

Homework #4, EECS 755, W13. Due **Wed. Nov. 13** by 5:00 PM

Solve #1 and at least two others. Problems labeled “(Solve?)” are ones where I have not yet worked out a solution.

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**Image restoration revisited**


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1. [10] Use circulant end conditions to synthesize a gaussian random field image like that in Fig. 1.7.1, for the 2D finite differencing matrix  $\mathbf{C}$  defined in (1.10.8).

Hint. The goal is to draw  $\mathbf{x} \sim \mathcal{N}(\mathbf{0}, \mathbf{K}_{\mathbf{x}})$ , so let  $\mathbf{x} = \mathbf{K}_{\mathbf{x}}^{1/2} \mathbf{w}$  where  $\mathbf{w} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ . In this case,  $\mathbf{K}_{\mathbf{x}} = [\mathbf{C}'\mathbf{C}]^{-1}$ . Because  $\mathbf{K}_{\mathbf{x}}$  is not invertible, use its pseudo inverse. Do *not* use the `pinv` command; use FFTs.

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**Optimization transfer / majorization**


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2. [10] From the perspective of algorithm development, is condition (12.1.3) more general, less general, or equivalent to condition (12.1.2)?

3. [10] Analyze the asymptotic convergence rate of a version of the steepest descent algorithm that uses just one subiteration of the line-search method described in §12.5.6. (Solve?)

4. [10] As described in §2.4.2, generalize the algorithm derived in Example 12.5.1 to a 2D problem with a rotationally-invariant penalty function of the form (2.4.3). Hint: use (12.4.15). (Using optimization transfer, this generalization is much simpler than in the half-quadratic approach [1].)

5. [10] Generalize the iterative soft-thresholding algorithm of Example 12.5.2 to the case of non-quadratic data-fit terms

$$\Psi(\mathbf{x}) = \sum_{i=1}^{n_d} h_i([\mathbf{A}\mathbf{x}]_i) + \beta \|\mathbf{U}'\mathbf{x}\|_1.$$

Make appropriate reasonable assumptions about the  $h_i$  functions.

6. [10] Apply the IST algorithm of Example 12.5.2 to a 2D image restoration problem with shift-invariant blur. Hint. One can modify `mri_cs_ist_example.m` to use `Gblur` instead of `Gdft`.

7. [10]

The standard *iterative soft thresholding (IST)* algorithm described in §12.5.7.3 is not applicable to a standard *total variation* type of regularizer  $\|\mathbf{C}\mathbf{x}\|_1$  because the usual choices for  $\mathbf{C}$  like  $\mathbf{D}_N$  in (1.8.4) are not invertible. However if we add one more row to  $\mathbf{D}_N$  as follows:  $\mathbf{C} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ & \mathbf{D}_N & & \end{bmatrix}$  then this matrix is invertible and its inverse is lower-triangular. Develop a IST algorithm for 1D problems with this regularizer. Does the principle generalize to 2D?

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[1] G. Aubert and L. Vese. A variational method in image recovery. *SIAM J. Numer. Anal.*, 34(5):1948–97, October 1997.