

Dictionary-Based Oscillating Steady State fMRI Reconstruction

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Declaration of Financial Interests or Relationships

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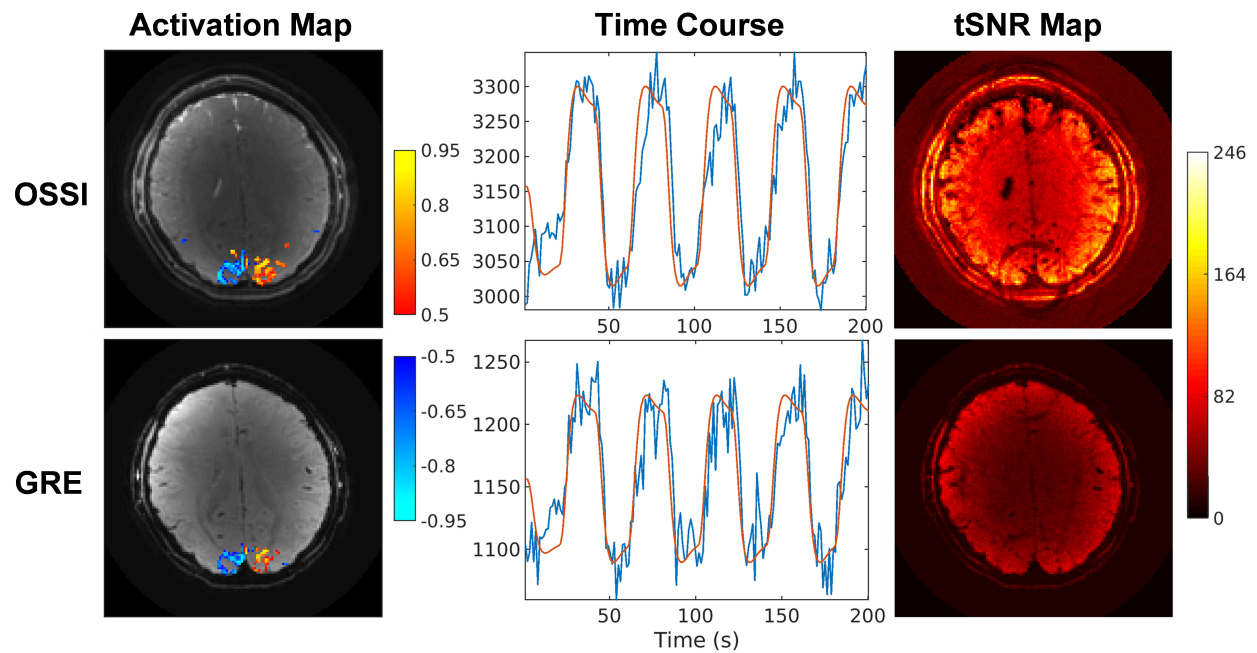
I have no financial interests or relationships to disclose with regard to the subject matter of this presentation.

Oscillating Steady-State Imaging (OSSI)¹

A new fMRI acquisition method exploits a large, oscillating signal

compared to GRE

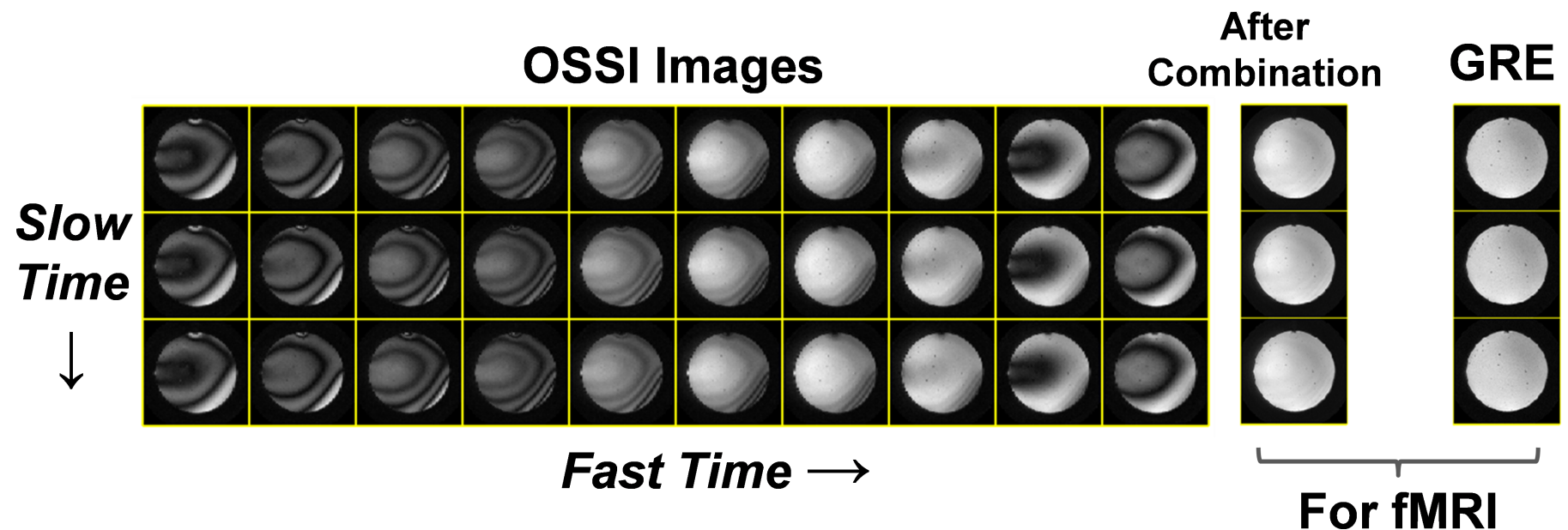
- ▶ 2 times higher SNR
- ▶ high-resolution fMRI



