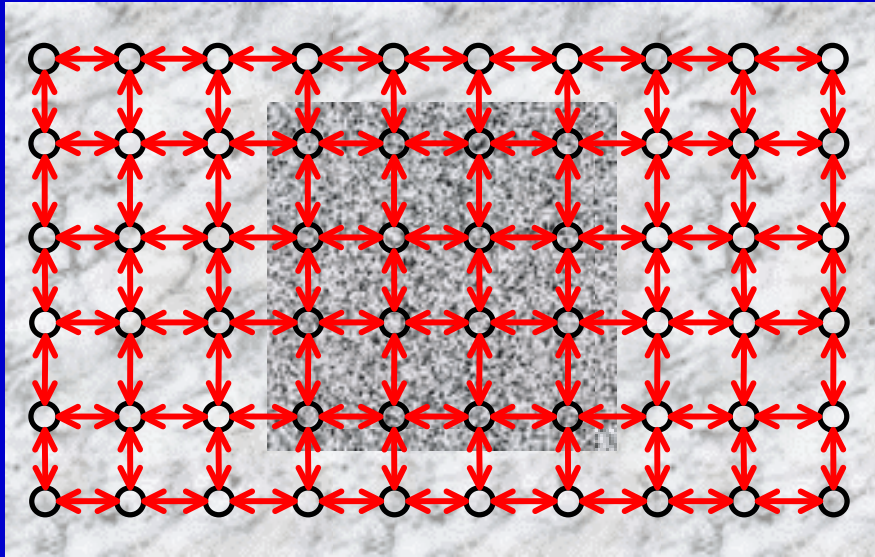
- The eigenvector solution is a linear transformation (scaled and offset version) of the probabilistic membership indicator for one group.
- If y is well separated, then two groups are well defined; otherwise, the separation is ambiguous



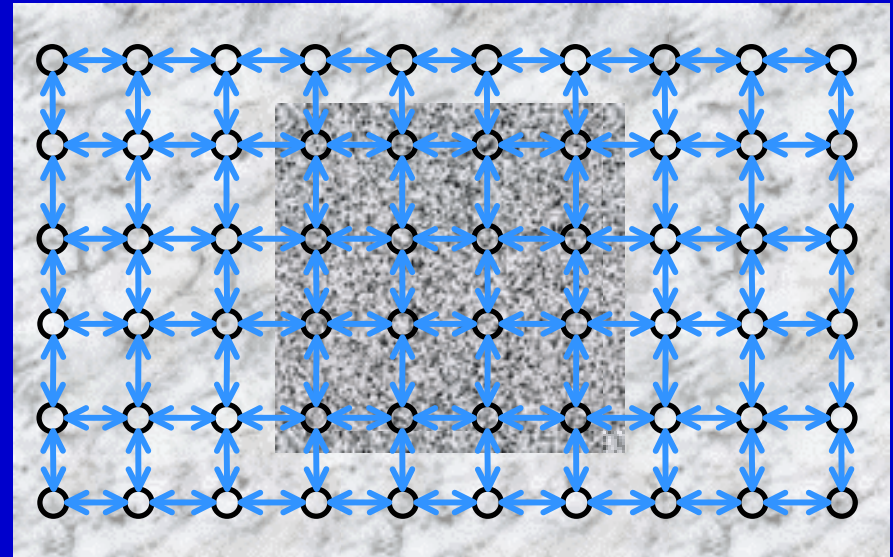
Model: goal



Model: representation

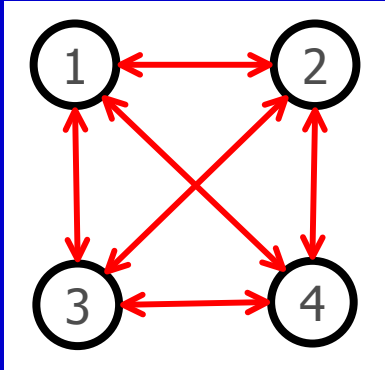


- $G=(V, E, A)$
- A asymmetric
- Separation cost



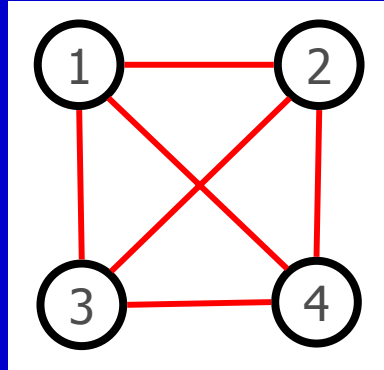
- $G=(V, E, R)$
- R asymmetric
- Separation gain

