| EECS 598: Prediction and Learning: It's Only a Game | Fall 2013 |
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| Lecture 8: Game Theory III |  |
| Prof. Jacob Abernethy |  |

## Announcements

- Moving 10/16 class. Possible candidates:
- 9:30am-11:ooam (3 students unavailable)
- Relocate to central campus at usual time (4 students unavailable)
- Class participation credit may be satisfied in the following ways:
- Scribing ( $50 \%+50 \%$ for an additional scribe)
- Solving a challenge problem (5-20\% depending on difficulty of problem and/or quality of solution)
- Presenting homework solutions ( $10 \%$ )
- Presenting final project (50\%)
- On scribe notes...
- Notes are expected back 3 business days from original lecture
- Sign-up sheet for scribing is posted on CTools
- Notes on proof of Nash's Theorem posted on course website


## An Observation on Nash's Theorem

Given a bimatrix game $(A, B)$, we would like to define the map $(x, y) \mapsto\left(x^{\prime}, y^{\prime}\right)$ such that

$$
\begin{equation*}
x^{\prime}=\underset{x}{\arg \max } x^{\top} A y \quad \text { and } \quad y^{\prime}=\underset{y}{\arg \max } x^{\top} B y . \tag{8.1}
\end{equation*}
$$

We would like to use Brouwer's fixed point theorem to prove that there exists some $(x, y)$ which maps to itself. However, the mapping we have defined is not continuous. Yet, for some small $\epsilon>0$, we may define a mapping $(x, y) \mapsto\left(x^{\prime}, y^{\prime}\right)$ such that

$$
x^{\prime}=\underset{x}{\arg \max } x^{\top} A y-\epsilon\|x\|^{2} \quad \text { and } \quad y^{\prime}=\underset{y}{\arg \max } x^{\top} B y-\epsilon\|y\|^{2} .
$$

In this case, the mapping is continuous and Brouwer applies. We may then regard any fixed point, $\left(x^{\epsilon}, y^{\epsilon}\right)$, of this mapping as an " $\epsilon$-optimal" Nash equilibrium pair. Now, we should be able to take some sequence of $\epsilon$ values which converge to zero and argue that there exists a fixed point in the limiting case of equation ??.

Exercise: Formalize and prove (or disprove) the arguments given above.

## Von Neumann's Minimax Theorem

Let $p$ take values in $\Delta_{n}$, let $q$ take values in $\Delta_{m}$, and let $M \in[0,1]^{n \times m}$. Then

$$
\begin{equation*}
\min _{p} \max _{q} p^{\top} M q=\max _{q} \min _{p} p^{\top} M q \tag{8.2}
\end{equation*}
$$

### 8.1 Proof of " $\geq$ "

This part of the proof is trivial. To see this, consider the right hand side of ??. Let us regard $p$ as a function of $q$ where

$$
\begin{equation*}
p(q)=\min _{p} p^{\top} M q . \tag{8.3}
\end{equation*}
$$

Informally, we may regard the value of ?? as the value obtained from $p$ 's best strategy given $q$ 's strategy. Similarly, we may regard the left hand side of ?? as the value achieved from q's best strategy given $p$ 's strategy. Now, since $q$ can do no worse upon observing $p$ 's strategy than it could if it had to choose a strategy beforehand, it follows that the LHS of equation ?? meets or exceeds the RHS.

### 8.2 Alternate Formulation of " $\geq$ " Proof

The LHS of equation ?? is the smallest $c_{1}$ such that

$$
\begin{equation*}
\exists p \forall q: p^{\top} M q \leq c_{1} . \tag{8.4}
\end{equation*}
$$

However, the RHS of equation ?? is the smallest $c_{2}$ such that

$$
\begin{equation*}
\forall q \exists p: p^{\top} M q \leq c_{2} . \tag{8.5}
\end{equation*}
$$

Let $p *$ be any strategy which achieves the minimum value in ??. Then we must have $c_{1} \geq c_{2}$ since we may always play $p *$ in response to any $q$ in ??.

## Linear Programming Connections

Consider a linear program which seeks to minimize $c$ over variables $c$ and $p \in \Delta_{n}$ subject to the constraints:

$$
p^{\top} M e_{j} \leq c \quad j=1, \ldots, m
$$

where $M \in[0,1]^{n \times m}$. This is equivalent to finding the value of $c_{1}$ in ??. Note that we do not need explicit constraints for every $q \in \Delta_{m}$; we only need to consider the corners of the simplex. One can show that the dual LP is equivalent to the max-min formulation.

### 8.3 General LP's

For given vectors $d$ and $b$ and matrix $A$, we seek the maximum value of $d^{\top} x$ over $x$ subject to the constraint that $A x \leq b$ and $x \geq 0$. If we allow these constraints to be broken with infinite cost, then we may instead seek

$$
\max _{x \geq 0} \min _{y \geq 0} d^{\top} x+y^{\top}(b-A x) .
$$

Thus, if any entry of $A x$ exceeds $b$, then $y$ may be arbitrarily large such that the sum diverges to $-\infty$. Now, in cases where strong duality holds, we may write

$$
\begin{aligned}
\max _{x \geq 0} \min _{y \geq 0} d^{\top} x+y^{\top}(b-A x) & =\min _{y \geq 0} \max _{x \geq 0} d^{\top} x+y^{\top}(b-A x) \\
& =\min _{y \geq 0} \max _{x \geq 0}\left(d-y^{\top} A\right) x+y^{\top} b
\end{aligned}
$$

This invokes the dual LP which seeks to minimize $y^{\top} b$ subject to the constraint that $y^{\top} A \geq d$ and $y \geq 0$.

Note: It has been shown that LP strong duality is equivalent to minimax duality [?].

