EECS 583 – Class 3 Region Formation, Predicated Execution

University of Michigan

September 11, 2019

Announcements & Reading Material

- ♦ HW1 is out Due Fri Sept 20
 - » http://web.eecs.umich.edu/~mahlke/courses/583f19
- Today's class
 - "Trace Selection for Compiling Large C Applications to Microcode", Chang and Hwu, MICRO-21, 1988.
 - "The Superblock: An Effective Technique for VLIW and Superscalar Compilation", Hwu et al., Journal of Supercomputing, 1993
- Material for Monday
 - "The Program Dependence Graph and Its Use in Optimization", J. Ferrante, K. Ottenstein, and J. Warren, ACM TOPLAS, 1987
 - This is a long paper the part we care about is the control dependence stuff. The PDG is interesting and you should skim it over, but we will not talk about it now
 - "On Predicated Execution", Park and Schlansker, HPL Technical Report, 1991.

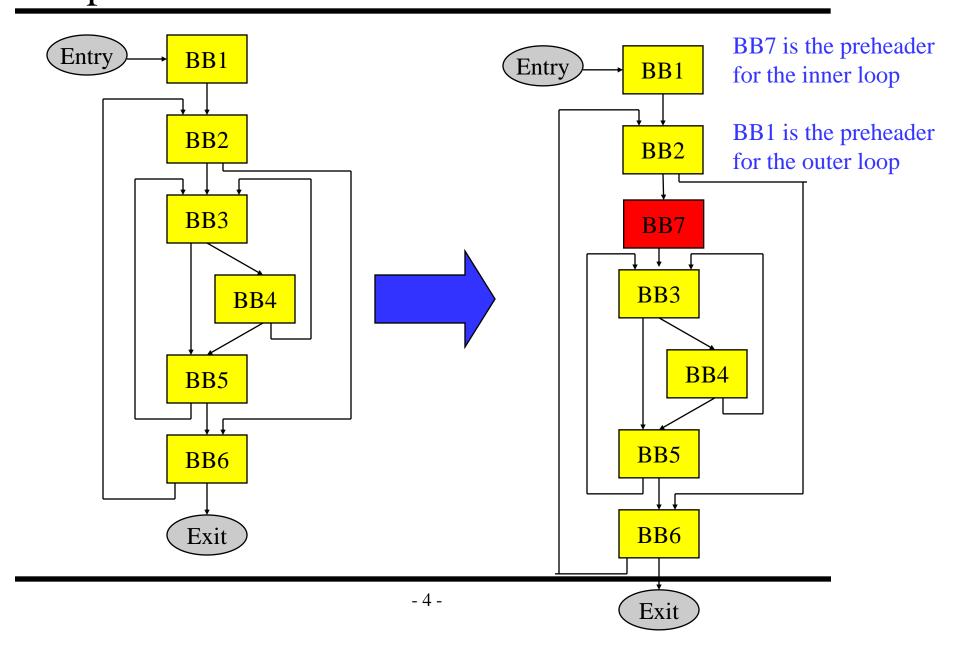
Announcements 2

- Optional EECS 583 WhatsApp group
 - » Zephaniah Hill organizing
 - » Purpose: Arrange group study sessions and discussions.
 - » To set up: Need WhatsApp and have your number attached to a WhatsApp account.
 - » To join: Contact Zephaniah at 219-742-4398. Please identify that you are from EECS 583 and wish to be added to the WhatsApp group.

From Last Time: Loop Detection

- Identify all backedges using Dom info
- \bullet Each backedge (x \rightarrow y) defines a loop
 - » Loop header is the backedge target (y)
 - » Loop BB basic blocks that comprise the loop
 - All predecessor blocks of x for which control can reach x without going through y are in the loop
- Merge loops with the same header
 - » I.e., a loop with 2 continues
 - » LoopBackedge = LoopBackedge1 + LoopBackedge2
 - » LoopBB = LoopBB1 + LoopBB2
- Important property
 - » Header dominates all LoopBB