¹Guo and Noll, ISMRM, 2018 #5441, 2019 #1170

Need for k-Space Undersampling

RF phase cycling with cycle length n_c , OSSI signal oscillates with period $n_c TR$

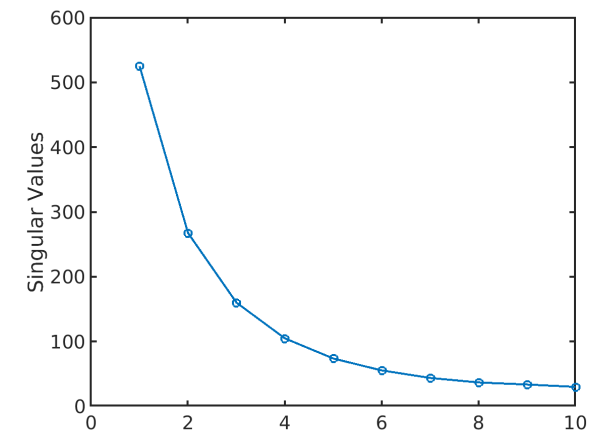
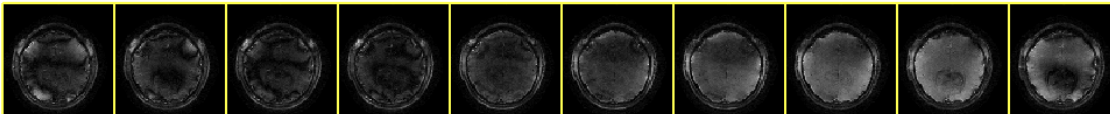


- ▶ $n_c = 10$ times more images would compromise temporal resolution
- ▶ short $TR = 15$ ms limits single-shot spatial resolution

Need for Nonlinear Dimension Reduction

Not very low-rank along fast time², linear subspace model may not help much

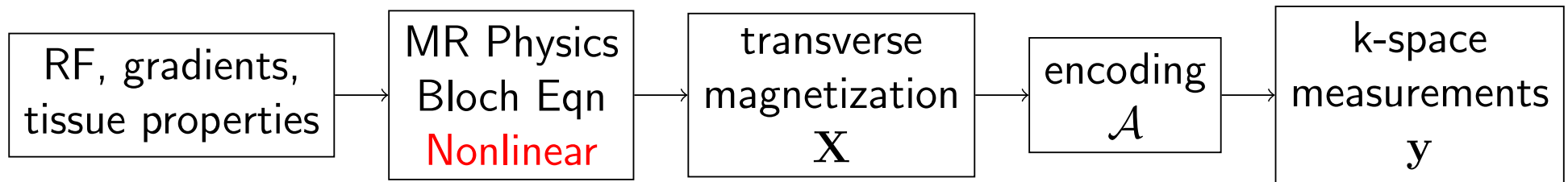
1 slow-time image set = 10 fast-time images



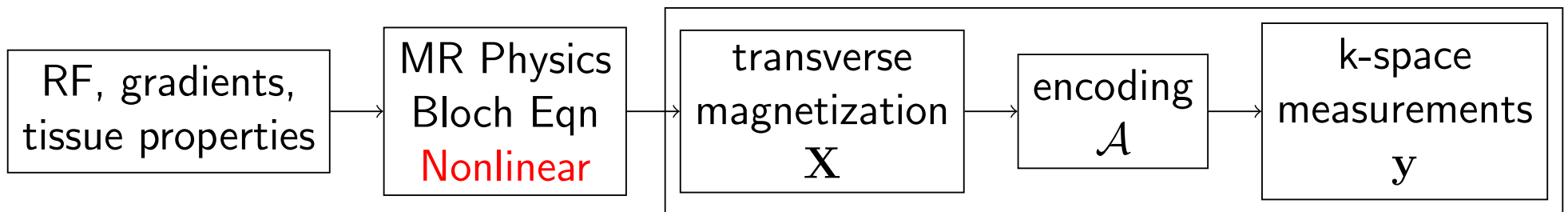
- ▶ nonlinearity of the OSSI signal
- ▶ dimension reduction for undersampling