Model: attraction, repulsion, difference flow



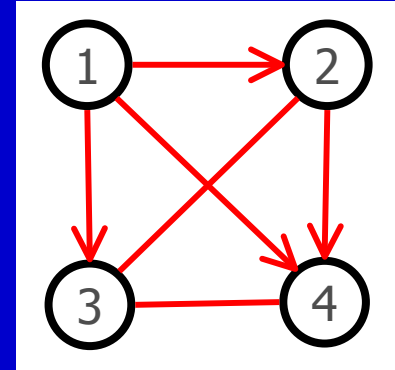
A

=

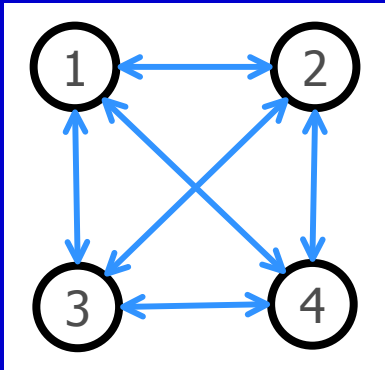


$A_u = A + A^T$

+

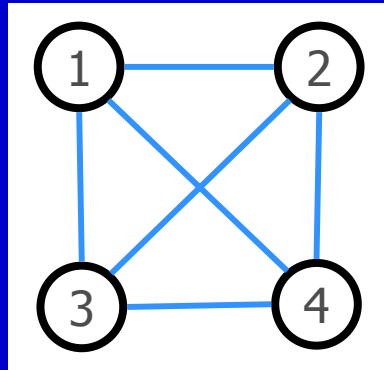


$A_d = A - A^T$



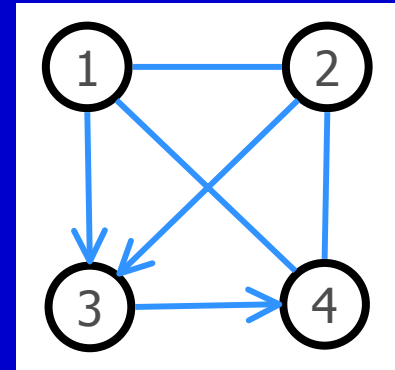
R

=



$R_u = R + R^T$

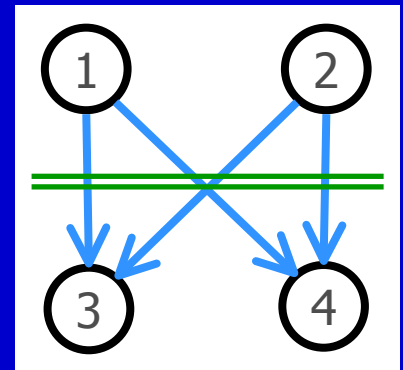
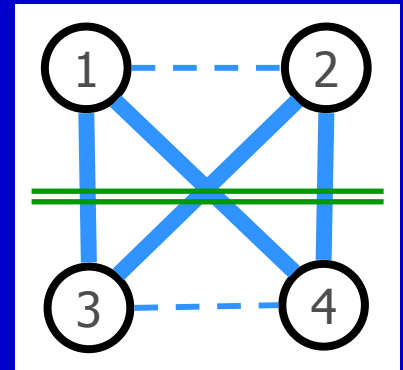
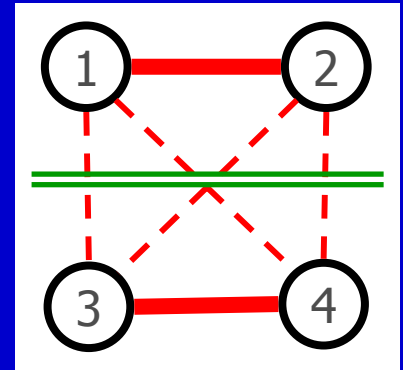
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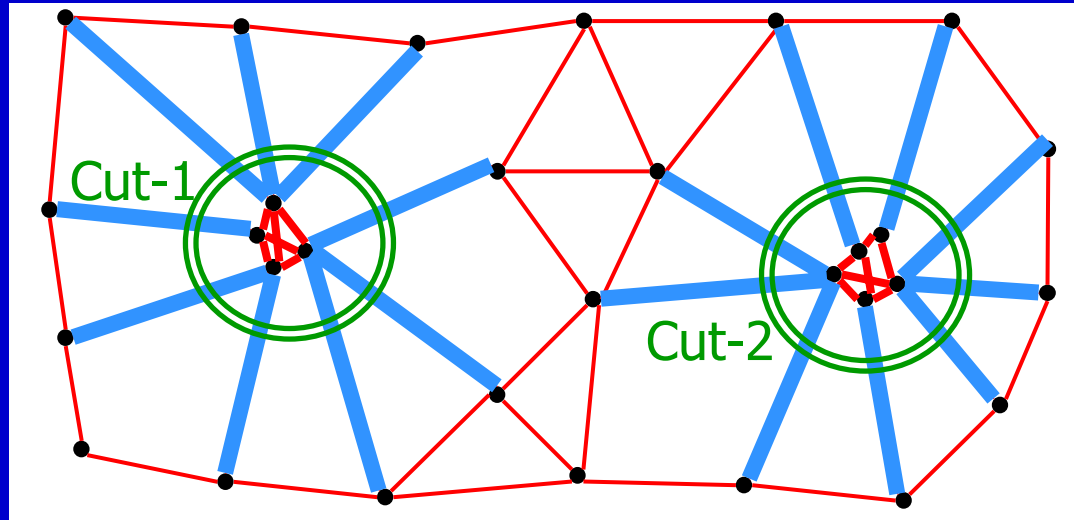
$R_d = R - R^T$

Model: criteria

- Maximize normalized
within-region similarity
between-region dissimilarity
figure-to-ground order
- Minimize normalized
between-region similarity
within-region dissimilarity
ground-to-figure order