From Last Time: Find the Preheaders for each Loop

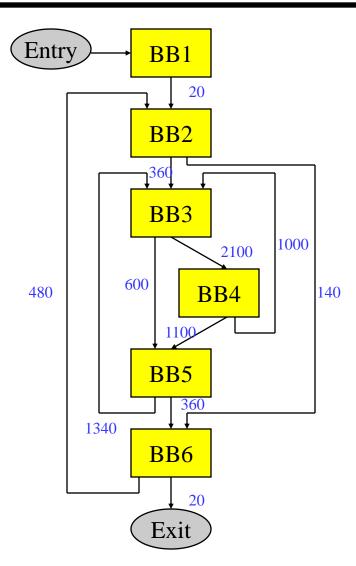


Characteristics of a Loop

- Nesting (generally within a procedure scope)
 - » Inner loop Loop with no loops contained within it
 - Outer loop Loop contained within no other loops
 - » Nesting depth
 - depth(outer loop) = 1
 - depth = depth(parent or containing loop) + 1
- Trip count (average trip count)
 - » How many times (on average) does the loop iterate
 - » for (i=0; i<100; i++) \rightarrow trip count = 100
 - » With profile info:
 - Ave trip count = weight(header) / weight(preheader)

Trip Count Calculation Example

Calculate the trip counts for all the loops in the graph



Reducible Flow Graphs

- * A flow graph is <u>reducible</u> if and only if we can partition the edges into 2 disjoint groups often called forward and back edges with the following properties
 - » The forward edges form an acyclic graph in which every node can be reached from the Entry
 - » The back edges consist only of edges whose destinations dominate their sources
- More simply Take a CFG, remove all the backedges
 (x→ y where y dominates x), you should have a
 connected, acyclic graph

Non-reducible!

Regions

- Region: A collection of operations that are treated as a single unit by the compiler
 - » Examples
 - Basic block
 - Procedure
 - Body of a loop
 - » Properties
 - Connected subgraph of operations
 - Control flow is the key parameter that defines regions
 - Hierarchically organized

Problem

- » Basic blocks are too small (3-5 operations)
 - Hard to extract sufficient parallelism
- » Procedure control flow too complex for many compiler xforms
 - Plus only parts of a procedure are important (90/10 rule)

Regions (2)

Want

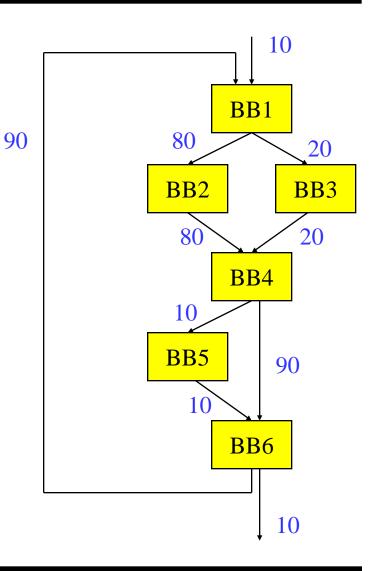
- » Intermediate sized regions with simple control flow
- » Bigger basic blocks would be ideal !!
- » Separate important code from less important
- » Optimize frequently executed code at the expense of the rest

Solution

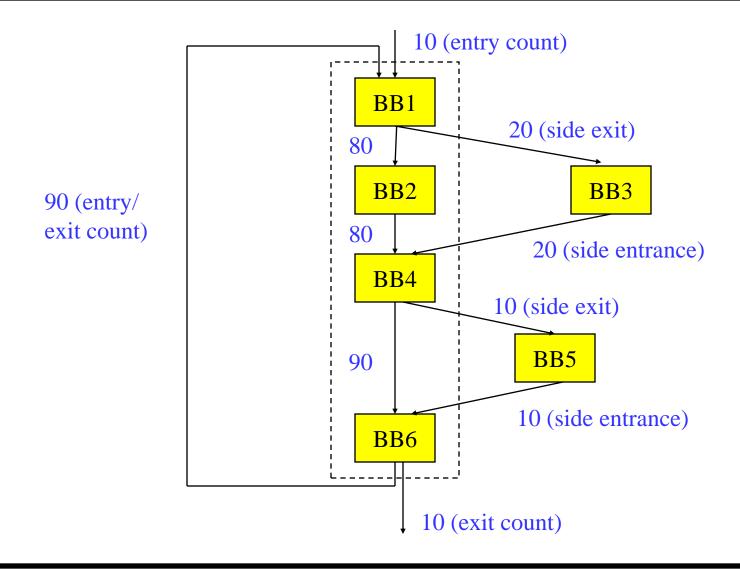
- » Define new region types that consist of multiple BBs
- » Profile information used in the identification
- » Sequential control flow (sorta)
- » Pretend the regions are basic blocks