²Guo and Noll, ISMRM, 2018 #3531

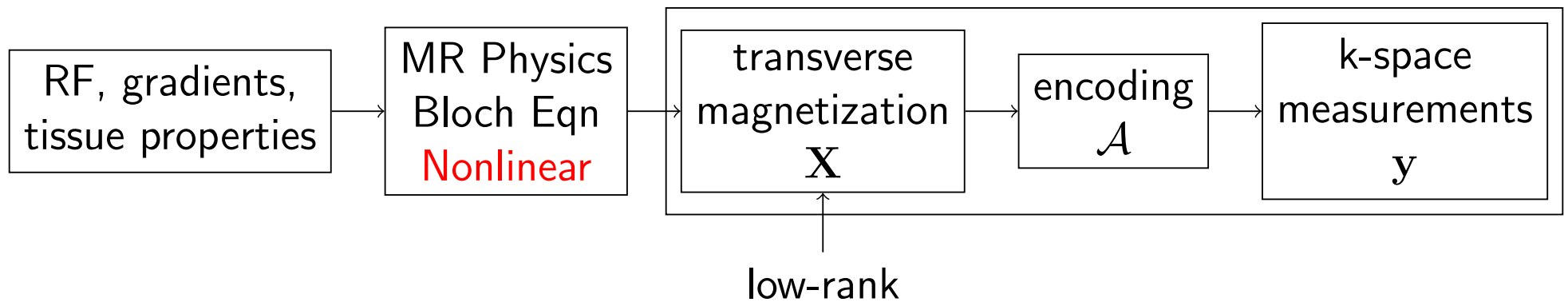
OSSI Manifold Model



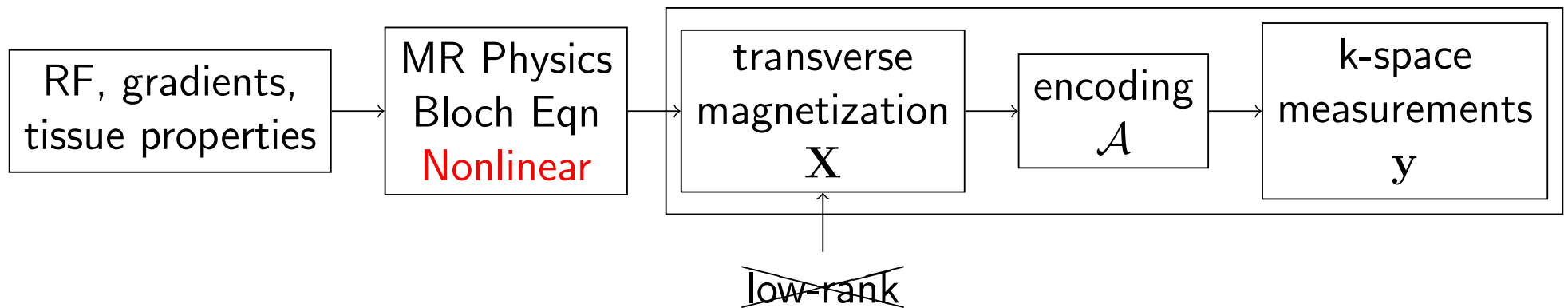
OSSI Manifold Model



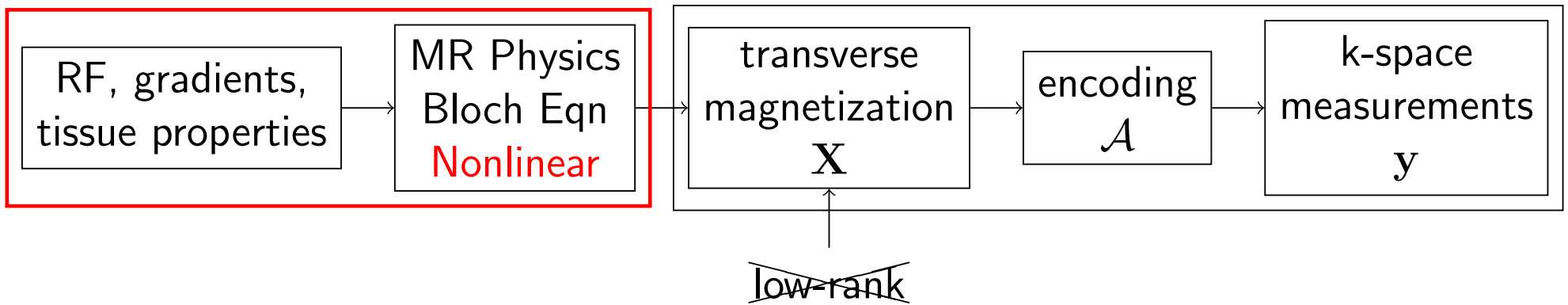
OSSI Manifold Model



