

Homework #1, EECS 755, W13. Due **Wed. Sep. 25** by 5:00 PM

Hand in solutions to any 5 of the following problems.

**Image restoration**

1. [10]

An image restoration method uses object model (1.3.6) with a 2D rectangular basis function:  $\beta_0(x, y) = \text{rect}_2(x/\Delta_x, y/\Delta_y)$ . The sensor is shift invariant with a rectangular blur:  $b(x, y) = \frac{1}{4\Delta_x\Delta_y} \text{rect}_2\left(\frac{x}{2\Delta_x}, \frac{y}{2\Delta_y}\right)$ . Assuming zero end conditions, determine the values of elements  $a_{ij}$  of the system matrix  $\mathbf{A}$ . Assume both the spacing of the sensor elements and the spacing of the object basis functions are  $(\Delta_x, \Delta_y)$ .

2. [10] If a matrix  $\mathbf{M}$  is square and circulant, then computing  $\mathbf{Q}\mathbf{M}\mathbf{Q}^{-1}$  will yield an exactly diagonal matrix, where  $\mathbf{Q}$  is the DFT matrix defined in (1.4.27). Consider the following four representations of a system matrix  $\mathbf{A}$ : (1.4.7), (1.4.9), (1.4.10), and (1.4.13). For each representation, using MATLAB to compute  $\mathbf{D} = \mathbf{Q}\mathbf{A}'\mathbf{A}\mathbf{Q}^{-1}$  for the impulse response  $b[n] = \delta[n-1] + 2\delta[n] + \delta[n+1]$  and for  $N = 64$ . (Hint: you can create each of the  $\mathbf{A}$  matrices needed in one or two lines of MATLAB using `convmtx`.) Display for yourself the  $\mathbf{D}$  matrices to visualize how close to diagonal they are. Compute the fractional off-diagonal “energy” as follows:

$$\frac{\sqrt{\sum_{k \neq j} |d_{kj}|^2}}{\sqrt{\sum_{k,j} |d_{kj}|^2}}.$$

Compare the four models using this quantitative measure of “non-circulant-ness.”

3. [10] For any  $n_p \times n_p$  unitary matrix  $\mathbf{U}$ , consider the penalized-likelihood cost function

$$\Psi(\mathbf{x}) = \frac{1}{2} \|\mathbf{y} - \mathbf{U}\mathbf{x}\|^2 + \beta \sum_{j=1}^{n_p} \psi(x_j).$$

- Defining  $\tilde{\mathbf{y}} = \mathbf{U}'\mathbf{y}$ , and using the fact that

$$\|\mathbf{y} - \mathbf{U}\mathbf{x}\|^2 = \|\mathbf{U}'\mathbf{y} - \mathbf{x}\|^2 = \sum_{j=1}^{n_p} |\tilde{y}_j - x_j|^2,$$

find an *analytical* solution for  $\hat{\mathbf{x}}$  in terms of  $\tilde{\mathbf{y}}$ , for the  $l_1$  regularized case where  $\psi(t) = |t|$ . Sketch  $\hat{x}_j$  vs  $\tilde{y}_j$ .

- Compare to the solution when an  $l_2$  penalty is used where  $\psi(t) = \frac{1}{2} |t|^2$ . Repeat for at least one more of the following potential functions.
- $l_0$  potential:  $\psi(t) = \mathbb{1}_{\{t \neq 0\}}$ .
- The truncated absolute value potential:  $\psi(t) = \min(|t|, \delta)$ .
- The broken parabola potential:  $\psi(t) = \min\left(\frac{1}{2} |t|^2, \frac{1}{2} \delta^2\right)$ .
- Huber potential (1.10.9).
- Generalized-gaussian potential (challenging!):  $\psi(t) = |t|^p$ , for  $p \neq 1$ . (Focus on  $p \in \{1/2, 4/3, 3/2, 2, 3, 4\}$  [2].)
- The hyperbola potential (challenging!):  $\psi(t) = \delta^2 (\sqrt{1 + |t/\delta|^2} - 1)$ .

This problem relates to wavelet-based *denoising* using *shrinkage* [3] and *soft thresholding* [4, 5].

4. [10] Let  $\mathbf{D}_N$  denote the  $(N-1) \times N$  one-dimensional finite-differencing matrix shown in (1.8.4), and  $\mathbf{I}_N$  denote the  $N \times N$  identity matrix. Show that the simple quadratic penalty (1.10.1) that uses only horizontal and vertical differences can be written in the form (1.10.7), where  $\mathbf{C}$  is the following  $[M(N-1) + N(M-1)] \times NM$  matrix:

$$\mathbf{C} = \begin{bmatrix} \mathbf{I}_M \otimes \mathbf{D}_N \\ \mathbf{D}_M \otimes \mathbf{I}_N \end{bmatrix}, \quad (\text{E1})$$

and “ $\otimes$ ” denotes the *Kronecker product* defined in (25.1.12).

5. [10]

For regularized restoration of a  $N \times M$  image using a penalty function  $R(\mathbf{x}) = \frac{1}{2} \|\mathbf{C}\mathbf{x}\|^2$ , one option is to use

$$\mathbf{C} = \begin{bmatrix} \mathbf{D}_{NM} \\ \mathbf{T} \end{bmatrix}, \quad (\text{E2})$$

where  $\mathbf{T}$  is an  $N(M-1) \times NM$  Toeplitz matrix with first row  $[-1 \mathbf{0}'_{N-1} \ 1 \ \mathbf{0}'_{NM-N-1}]$ , where  $\mathbf{0}'_N$  denotes the row vector of  $N$  zeros. Another option is to use  $\mathbf{C}$  defined in (E1). Using (E2) may be slightly faster (in ANSI C). Explain the advantage of using (E1).