Region Type 1 - Trace

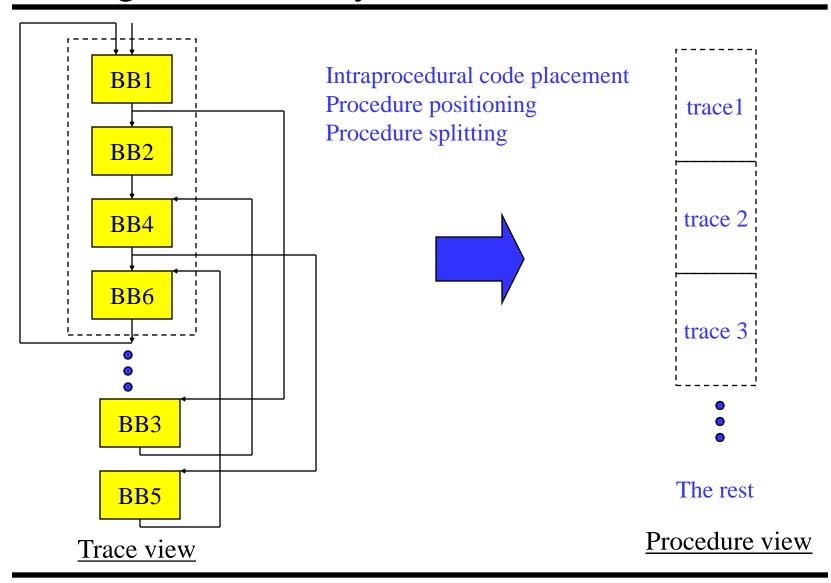
- Trace Linear collection of basic blocks that tend to execute in sequence
 - "Likely control flow path"
 - » Acyclic (outer backedge ok)
- Side entrance branch into the middle of a trace
- Side exit branch out of the middle of a trace
- Compilation strategy
 - » Compile assuming path occurs 100% of the time
 - » Patch up side entrances and exits afterwards
- Motivated by scheduling (i.e., trace scheduling)



Linearizing a Trace

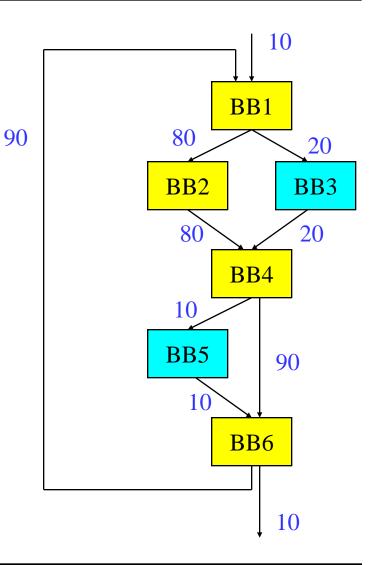


Intelligent Trace Layout for Icache Performance



Issues With Selecting Traces

- Acyclic
 - » Cannot go past a backedge
- Trace length
 - » Longer = better ?
 - » Not always!
- On-trace / off-trace transitions
 - » Maximize on-trace
 - » Minimize off-trace
 - » Compile assuming on-trace is 100% (ie single BB)
 - » Penalty for off-trace
- Tradeoff (heuristic)
 - » Length
 - » Likelihood remain within the trace



Trace Selection Algorithm

```
i = 0;
mark all BBs unvisited
while (there are unvisited nodes) do
     seed = unvisited BB with largest execution freq
     trace[i] += seed
     mark seed visited
     current = seed
     /* Grow trace forward */
     while (1) do
       next = best_successor_of(current)
       \underline{if} (next == 0) \underline{then} break
        trace[i] += next
        mark next visited
        current = next
     endwhile
     /* Grow trace backward analogously */
     i++
endwhile
```