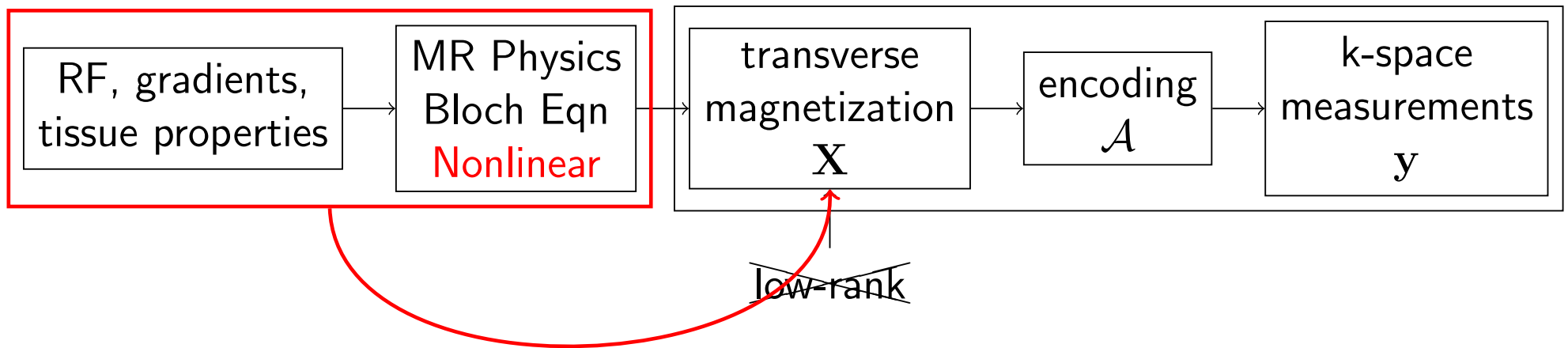
OSSI Manifold Model



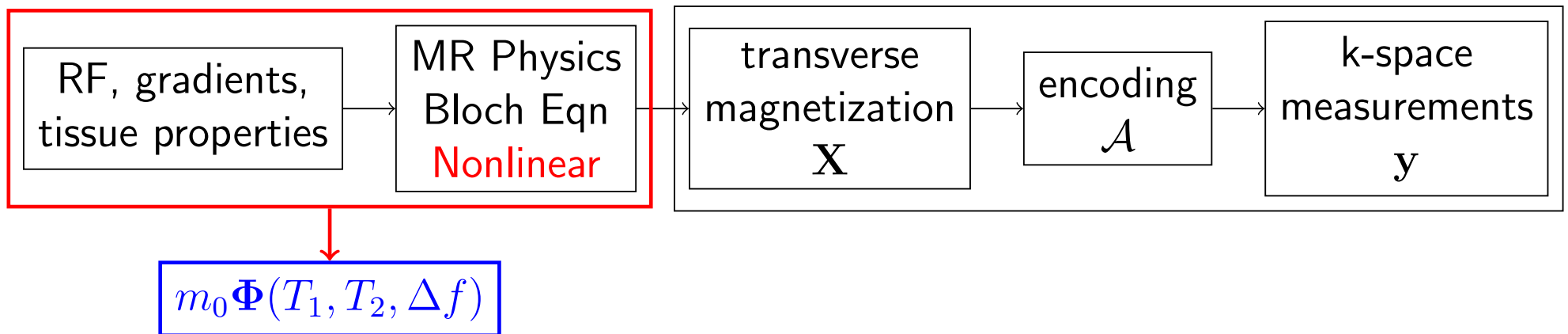
OSSI Manifold Model



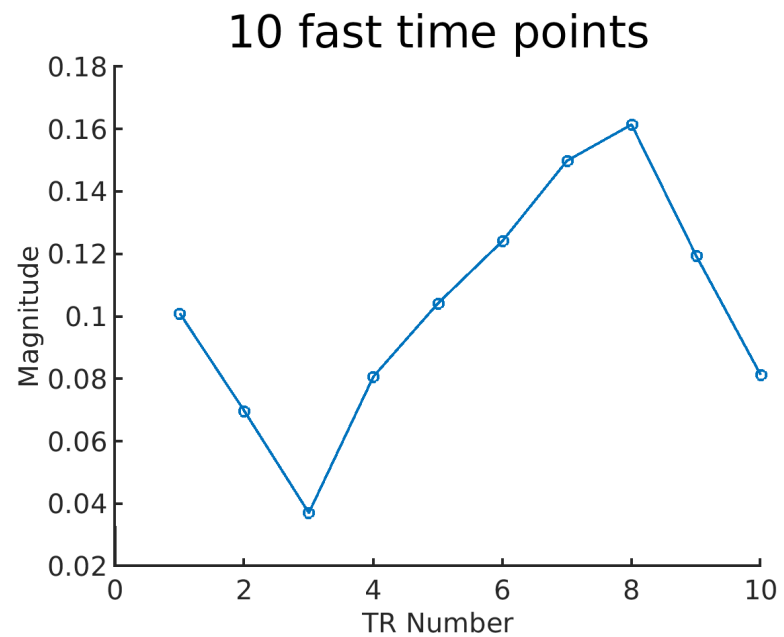
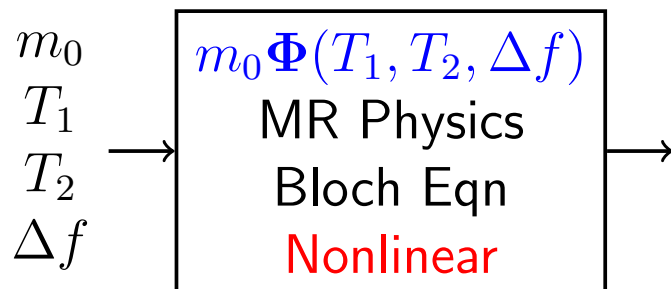
OSSI Manifold Model