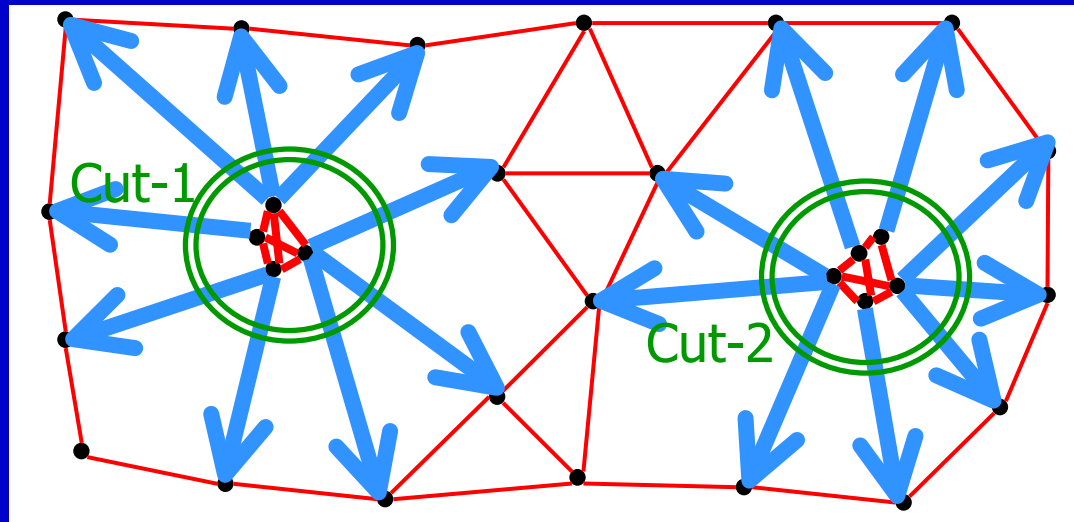


Model: is repulsion what we want?



- $\text{Cost-1} + \text{Cost-2} < \min (\text{Cost-1} + \text{Gain-2}, \text{Cost-2} + \text{Gain-1})$
- Repulsion unites elements who have common enemies

Model: is difference flow what we want?



- $\text{Cut}(V1, V2) \neq \text{Cut}(V2, V1)$
- Ordered partitioning

Model: energy formulation

$$X_l(u) = \begin{cases} 1, & u \in V_l \\ 0, & u \notin V_l \end{cases}$$

- Variables: group indicators

$$U = A_u - R_u + D_R$$

$$V = A_d + R_d$$

$$D = D_{A_u} + D_{R_u}$$

- Weight matrices and degree matrix

- Energy functions of indicator variables

$$Nassoc(X_1, X_2) = \sum_{t=1}^2 \frac{X_t^T U X_t}{X_t^T D X_t} + \frac{2X_1^T V X_2}{\sqrt{X_1^T D X_1 \cdot X_2^T D X_2}}$$

Model: energy formulation

$$Nassoc(X_1, X_2) = \sum_{t=1}^2 \frac{X_t^T U X_t}{X_t^T D X_t} + \frac{2X_1^T V X_2}{\sqrt{X_1^T D X_1 \cdot X_2^T D X_2}}$$

$$z = \sqrt{1-\alpha} X_1 - i\sqrt{\alpha} X_2, \quad \alpha = \frac{\deg(V_1)}{\deg(V)}$$

$$W = U + i \cdot V$$

$$Nassoc(z) = \frac{z^H W z}{z^H D z}$$

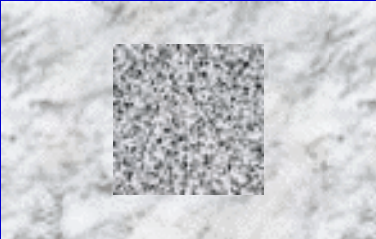
$$s.t. \quad z^{2T} D 1 = 0$$

- Change of variables
- Generalized affinity
- Rayleigh quotient

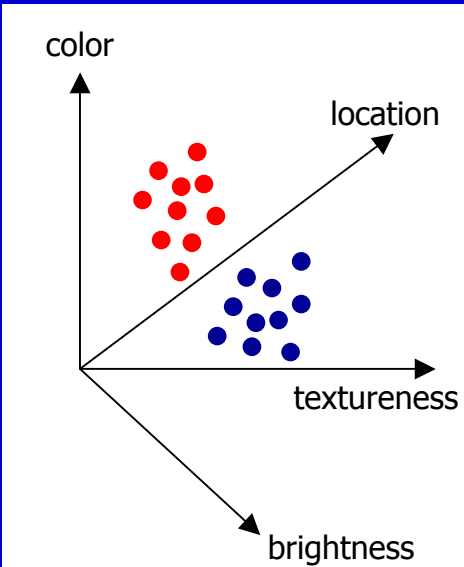
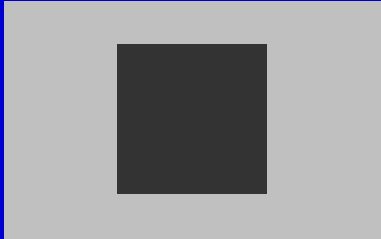
Model: three aspects of solutions

