

**Homework #11**

Due Date: Apr. 18, 2005

1. The following differential equations describe a casual, linear, time-invariant system. For each
  - i. Determine the poles and zeros. Is this system stable?
  - ii. Determine the partial fraction expansion or  $H(s)$ .
  - iii. Determine the impulse response,  $h(t)$ .

You may use the Matlab functions, `roots` and `residue`, to solve this problem. These are all real valued signals, so don't leave  $h(t)$  in terms of complex exponentials

- a. 
$$\frac{d^3 y}{dt^3} + 4 \frac{d^2 y}{dt^2} + 5 \frac{dy}{dt} + 2y = 2 \frac{d^3 x}{dt^3} - 8 \frac{d^2 x}{dt^2} + 10 \frac{dx}{dt} - 4x$$
- b. 
$$\frac{d^2 y}{dt^2} + 2 \frac{dy}{dt} + 5y = \frac{dx}{dt} + 1$$

2. O&W 10.21 (a-d,h)
3. O&W 10.23. Do only the right sided sequences, e.g. the 1<sup>st</sup>, 3<sup>rd</sup> and 5<sup>th</sup>  $X(z)$ .
4. O&W 10.28
5. O&W 10.29. Use Matlab to determine  $|H(\omega)|$  for  $\omega$  in  $[-\pi, \pi]$ . In each case, please try to sketch the shape of the  $|H(\omega)|$  prior to plotting with Matlab. You may use any Matlab tool you wish or write your own plotting program.
  - a. (i) Poles: 0, zeros:  $0.9e^{i\pi/4}$ ,  $0.9e^{-i\pi/4}$   
(ii) Poles: 0, zeros:  $0.5e^{i\pi/4}$ ,  $0.5e^{-i\pi/4}$
  - b. (i) Poles: 0, zeros: 0.9  
(ii) Poles: 0, zeros: 0.5
  - c. Poles:  $0.9e^{i\pi/3}$ ,  $0.9e^{-i\pi/3}$ , zeros:  $0.9e^{i\pi/4}$ ,  $0.9e^{-i\pi/4}$
  - d. (i) Poles: 0.9, -0.9  
(ii) Poles: 0.5, -0.5
  - e. (i) radius 0.9  
(ii) radius 0.5
6. For 6.a(i), 6.b(i), and 6.e(i). Determine (to within a constant scaling factor) the impulse response,  $h(n)$ . All three of these are real-valued, finite length sequences.
7. O&W 10.33. You may wish to use Matlab's `residue` function to solve this problem.