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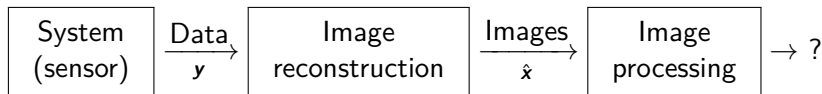
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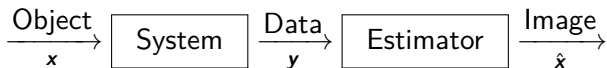


ICASSP Panel

2017-03-06



- ▶ Image reconstruction **goals**
 - ▶ Produce “better” images from same data
 - ▶ Produce “good” images from less data or noisier data (*cf.* data used by conventional algorithms)
- ▶ Image reconstruction challenges
 - ▶ Accurate physics/statistics models for system/sensor
 - ▶ Best/suitable **signal models**
 - ▶ Fast **computation / optimization**
 - ▶ Characterization / **performance guarantees**
- ▶ Image processing goals and challenges
 - ▶ ?



Typical “modern” formulation (MBIR) [1–5]:

$$\hat{\mathbf{x}} = \arg \min_{\mathbf{x}} \Psi(\mathbf{x}), \quad \Psi(\mathbf{x}) = -\log p(\mathbf{y} | \mathbf{x}) + R(\mathbf{x})$$

“Bayesian / variational / statistical / regularized / iterative / ...”

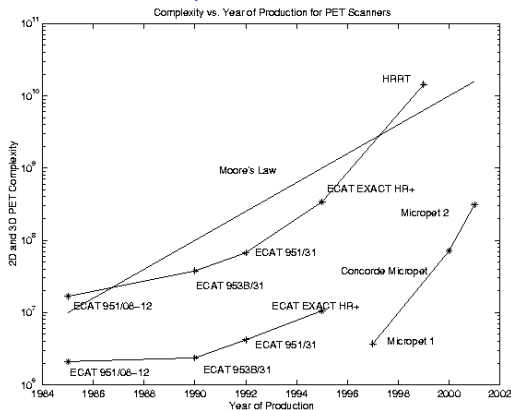
Active research topics:

- $p(\mathbf{y} | \mathbf{x})$: physics / statistics models (computation trade-offs)
- $R(\mathbf{x})$: regularizer / prior information / **signal models**
- $\arg \min$: **optimization algorithms**
- $\hat{\mathbf{x}}$: characterization / **performance guarantees**

(Clinical “breakthrough” ≈ 20 years ago in PET, ≈ 4 in CT, ≈ 0 from now in MRI)

What is the most important breakthrough in your field in the past 10 years and how did this affect your field?

1. Advances in **computing power** (but Moore's law insufficient)
⇒ **Clinical adoption of MBIR methods in PET and CT.**



(Courtesy of R. Leahy)

2. Advances in **optimization algorithms**

- ▶ incremental gradients / ordered subsets [6–8]
- ▶ non-smooth problems: (AL/ADMM, proximal splitting, majorization, ...) [9, 10]
- ▶ momentum methods (e.g., FISTA) [11, 12]
- ▶ non-convex problems (...)

⇒ OS made MBIR for PET clinically feasible.

3. Signal models based on **sparsity** (compressed sensing ...) [13–20]

⇒ **Emboldened research on highly under-sampled problems.**

“dynamic” = changing over time = motion [21–24]

▶ Nuisance motions:

- Breathing
- Cardiac
- Peristalsis
- Tremors
- Kids ...

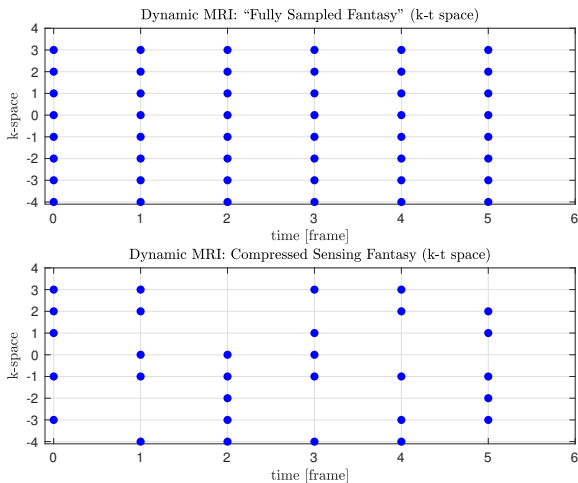
⇒ Faster scans (shorter time) can help reduce motion blur