- Efficient solutions in the continuous domain:
 - Eigenvector corresponding to the largest eigenvalue of (W, D)
- Little increase in complexity
 - Hermitian matrices and sparse matrix eigendecomposition
- Interpretation of complex-valued solutions
 - Phase plane partitioning

Model: segmentation as embedding



Assign region identity.



$$z_{opt} = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix}$$

grouping

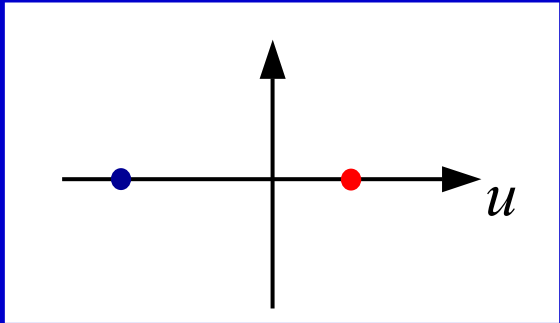
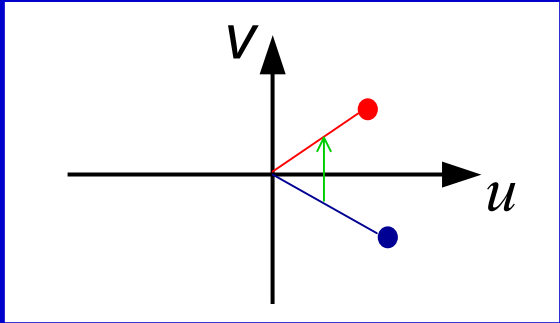


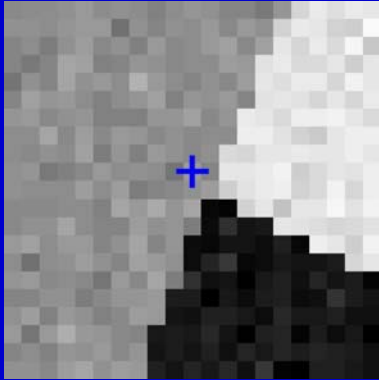
figure-ground

$$z_{opt} = \begin{bmatrix} u_1 + i \cdot v_1 \\ \vdots \\ u_n + i \cdot v_n \end{bmatrix}$$