Best Successor/Predecessor

- Node weight vs edge weight
 - » edge more accurate

* THRESHOLD

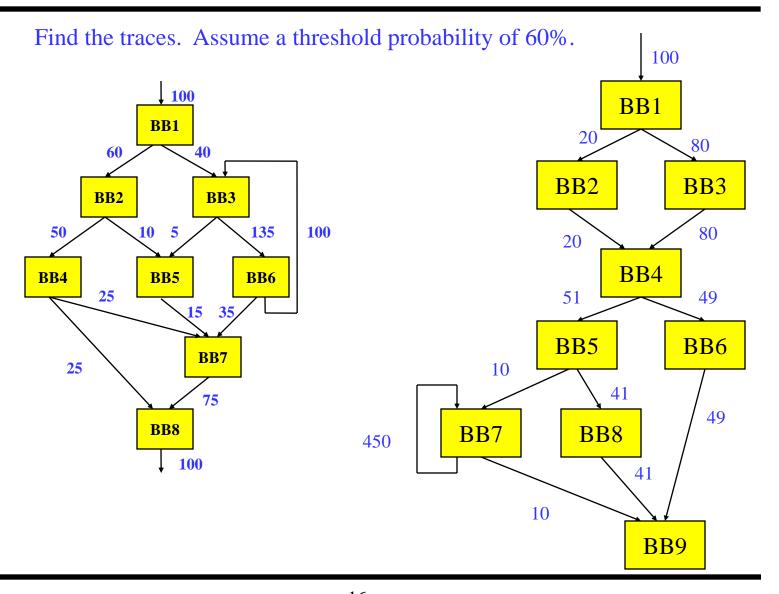
- » controls off-trace probability
- » 60-70% found best

Notes on this algorithm

- » BB only allowed in 1 trace
- » Cumulative probability ignored
- » Min weight for seed to be chose (ie executed 100 times)

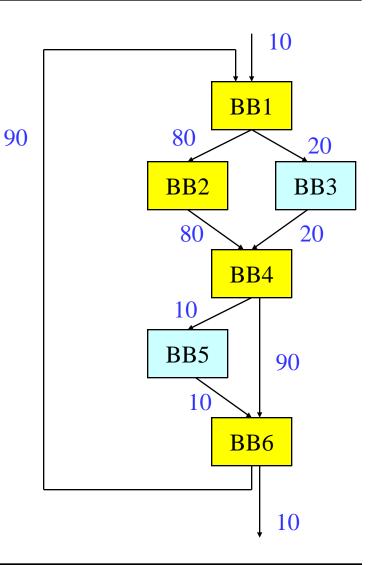
```
best_successor_of(BB)
  e = control flow edge with highest
      probability leaving BB
  if (e is a backedge) then
     return 0
  endif
  <u>if</u> (probability(e) <= THRESHOLD) <u>then</u>
     return 0
  endif
  d = destination of e
  if (d is visited) then
     return 0
  endif
  return d
end procedure
```

Class Problems



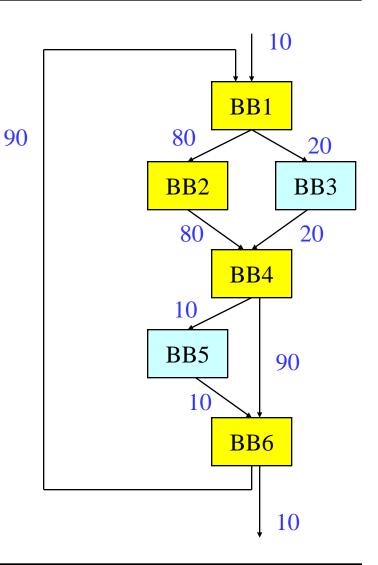
Traces are Nice, But ...

- Treat trace as a big BB
 - » Transform trace ignoring side entrance/exits
 - » Insert fixup code
 - aka bookkeeping
 - » Side entrance fixup is more painful
 - » Sometimes not possible so transform not allowed
- Solution
 - » Eliminate side entrances
 - » The <u>superblock</u> is born



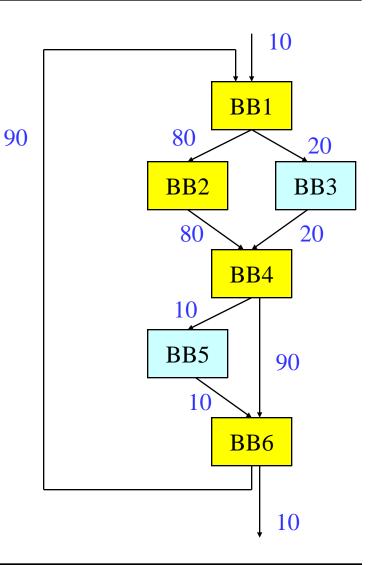
Region Type 2 - Superblock

- Superblock Linear collection of basic blocks that tend to execute in sequence in which control flow may only enter at the first BB
 - "Likely control flow path"
 - » Acyclic (outer backedge ok)
 - » Trace with no side entrances
 - » Side exits still exist
- Superblock formation
 - » 1. Trace selection
 - » 2. Eliminate side entrances