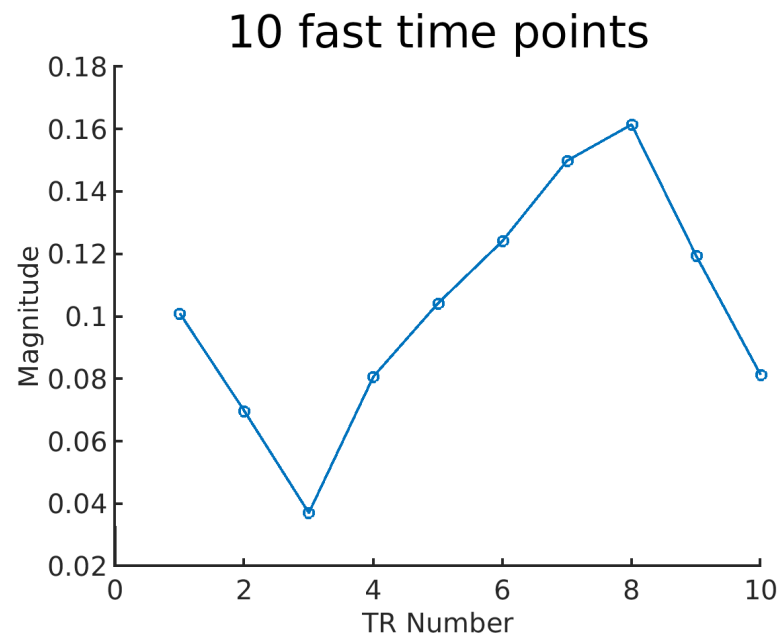
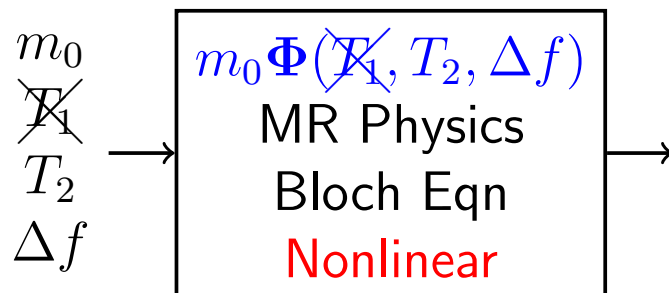
OSSI Manifold Model



Parameterization of OSSI Signal

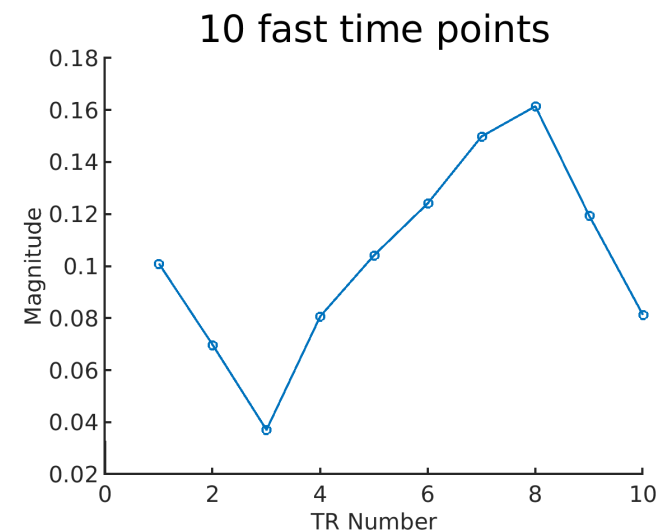
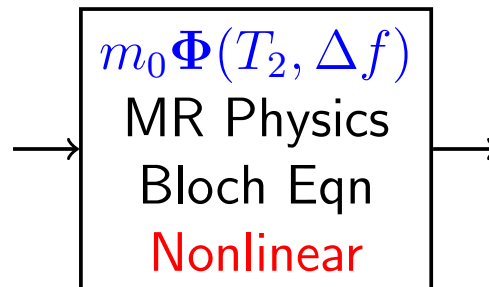


Parameterization of OSSI Signal



Parameterization of OSSI Signal

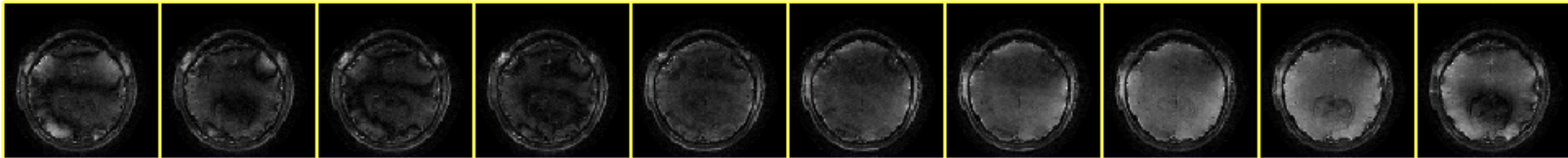
m_0 signal magnitude
 T_2 tissue properties
 Δf off-resonance frequency



- ▶ effectively 3 physical parameters \Rightarrow 10 time points
- ▶ nonlinear dimension reduction

Voxel-Wise Near Manifold Regularizer

- ▶ One slow-time image set $\mathbf{X} \in \mathbb{C}^{N_x \times N_y \times n_c}$, $n_c = 10$



- ▶ Voxel-wise

$\mathbf{v} = \mathbf{X}[i, j, :] \in \mathbb{C}^{n_c}$ is a vector of 10 fast-time image values

Voxel-Wise Near Manifold Regularizer

- Problem formulation for one slow-time image set $\mathbf{X} \in \mathbb{C}^{N_x \times N_y \times n_c}$,