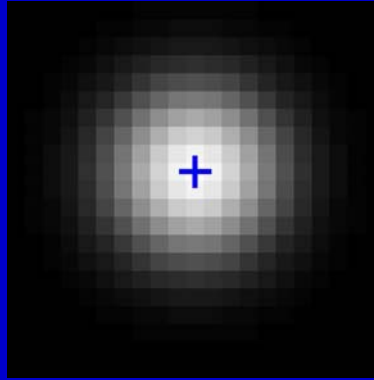


Results: difference flow for relative depth

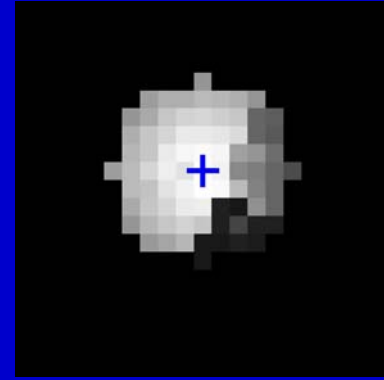
image



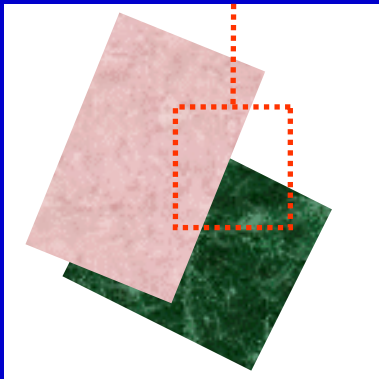
A by proximity



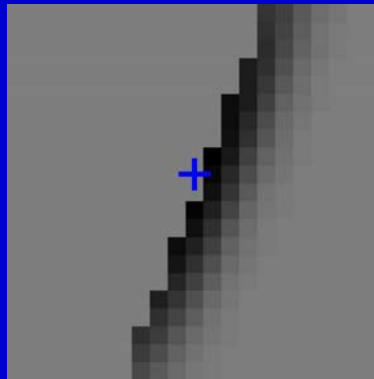
A by brightness similarity



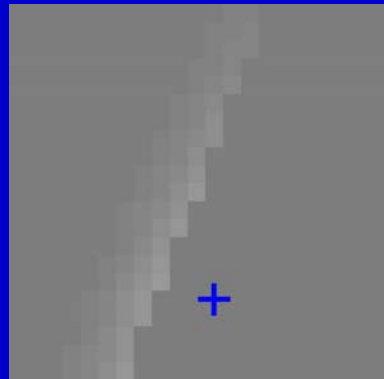
Relative depth
from T-junctions



R_d for a figure pixel

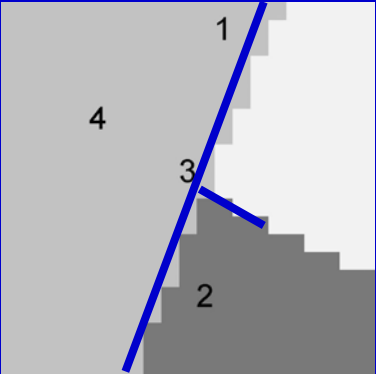


R_d for a ground pixel

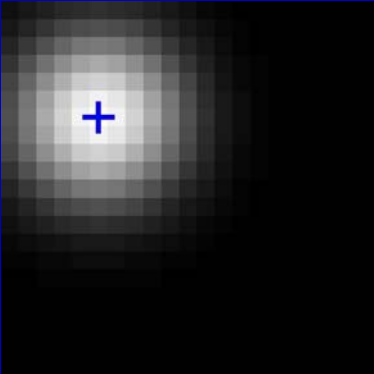


Results: interaction of attraction and repulsion

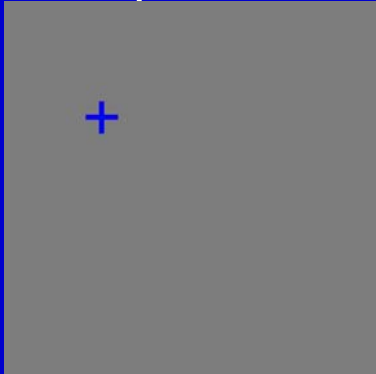
Image



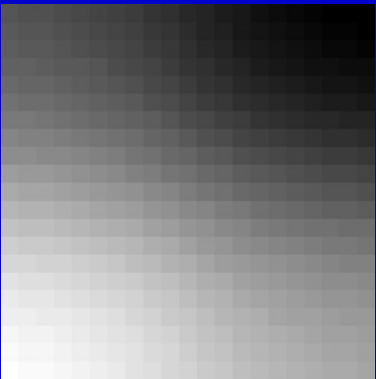
Attraction



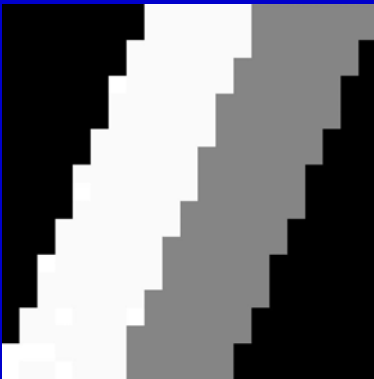
Repulsion