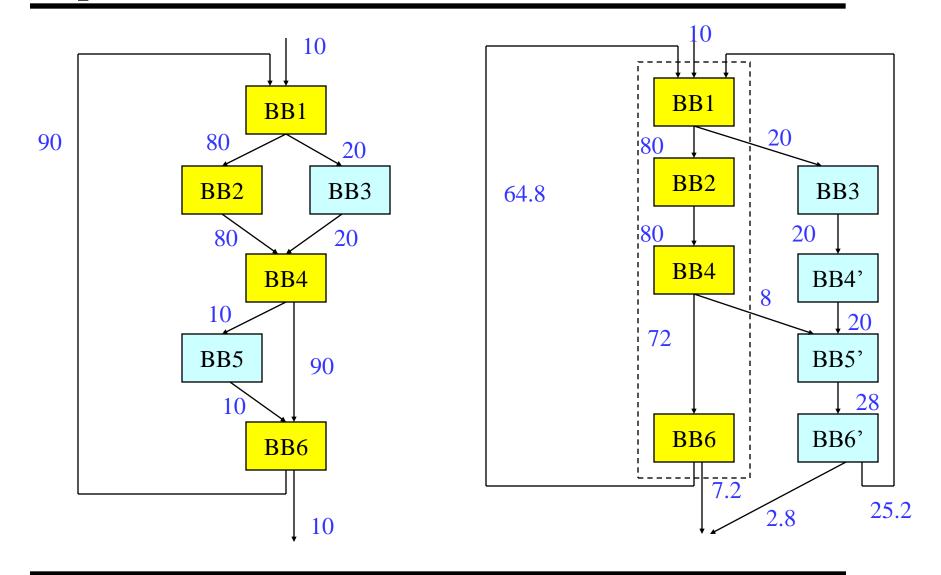


Tail Duplication

- To eliminate all side entrances replicate the "tail" portion of the trace
 - » Identify first side entrance
 - » Replicate all BB from the target to the bottom
 - » Redirect all side entrances to the duplicated BBs
 - » Copy each BB only once
 - » Max code expansion = 2x-1 where x is the number of BB in the trace
 - » Adjust profile information



Superblock Formation



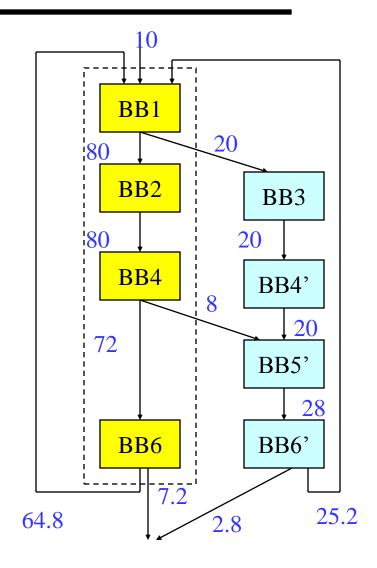
Issues with Superblocks

Central tradeoff

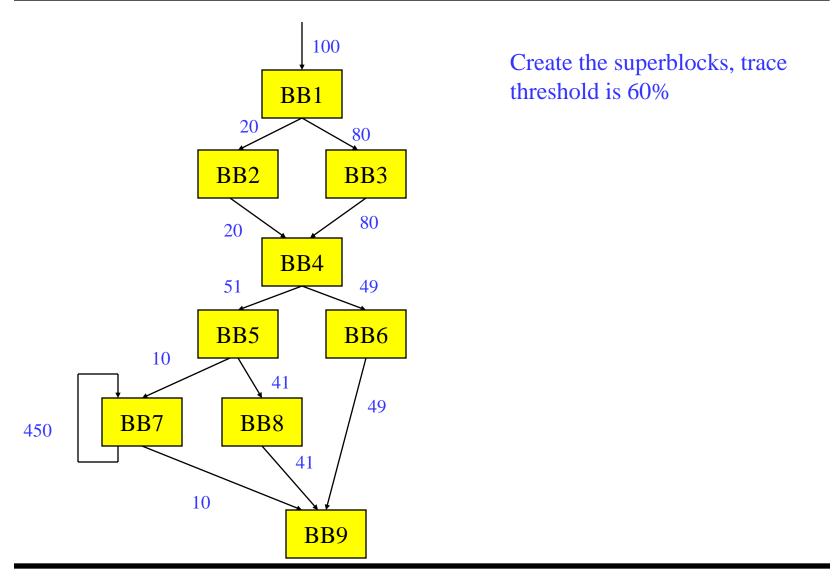
- » Side entrance elimination
 - Compiler complexity
 - Compiler effectiveness
- » Code size increase