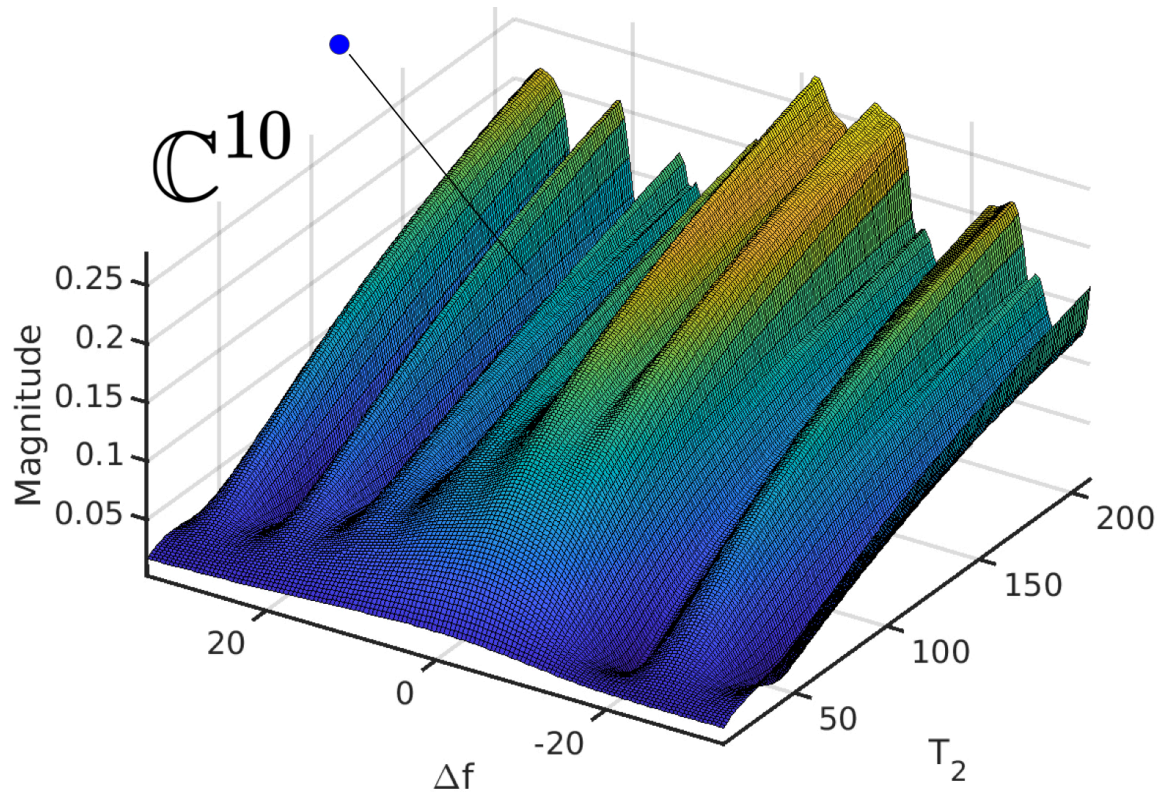
$$\hat{\mathbf{X}} = \arg \min_{\mathbf{X}} \frac{1}{2} \|\mathcal{A}(\mathbf{X}) - \mathbf{y}\|_2^2 + \beta \sum_{i,j} R(\mathbf{X}[i, j, :]),$$

$$R(\mathbf{v}) = \min_{m_0, T_2, \Delta f} \|\mathbf{v} - m_0 \Phi(T_2, \Delta f)\|_2^2,$$

- $\mathcal{A}(\cdot)$ is the encoding operator,
- \mathbf{y} denotes undersampled k-space measurements,
- β is the regularization parameter.

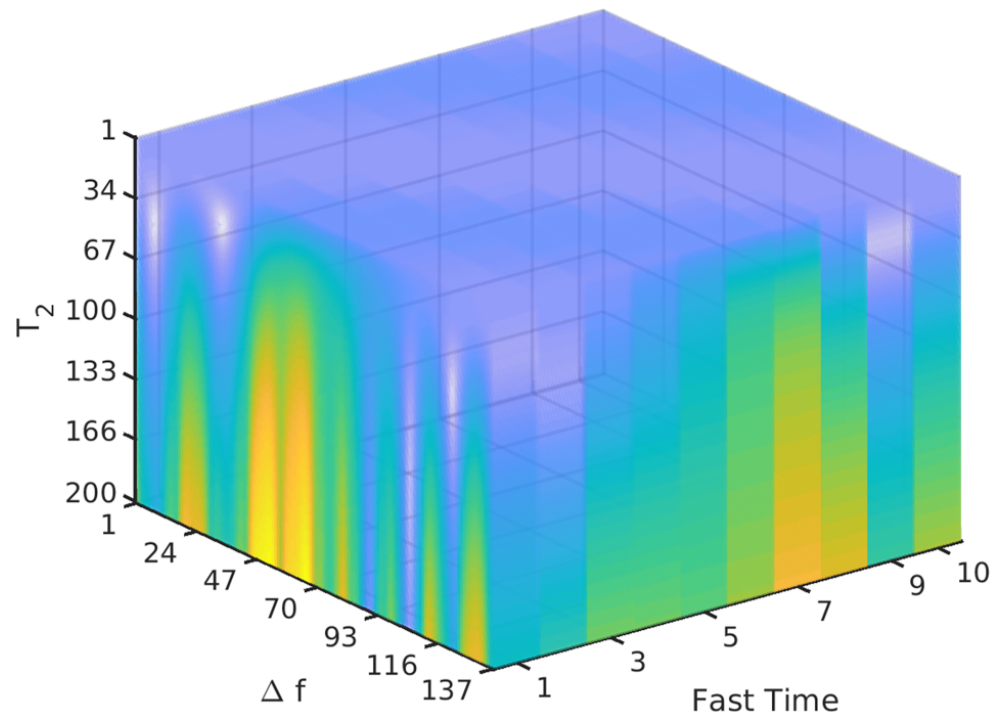
$$R(\mathbf{v}) = \min_{m_0, T_2, \Delta f} \|\mathbf{v} - m_0 \Phi(T_2, \Delta f)\|_2^2$$