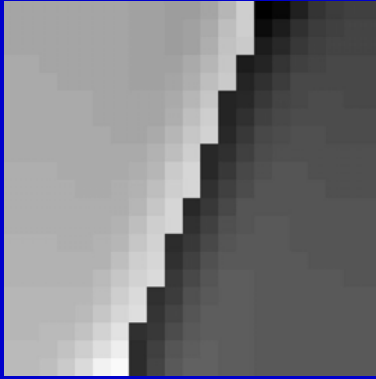
Result: A



Result: R

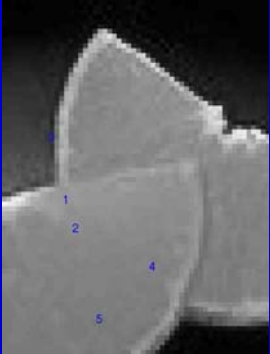


Result: A and R

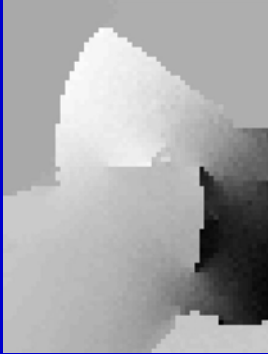


Results: figure-ground segregation

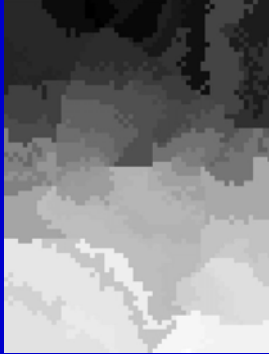
Image



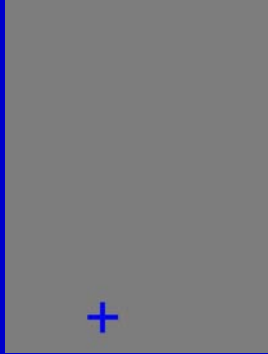
Solutions: A



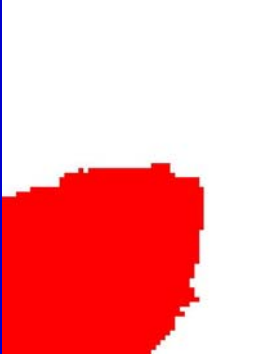
Oversegmentation based on A



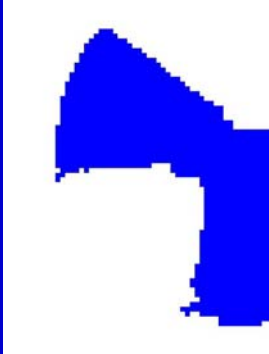
R



Figure



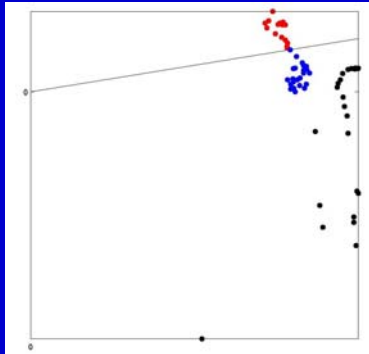
Ground 1



Ground 2

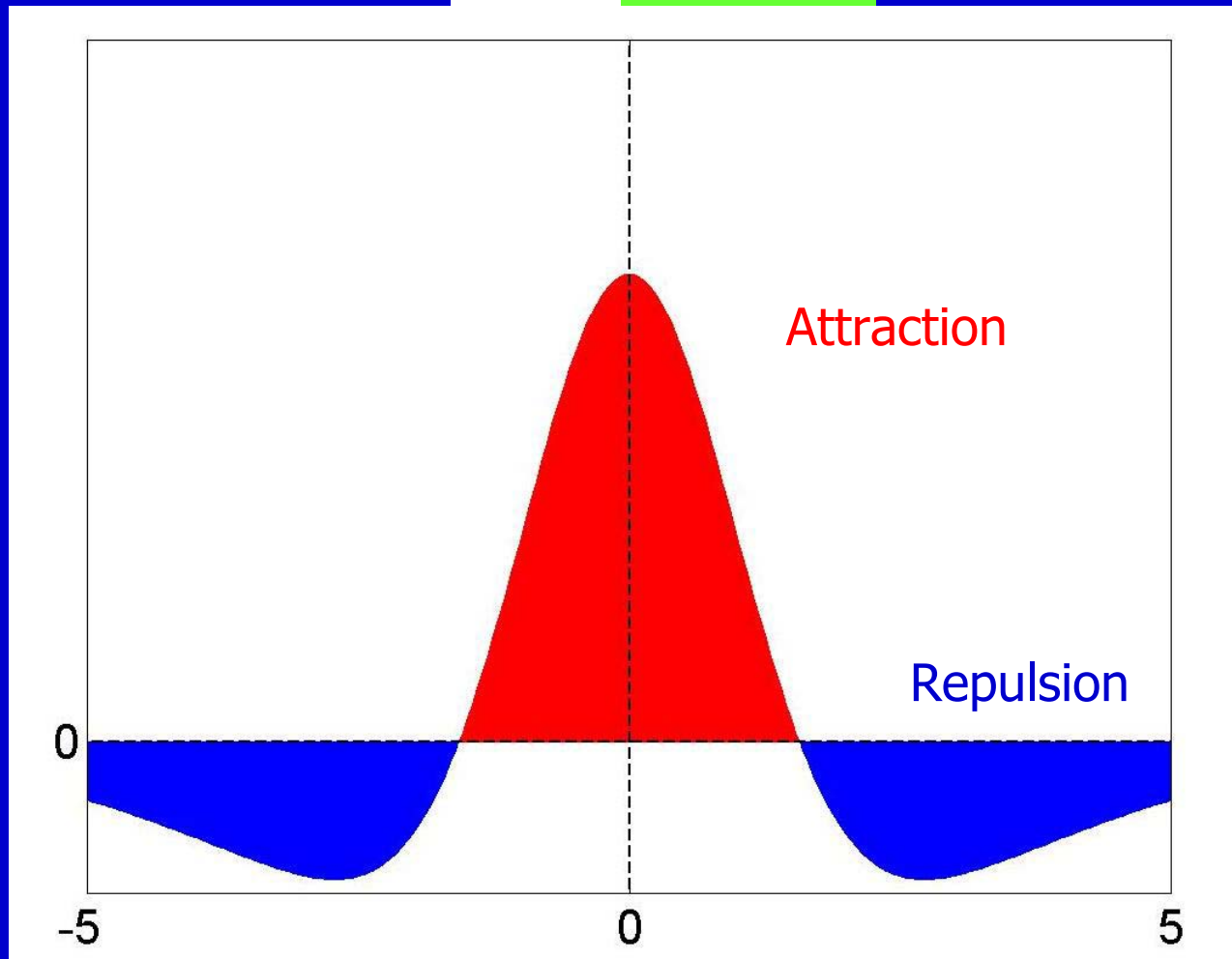


Phase plot

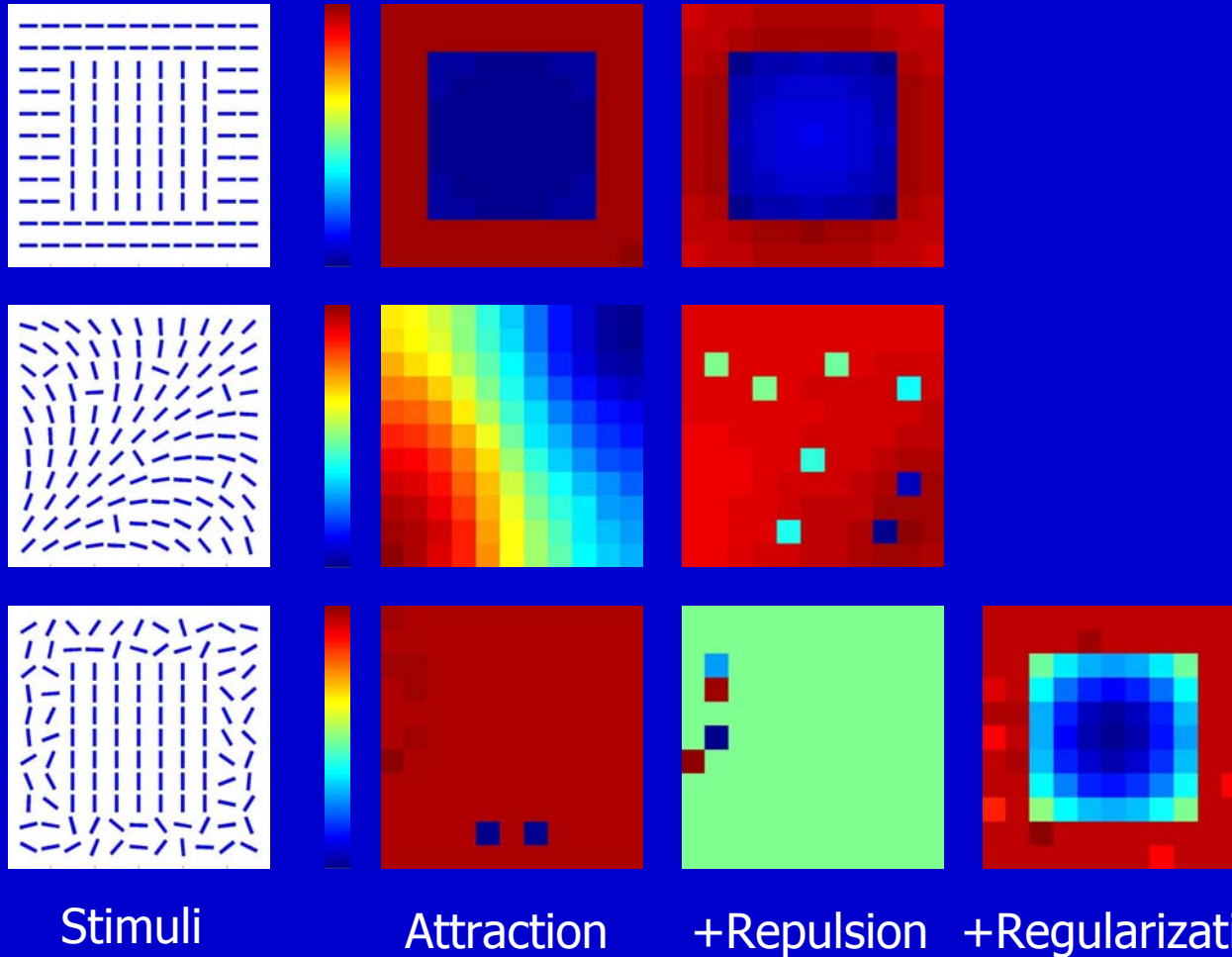


Results: from Gaussian to Mexican hat

$$U = A_u - R_u + D_R$$



Results: popout



Attraction to bind similar elements