Apply intelligently

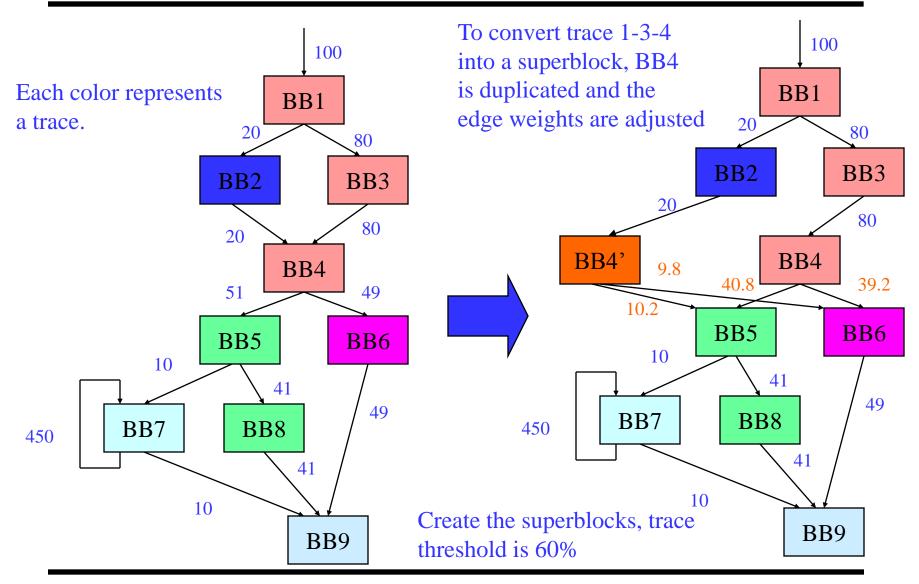
- » Most frequently executed BBs are converted to SBs
- » Set upper limit on code expansion
- 1.0 1.10x are typical code expansion ratios from SB formation



Class Problem



Class Problem Solution – Superblock Formation



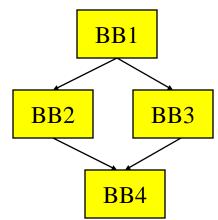
An Alternative to Branches: Predicated Execution

- Hardware mechanism that allows operations to be conditionally executed
- Add an additional boolean source operand (predicate)
 - » ADD r1, r2, r3 if p1
 - if (p1 is True), r1 = r2 + r3
 - else if (p1 is False), do nothing (Add treated like a NOP)
 - p1 referred to as the guarding predicate
 - Predicated on True means always executed
 - Omitted predicated also means always executed
- Provides compiler with an alternative to using branches to selectively execute operations
 - » If statements in the source
 - » Realize with branches in the assembly code
 - » Could also realize with conditional instructions
 - » Or use a combination of both

Predicated Execution Example

```
a = b + c
if (a > 0)
e = f + g
else
e = f / g
h = i - j
```

BB1 add a, b, c
BB1 bgt a, 0, L1
BB3 div e, f, g
BB3 jump L2
BB2 L1: add e, f, g
BB4 L2: sub h, i, j



Traditional branching code

$$p2 \rightarrow BB2$$

$$p3 \rightarrow BB3$$

BB1 add a, b, c if T BB1 p2 = a > 0 if T BB1 p3 = a <= 0 if T BB3 div e, f, g if p3 BB2 add e, f, g if p2 BB4 sub h, i, j if T

BB1 BB2 BB3 BB4

Predicated code

What About Nested If-then-else's?