- $\{m_0 \Phi(T_2, \Delta f) \in \mathbb{C}^{10} : m_0 \in \mathbb{C}, T_2, \Delta f \in \mathbb{R}\}$



$$R(\mathbf{v}) = \min_{m_0, T_2, \Delta f} \|\mathbf{v} - m_0 \Phi(T_2, \Delta f)\|_2^2$$

- ▶ nonlinear least square \implies dictionary fitting via VARPRO³



³Golub and Pereyra, Inverse problems, 2003

MR Physics Based Reconstruction

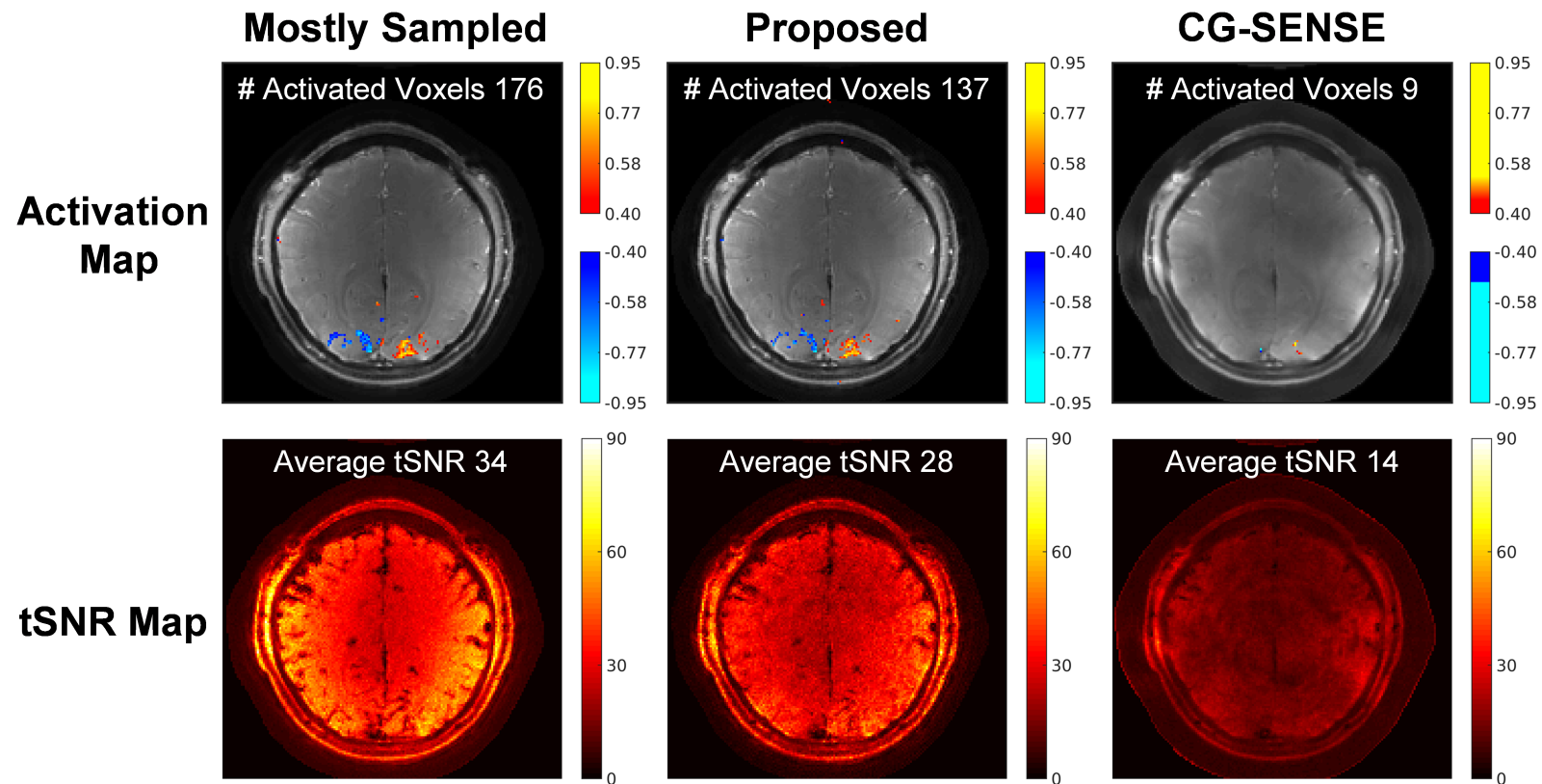
$$\hat{\mathbf{X}} = \arg \min_{\mathbf{X}} \frac{1}{2} \|\mathcal{A}(\mathbf{X}) - \mathbf{y}\|_2^2 + \beta \sum_{i,j} R(\mathbf{X}[i, j, :]),$$

$$R(\mathbf{v}) = \min_{m_0, T_2, \Delta f} \|\mathbf{v} - m_0 \Phi(T_2, \Delta f)\|_2^2,$$

