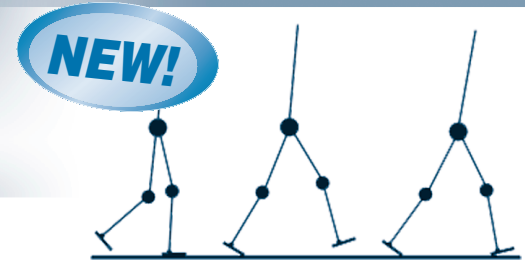


Feedback Control of Dynamic Bipedal Robot Locomotion

Explore Walking Robots from a Truly Dynamic Perspective



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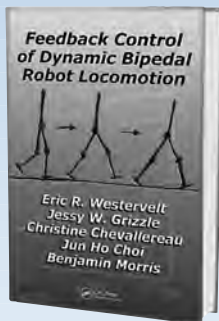
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