a = b + c if $(a > 0)$	BB1 BB1	add a, b, c bgt a, 0, L1		BB1
if (a > 25) $e = f + g$	BB3	div e, f, g	DE	DD2
else	BB3 BB2	jump L2 L1: bgt a, 25, L3	BE	BB3
e = f * g else	BB6 BB6	mpy e, f, g jump L2	BB5	BB6
e = f / g $h = i - j$	BB5 BB4	L3: add e, f, g L2: sub h, i, j		
v	704	L2. Suo 11, 1, j		BB4

Traditional branching code

Nested If-then-else's – No Problem

a = b + c	BB1	add a, b, c if T	
if $(a > 0)$	BB1	p2 = a > 0 if T	BB1
if $(a > 25)$	BB1	$p3 = a \le 0 \text{ if } T$	BB2
e = f + g	BB3	div e, f, g if p3	BB3
else	BB3	p5 = a > 25 if p2	BB4
e = f * g	BB3	$p6 = a \le 25 \text{ if } p2$	BB5
else	BB6	mpy e, f, g if p6	BB6
e = f / g	BB5	add e, f, g if p5	DD 0
h = i - j	BB4	sub h, i, i if T	

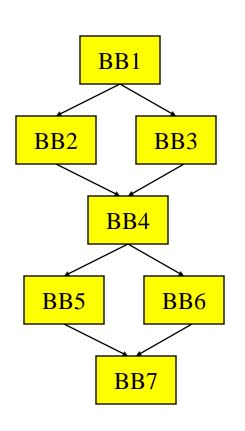
Predicated code

What do we assume to make this work ??

if p2 is False, both p5 and p6 are False

So, predicate setting instruction should set result to False if guarding predicate is false!!!

Benefits/Costs of Predicated Execution



BB1 BB2 BB3 BB4 BB5 BB6 BB7

Benefits:

- No branches, no mispredicts
- Can freely reorder independent operations in the predicated block
- Overlap BB2 with BB5 and BB6

Costs (execute all paths)

- -worst case schedule length
- -worst case resources required

HPL-PD Compare-to-Predicate Operations (CMPPs)

- How do we compute predicates
 - » Compare registers/literals like a branch would do
 - » Efficiency, code size, nested conditionals, etc
- 2 targets for computing taken/fall-through conditions with
 1 operation

```
p1, p2 = CMPP.cond.D1a.D2a (r1, r2) if p3

p1 = first destination predicate
p2 = second destination predicate
cond = compare condition (ie EQ, LT, GE, ...)
D1a = action specifier for first destination
D2a = action specifier for second destination
(r1,r2) = data inputs to be compared (ie r1 < r2)
p3 = guarding predicate
```

CMPP Action Specifiers

Guarding predicate	Compare Result	UN	UC	ON	OC	AN	AC
0	0	0	0	_	_		
0	1	0	0	- 2	_	_	1
1	0	0	1	_	1	0	-
1	1	1	0	1	-	-	0

UN/UC = Unconditional normal/complement

This is what we used in the earlier examples

guard = 0, both outputs are 0

guard = 1, UN = Compare result, UC = opposite

ON/OC = OR-type normal/complement

AN/AC = AND-type normal/complement

OR-type, AND-type Predicates

$$p1 = (r1 < r2) | (!(r3 < r4)) |$$

(r5 < r5)

Wired-OR into p1

Generating predicated code for some source code requires OR-type predicates

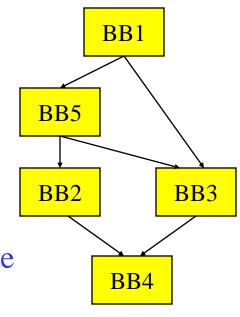
$$p1 = (r1 < r2) & (!(r3 < r4)) & (r5 < r5)$$

Wired-AND into p1

Talk about these later – used for control height reduction

Use of OR-type Predicates

$$a = b + c$$
if $(a > 0 & b > 0)$
 $e = f + g$
else
 $e = f / g$
 $h = i - j$



p2	\rightarrow	BB2
p 3	\rightarrow	BB3
p5	\rightarrow	BB5

BB1 BB5 BB2 BB3 BB4

Predicated code

Homework Problem – Answer Next Time

```
if (a > 0) {
    if (b > 0)
        r = t + s
    else
        u = v + 1
    y = x + 1
}
```

- a. Draw the CFG
- b. Predicate the code removing all branches