▶ Motions of interest (true “dynamic” scans):

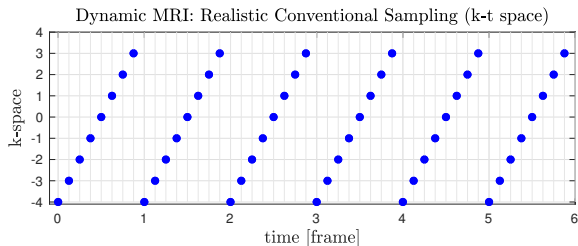
- Vocalization (for speech studies)
- Cardiac (for function)
- Joint articulation (musculoskeletal scans)
- Contrast agent (blood flow / perfusion)
- Diffusion

⇒ Trade-offs between temporal resolution and spatial resolution

Dynamic MRI sampling: Fantasy edition



- ▶ Scan "twice as fast" !?
- ▶ Matrix completion problem!? \implies ... robust PCA (L+S) ...
[25, 26]



- ▶ All 3D dynamic MRI data is *inherently under-sampled*
- ▶ No real “fully sampled” data exists, now or ever
- ▶ Unlikely to satisfy any “matrix completion” sufficient conditions (N measurements but N^2 unknowns per frame)
- ▶ Retrospective “under sampling” of “fully sampled” dynamic data is dubious
- ▶ Opportunity: powerful **signal models** needed for reconstruction from such data
- ▶ Challenge: validation of signal models given such highly incomplete data (low-rank / locally low rank / tensors / wavelets / non-local patches / ...)

- ▶ Edge-preserving roughness penalties / Markov random fields:

$$R(\mathbf{x}) = \beta \sum_{j=1}^{n_p} \sum_{k \in \mathcal{N}_j} \psi(x_j - x_k).$$

- ▶ Sparsity (analysis form): $R(\mathbf{x}) = \beta \|\mathbf{W}\mathbf{x}\|_1.$
- ▶ Sparsity (synthesis form): $\mathbf{x} = \mathbf{D}\mathbf{z}, \quad \|\mathbf{z}\|_0 \leq k, \quad \mathbf{D}$ “known”

$$R(\mathbf{x}) = \min_{\mathbf{z}} \beta \|\mathbf{x} - \mathbf{D}\mathbf{z}\|_2^2 + \alpha \|\mathbf{z}\|_p$$

- ▶ Sparsity of patches in adapted (learned) patch dictionary:

$$R(\mathbf{x}) = \min_{\mathbf{D} \in \mathcal{D}} \min_{\mathbf{Z}} \beta \sum_k \|\mathbf{P}_k \mathbf{x} - \mathbf{D}\mathbf{z}_k\|_2^2 + \alpha \|\mathbf{Z}\|_p$$

- ▶ Dynamic problems: low-rank / locally low-rank, tensors, ...

- ▶ **Analytical** reconstruction methods (classical):
idealized mathematical imaging system models [27]
e.g., CT inverse Radon transform, MR inverse FFT
- ▶ **Model-based** image reconstruction (“recent”):
 - ▶ physics and statistics models
 - ▶ mathematical signal models
- ▶ **Data-driven** image reconstruction (emerging):
parts of reconstruction algorithm learned from *training data*

- ▶ Training stage

Learn sparsifying transform $\hat{\Omega}$

from training data (image patches) $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \}$:

$$\hat{\Omega} \triangleq \arg \min_{\Omega} \min_{\mathbf{Z}} \sum_k \|\Omega \mathbf{x}_k - \mathbf{z}_k\|_2^2 + \lambda \|\mathbf{Z}\|_p.$$

Efficient methods with some convergence guarantees
Sai Ravishankar & Yoram Bresler, 2012-2015 [28–37].