- ▶ alternating minimization
- ▶ \mathbf{X} update \rightarrow the conjugate gradient method
- ▶ regularizer update \rightarrow dictionary fitting
- ▶ easily parallelized for all slow-time points

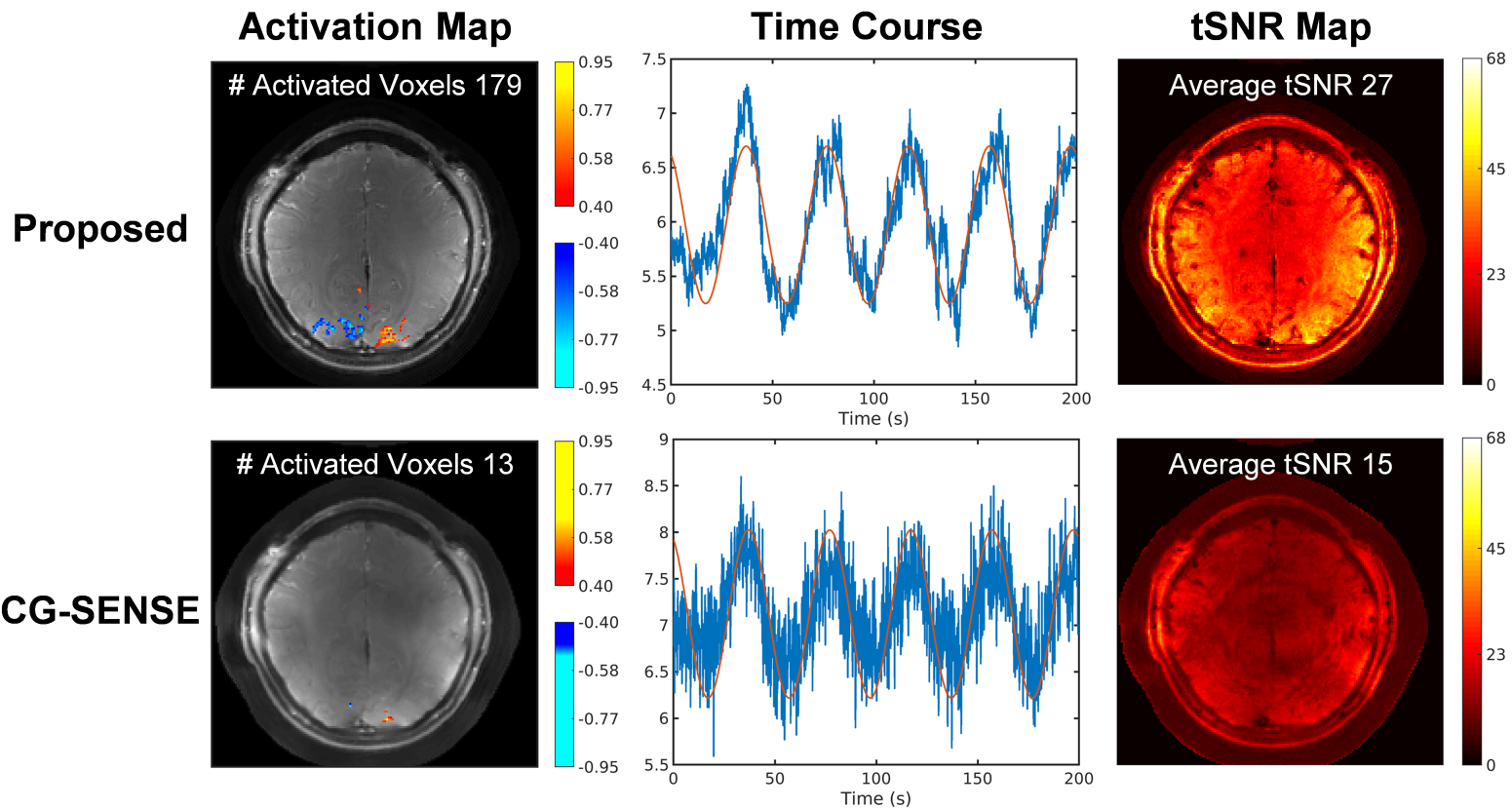
2D Human Retrospective Undersampling

- ▶ acceleration factor 12, NRMSD 5.6%, spatial resolution = 1.3 mm



2D Human Prospective Undersampling

- ▶ acceleration factor 12, spatial resolution = 1.3 mm, temporal resolution = 150 ms



Dictionary-Based Oscillating Steady State fMRI Reconstruction

- ▶ MR physics based signal model for reconstruction as a voxel-wise parametric regularizer
- ▶ Nonlinear dimension reduction for OSSI
- ▶ Acceleration factor of 12 with NRMSE 5.6%
- ▶ No spatial or temporal smoothing
- ▶ Joint undersampled reconstruction and parameter estimation

Future Work

- ▶ More accurate parameterization, T_2 or T_2^*
- ▶ More exploration of the manifold
- ▶ Combine with other regularizers
(for both undersampled reconstruction and parameter estimation)

Acknowledgement

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