## Exponential Weights Algorithm with Gains

Consider EWA in the setting where money can always be made. We observe a sequence of gain vectors $g^{1}, \ldots, g^{T} \in[0,1]^{N}$. Let $g_{i}^{t}=$ money earned for action $i$ on round $t$. In this setting, we have

$$
\begin{equation*}
\operatorname{regret}_{T}=\max \sum_{t=1}^{T} g_{j}^{t}-\sum_{t=1}^{T} p^{t} \cdot g^{t} \tag{8.6}
\end{equation*}
$$

where $p^{t}$ is our strategy on round $t$. We assume that we can achieve some bound on regret which is sub-linear in $T$. In particular, we assume that our familiar bound $O(\sqrt{T \log N})$ holds. We then assign weights sequentially such that $w_{i}^{t+1}=w_{i}^{t} \exp \left(\eta g_{i}^{t}\right)$.

### 8.4 Proof of Strong Duality for Minimax Theorem

We shall now prove that $\min _{p} \max _{q} p^{\top} M q \leq \max _{q} \min _{p} p^{\top} M q+\epsilon$. However, we will see that this $\epsilon$ is inconsequential. Now, imagine that both players $P_{1}$ and $P_{2}$ play a game, each learning from the actions of the other. Then $P_{1}$ chooses $p^{1}, p^{2}, \ldots$ and $P_{2}$ chooses $q^{1}, q^{2}, \ldots$ according to the information available at each time step. Each $p^{t}$ is chosen by learning from loss vectors $\ell^{1}, \ldots, \ell^{t-1}$, where $\ell^{s}=M q^{s}$. Now, suppose at each time step, $P_{2}$ announces his strategy, $q^{t}$, to $P_{1}$. Our results will hold even when this is not the case, but this assumption will simplify our analysis. Now, we will have $q^{t}$ chosen according to $g^{1}, \ldots, g^{t-1}$, where $g^{s}=p^{s} M$. Let $\hat{q}^{T}=\frac{1}{T} \sum_{t=1}^{T} q^{t}$, the average strategy of $P_{2}$. We may now analyze the average payoffs

$$
\begin{aligned}
\frac{1}{T} \sum_{t=1}^{T}\left(p^{t}\right)^{\top} M q^{t} & =\frac{1}{T} \sum_{t=1}^{T} p^{t} \cdot \ell^{t} \\
& \leq \frac{1}{T} \min _{p} \sum_{t=1}^{T} p \cdot \ell^{t}+\frac{\operatorname{regret}_{T}}{T} \\
& =\min _{p} p^{\top} M \hat{q}^{T}+\epsilon_{T} \\
& \leq \max _{q} \min _{p} p^{\top} M q+\epsilon_{T}
\end{aligned}
$$

Here we have used $\epsilon_{T}:=\frac{\operatorname{regret}_{T}}{T}$ as a term that we can make vanish by increasing $T$.

Following a similar argument, with $\hat{p}^{T}=\frac{1}{T} \sum_{t=1}^{T} p^{t}$, we have

$$
\begin{aligned}
\frac{1}{T} \sum_{t=1}^{T}\left(p^{t}\right)^{\top} M q^{t} & \geq \frac{1}{T} \max _{q} \sum_{t=1}^{T} g^{t} \cdot q-\frac{\text { regret }_{T}}{T} \\
& =\max _{q}\left(\hat{p}^{T}\right)^{\top} M q-\epsilon_{T} \\
& \geq \min _{p} \max _{q} p^{\top} M q-\epsilon_{T}
\end{aligned}
$$

Combining these two chains of inequalities yields

$$
\min _{p} \max _{q} p^{\top} M q-2 \epsilon_{T} \leq \max _{q} \min _{p} p^{\top} M q .
$$

However, $T$ was arbitrary and so we may increase $T$ to make $\epsilon_{T}$ arbitrarily small. Taking the limit as $\epsilon_{T} \rightarrow 0$ implies that

$$
\min _{p} \max _{q} p^{\top} M q \leq \max _{q} \min _{p} p^{\top} M q
$$

## Observations:

1. $\hat{p}^{T}$ and $\hat{q}^{T}$ form a $2 \epsilon_{T}$-optimal Nash equilibrium pair. Let $v$ denote the value of the game. We then have

$$
\begin{aligned}
\max _{q} \hat{p}^{T} M q & \leq \max _{q} \min _{p} p^{\top} M q+2 \epsilon_{T} \\
& =v+2 \epsilon_{T}
\end{aligned}
$$

and

$$
\begin{aligned}
\min _{p} p^{\top} M \hat{q}^{T} & \geq \min _{p} \max _{q} p^{\top} M q-2 \epsilon_{T} \\
& =v-2 \epsilon_{T}
\end{aligned}
$$

and $2 \epsilon_{T}$-optimality holds.
2. Our proof had both players learning. Instead, if we have $q^{t}=\arg \max _{q} p^{t} M q$, then we get

$$
\begin{aligned}
\frac{1}{T} \sum_{t=1}^{T}\left(p^{t}\right)^{\top} M q^{t} & =\frac{1}{T} \sum_{t=1}^{T} \max _{q^{t}}\left(p^{t}\right)^{\top} M q^{t} \\
& \geq \frac{1}{T} \max _{q} \sum_{t=1}^{T}\left(p^{t}\right)^{\top} M q .
\end{aligned}
$$

The effect is that we drop the factor of two in the $2 \epsilon_{T}$ error bound.

## References

[1] Adler, Ilan. "The equivalence of linear programs and zero-sum games." International Journal of Game Theory 42, no. 1 (February 2013): 165-77. Accessed October 4, 2013. http://dx.doi.org/10.1007/soo182-012-0328-8.

