This is an addendum to "Strict L_{∞} isotonic regression" (2012), J. Optimization Theory and Applications 152, pp. 121–135, Quentin F. Stout.

Algorithm C below is a simplified algorithm for determining strict L_{∞} isotonic regression of an arbitrary dag. It uses a simple array and a single sort instead of the dynamic priority queue used in Algorithm B. The time constants should be quite small.

If the dag has a transitive closure of m' pairs then the time is $\Theta(m' \log m')$, the same as Algorithm B (this does not count the time to determine the transitive closure, which is part of the input). In terms of the original dag with n vertices this is at most $\Theta(n^2 \log n)$. A more detailed time analysis gives $\Theta(m' + m^* \log m^*)$, where m^* is the number of violating pairs of vertices, i.e., vertices u, v such that $u \prec v$ and f(u) > f(v). The only component taking $\Theta(m^* \log m^*)$ time is the sort, with all other lines combined taking only $\Theta(m')$. Thus, for a fixed dag, the more isotonic the data is, the faster the algorithm.

```
input: weighted data (f,w), lists of successors and predecessors for each vertex output: strict L_{\infty} isotonic regression function S violators: array of (mean_error,u,v) for violating pairs u \prec v, f(u) > f(v) lowbd(v), upbd(v): lower and upper bounds on S(v)
```

```
numviolate=0
```

```
for every vertex v
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lowbd(v) = $-\infty$; upbd(v) = $+\infty$; S(v) = undefined for every successor s of v if f(v) > f(s) then violators(numviolate)= (mean_err(v,s), v, s); numviolate++

```
sort violators by mean_err
```

```
for i=0 to numviolate-1
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```
(mean_err,pred,suc)=violators(i)
if (S(pred) defined) ∨ (S(suc) defined) then cycle
wmean = mean(pred,suc)
if wmean ≥ upbd(pred) then {f(pred) is ≥ upbd(pred), no later mean is < upbd(pred)}
S(pred) = upbd(pred)
if wmean ≤ lowbd(suc) then {f(suc) is ≤ lowbd(suc), no later mean is > lowbd(suc)}
S(suc) = lowbd(suc)
if (S(pred) undefined) ∧ (S(suc) undefined) then {low(suc) ≤ wmean ≤ high(pred)}
S(pred) = S(suc) = wmean
```

```
if S(pred) defined then
    for every successor s of pred
        lowbd(s) = max{lowbd(s),S(pred)}
if S(suc) defined then
    for every predecessor p of suc
        upbd(p) = min{upbd(p),S(suc)}
```

```
end for i
```

```
for every vertex v

if S(v) undefined then

if f(v) \geq upbd(v) then S(v)=upbd(v)

else if f(v) \leq lowbd(v) then S(v)=lowbd(v)

else S(v)=f(v)
```

Algorithm C: Computing S=Strict(f,w) using transitive closure