Repulsion to bind dissimilar elements

Regularization to equalize

Stimuli

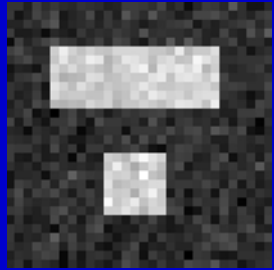
Attraction

+Repulsion

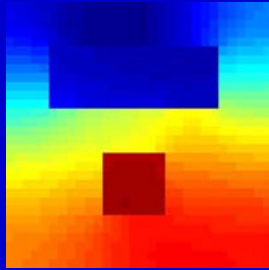
+Regularization

Results: computational efficiency

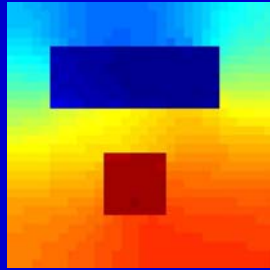
30 x 30 Image



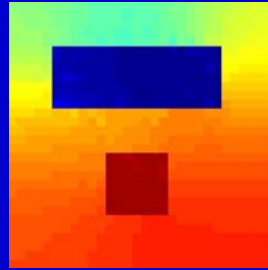
A: $r = 1$



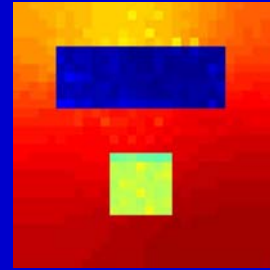
A: $r = 3$



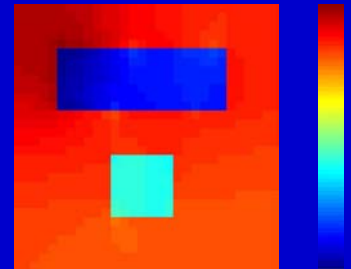
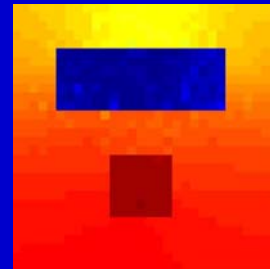
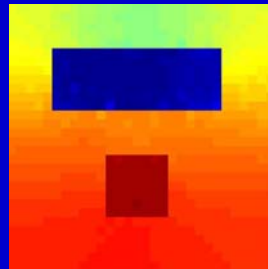
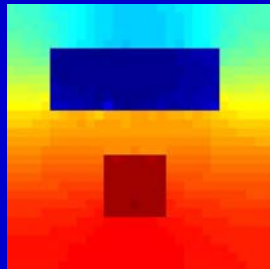
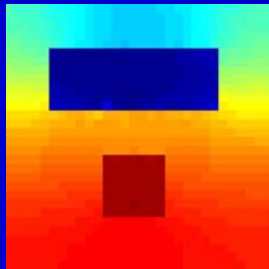
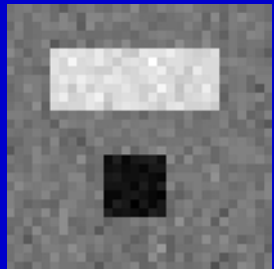
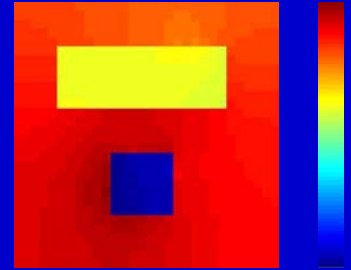
A: $r = 5$