- ▶ Image reconstruction stage:

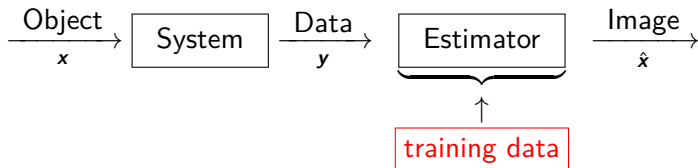
$$\arg \min_{\mathbf{x}} \Psi(\mathbf{x}), \quad \Psi(\mathbf{x}) \triangleq -\log p(\mathbf{y} | \mathbf{x}) + R(\mathbf{x})$$

$$R(\mathbf{x}) \triangleq \min_{\mathbf{Z}} \sum_j \left\| \hat{\Omega} \mathbf{P}_j \mathbf{x} - \mathbf{z}_j \right\|_2^2 + \lambda \|\mathbf{Z}\|_p.$$

Regularizer based on training data [38, 39] (!)

- ▶ Adaptive (blind) versions [40–44]
- ▶ Synthesis (dictionary) variant [45–47]

New paradigm:



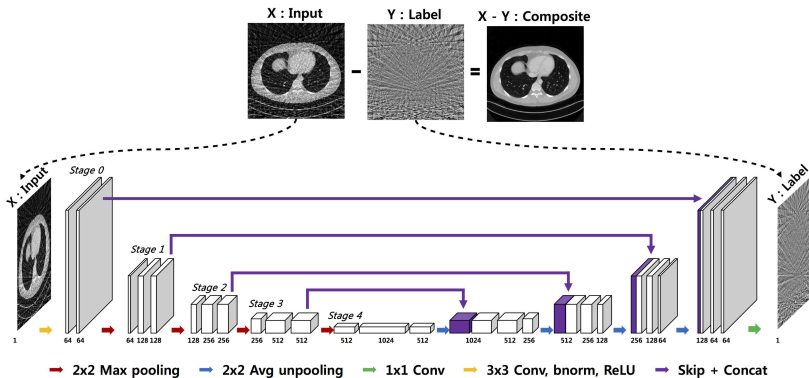
- ▶ Recent papers (mostly using “deep” convolutional neural networks): [48–57] (“deep imaging” ?)
- ▶ Many more to appear in 2017, e.g., [58].

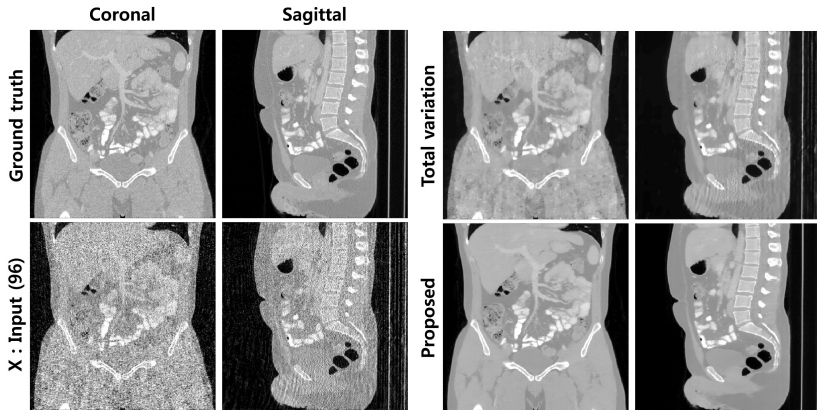
Data-driven image reconstruction: Example

Sparse-view CT “reconstruction” with learned streak removal

Han et al. 2016 [51]

Streak-estimation stages learned from (fully sampled) training data



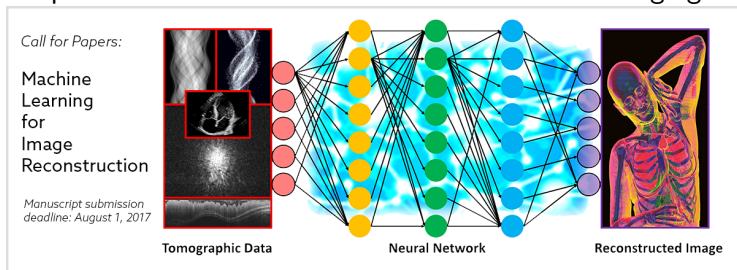


[51, Fig. 7], Han et al. 2016

- ▶ Slow learning from training data: $O(\text{days})$
(But very fast processing after training, *cf.* iterative MBIR)
- ▶ Re-training for different imaging conditions
- ▶ Non-convexity / nonlinearity
- ▶ Characterization / performance guarantees

(Job security for signal processors...)

Special issue of IEEE Transactions on Medical Imaging:



<https://ieeetmi.org>

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