6. [10] The 1D regularizer Hessian matrix in (1.8.6) has eigenvalues given in footnote 12.

Consider the 2D regularizer  $\mathbf{C}$  for a  $N \times M$  image given in (E1), and define the Hessian matrix  $\mathbf{R} = \mathbf{C}'\mathbf{C}$ . Determine analytically the eigenvalues of  $\mathbf{R}$ .

7. [10] This problem considers whether the penalized least-squares cost function  $\Psi(\mathbf{x})$  in (1.10.11) has a *unique minimizer* in the usual cases where  $\mathbf{A}$  and  $\mathbf{C}$  have *disjoint null spaces*.

- Prove that if the potential function  $\psi$  used in (1.10.11) is twice differentiable with a positive second derivative, then  $\Psi$  is strictly convex (and thus has a unique minimizer).
- What if  $\psi$  is strictly convex, but does not necessarily have a positive second derivative? An example would be  $\psi(t) = t^4$ .
- What if  $\psi$  is merely convex, like the Huber function? Hint: see Fig. 1.

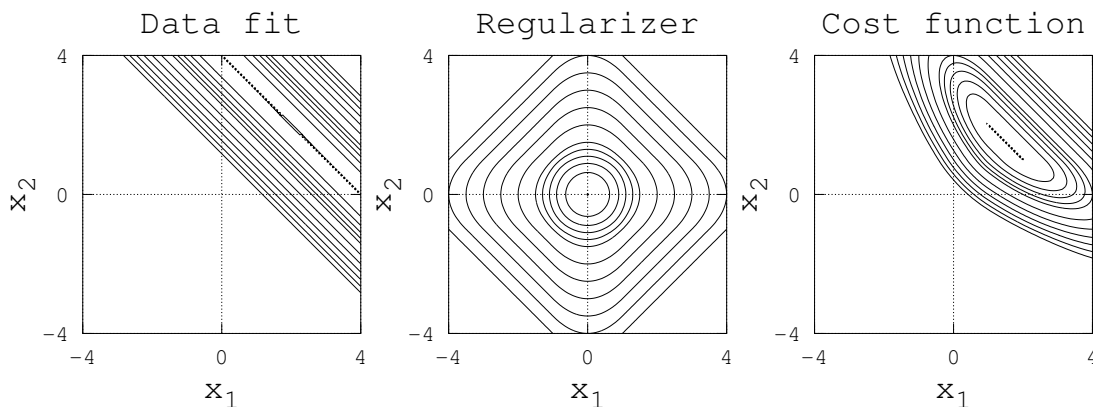


Figure 1: Contours of data fit term, regularizer, and cost function  $\Psi(\mathbf{x})$  for Problem 1.25.

8. [10]

Consider the regularized least-squares problem (1.10.11) with regularizer (1.10.10) and the usual 1st-order finite differencing matrix  $\mathbf{C}$ .

- Ken uses the generalized-gaussian potential function  $\psi(t) = |t|^q$  with  $q = 1.5$ , and states that the solution  $\hat{\mathbf{x}}$  satisfies the recursive expression (1.10.15). Discuss.
- Maria uses the Geman & McClure potential function  $\psi(t) = t^2/(1+t^2)$  and also states that the solution  $\hat{\mathbf{x}}$  satisfies the recursive expression (1.10.15). Discuss.

9. [10] Use circulant end conditions to synthesize a gaussian random field image like that in Fig. 1.7.1, for the 2D finite differencing matrix  $\mathbf{C}$  defined in (1.10.8).

Hint. The goal is to draw  $\mathbf{x} \sim \mathbf{N}(\mathbf{0}, \mathbf{K}_\mathbf{x})$ , so let  $\mathbf{x} = \mathbf{K}_\mathbf{x}^{-1/2} \mathbf{w}$  where  $\mathbf{w} \sim \mathbf{N}(\mathbf{0}, \mathbf{I})$ . In this case,  $\mathbf{K}_\mathbf{x} = [\mathbf{C}'\mathbf{C}]^{-1}$ . Because  $\mathbf{K}_\mathbf{x}$  is not invertible, use its pseudo inverse.

10. [10] Consider the discrete-space denoising problem with no boundary conditions and zero-mean white noise:

$$g[n] = f[n] + \varepsilon[n], \quad n \in \mathbb{Z},$$

Analyze the spatial resolution properties of the following quadratically-regularized denoising estimator for  $\beta > 0$ :

$$\hat{f} = \arg \min_{f \in \ell_2} \sum_{n=-\infty}^{\infty} \frac{1}{2} |g[n] - f[n]|^2 + \beta \sum_{n=-\infty}^{\infty} \frac{1}{2} |f[n] - f[n-1]|^2.$$

Hint. Using the DTFT, first find the frequency-domain relationship between  $E[\hat{f}]$  and  $f$ .

Optional: show that  $E[\hat{f}] = h * f$ , where the impulse response is

$$h[n] = ab^{|n|} = a e^{-|\log b||n|}, \quad b = \frac{1 + 2\beta - \sqrt{1 + 4\beta}}{2\beta} = \frac{2\beta}{1 + 2\beta + \sqrt{1 + 4\beta}},$$

where  $a = \frac{1+b^2}{1-b^2} \frac{1}{1+2\beta}$ . Note that  $0 < b < 1$ . Use §26.6.1. This is one of the few cases where we can find an explicit expression for the impulse response of a regularized problem [6, 7].

Determine the FWHM of the impulse response in terms of  $b$ .

11. [10] Find a matrix  $C$  such that when  $f(t) = \sum_{j=1}^{n_p} x_j \text{tri}(t-j)$ , we get equivalent values for the following continuous-space and discrete-space roughness penalty functions:

$$\int |f'|^2 dt = \|C\mathbf{x}\|^2.$$

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