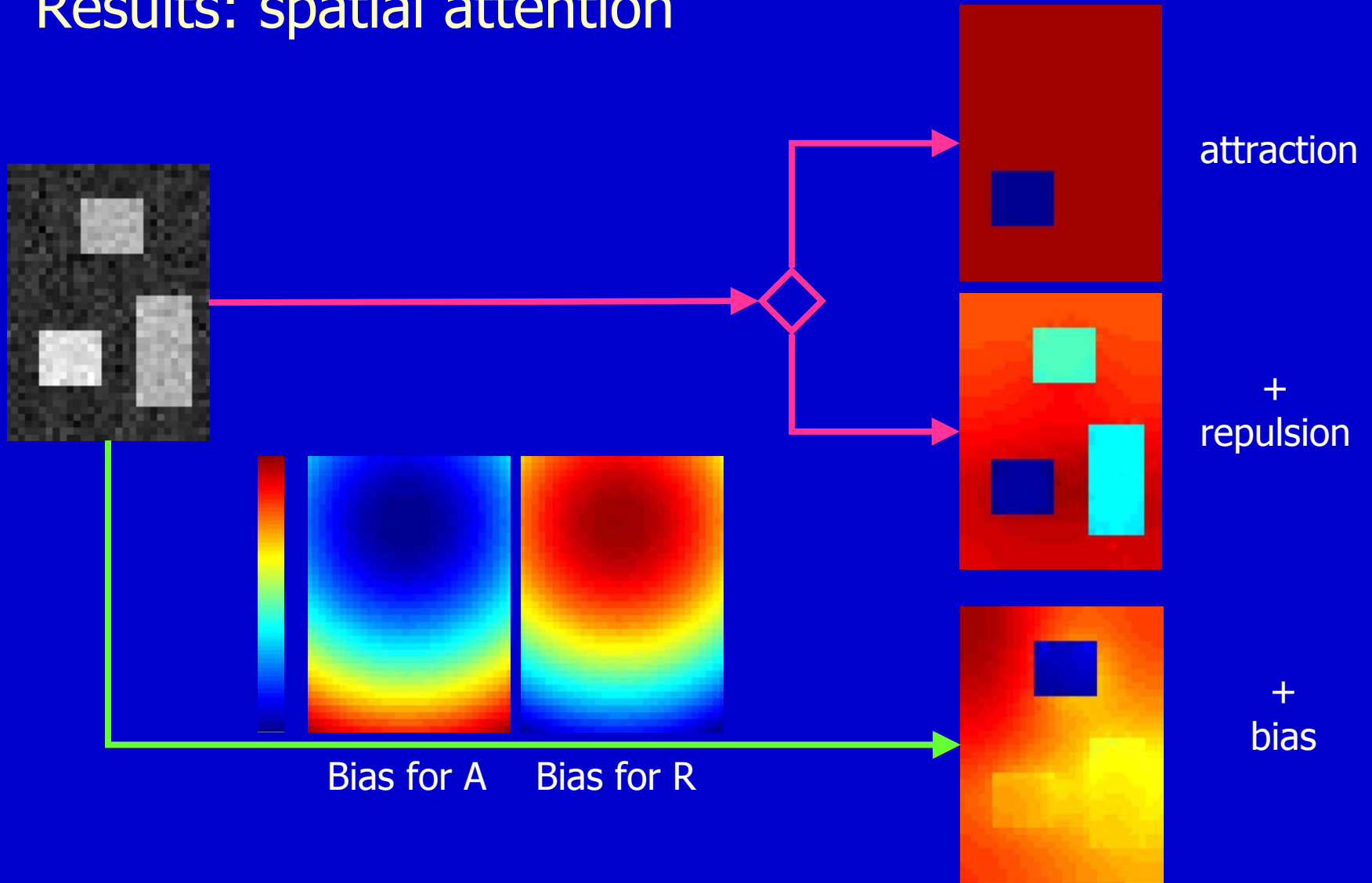
A: $r = 7$



[A, R]: $r = 1$



Results: spatial attention



Conclusions

- Pairwise relationships
 - Attraction: similarity grouping
 - Repulsion: dissimilarity grouping
 - Difference flow: relative ordering
- Advantages of repulsive and ordinal relationships:
 - Complementary
 - Computational efficiency
 - Treat 2D and 3D configuration cues equally
- Figure-ground organization

	Coherent ground	Incoherent ground
Coherent figure	Attraction	+Regularization
Incoherent figure	+Repulsion	