

APPLICATION: RAYLEIGH FADING CHANNEL

Goal | detect a sinusoid at a known frequency f_0 ,
 $0 < f_0 < 1/2$.

$$\left. \begin{array}{l} H_0: x(n) = w(n) \\ H_1: x(n) = A \cos(2\pi f_0 n + \phi) + w(n) \end{array} \right\} n=0,1,\dots,N-1$$

where $w(n) \stackrel{iid}{\sim} N(0, \sigma^2)$.

Assumptions

1. Time varying channel: A and ϕ are not fixed, but change with time due to moving transmitter/receiver or changing environmental conditions.

2. Multipath arrivals: Received signal is superposition of several versions of transmitted signal.

Examples | wireless comm, sonar

We have developed two general strategies for detection with unknown parameters, the Bayes Factor and GLRT.

Given our assumptions, the Bayesian approach makes more sense.

Observe

$$A \cos(2\pi f_0 n + \phi) = a \cos 2\pi f_0 n + b \sin 2\pi f_0 n$$

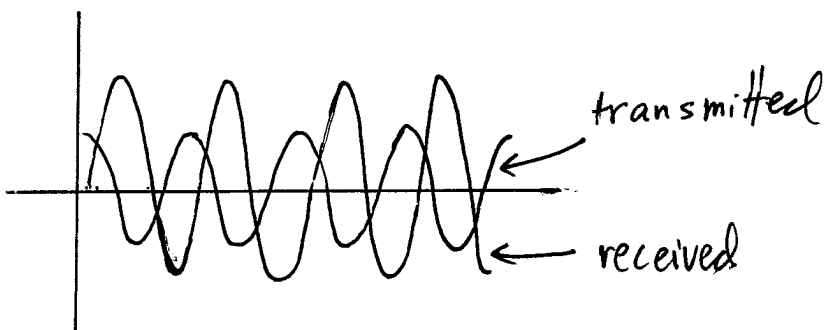
where

$$a = A \cos \phi, \quad b = A \sin \phi$$

Let's specify the following prior:

$$\underline{\theta} = \begin{bmatrix} a \\ b \end{bmatrix} \sim \mathcal{N} \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \tau^2 & 0 \\ 0 & \tau^2 \end{bmatrix} \right)$$

↑ due to many multipath arrivals
and appeal to central limit theorem



same frequency
different phase
and amplitude

The phrase "Rayleigh fading" comes from the fact that

$$A = \sqrt{a^2 + b^2}$$

has a Rayleigh distribution.

$$f(A) = \begin{cases} \frac{A}{\tau^2} \exp\left(-\frac{A^2}{2\tau^2}\right), & A > 0 \\ 0 & A < 0 \end{cases}$$

Also note

$$\phi = \arctan\left(-\frac{b}{a}\right) \sim \text{Uniform}[0, 2\pi]$$

Bayes Factor

$$\frac{f(\underline{x} | H_1)}{f(\underline{x} | H_0)} \stackrel{H_1}{\underset{H_0}{\gtrless}} \eta \quad \text{where}$$

$$f(\underline{x} | H_1) = \int f(\underline{x} | H_1, \underline{\theta}) f(\underline{\theta} | H_1) d\underline{\theta}$$

Exercise | (a) Determine $f(\underline{x} | H_1)$ (b) Use the MIL and a suitable approximation to simplify the detector (c) Interpret the detector (d) Choose threshold to ensure $P_F = \alpha$.

$$\text{MIL: } (A + BCD)^{-1} = A^{-1} - A^{-1}B(DA^{-1}B + C^{-1})^{-1}DA$$

Solution] (a) Writing $\underline{\theta} = \begin{bmatrix} a \\ b \end{bmatrix}$ and

$$H = \begin{bmatrix} 1 & 0 \\ \cos(2\pi f_0) & \sin(2\pi f_0) \\ \vdots & \vdots \\ \cos(2\pi f_0(N-1)) & \sin(2\pi f_0(N-1)) \end{bmatrix}$$

our model for H_1 is

$$H_1: \underline{x} = H\underline{\theta} + \underline{w}$$

where

$$\underline{\theta} \sim \mathcal{N}(\underline{0}, \tau^2 \mathbf{I}_{2 \times 2}), \quad \underline{w} \sim \mathcal{N}(\underline{0}, \sigma^2 \mathbf{I}_{N \times N})$$

↑ independent ↑

Therefore

$$\underline{x} = \begin{bmatrix} H & \mathbf{I} \end{bmatrix} \begin{bmatrix} \underline{\theta} \\ \underline{w} \end{bmatrix}$$

$$\sim \mathcal{N}(\underline{0}, \sigma^2 \mathbf{I}_{N \times N} + \tau^2 H H^T)$$

(b) log LRT :

$$-\frac{1}{2} \left[\underline{x}^T (\sigma^2 \mathbf{I} + \tau^2 \mathbf{H} \mathbf{H}^T)^{-1} \underline{x} - \underline{x}^T (\sigma^2 \mathbf{I})^{-1} \underline{x} \right] \underset{H_0}{\overset{H_1}{\gtrless}} \log \eta$$

Let's apply the matrix inversion lemma :

$$(\sigma^2 \mathbf{I} + \tau^2 \mathbf{H} \mathbf{H}^T)^{-1} = \frac{1}{\sigma^2} \mathbf{I} -$$

$$\frac{1}{\sigma^2} \mathbf{H} \left(\mathbf{H}^T \frac{1}{\sigma^2} \mathbf{I} \mathbf{H} + \frac{1}{\tau^2} \mathbf{I}_{2 \times 2} \right)^{-1} \mathbf{H}^T \cdot \left(\frac{1}{\sigma^2} \mathbf{I} \right)$$

Now $\mathbf{H}^T \mathbf{H} \approx \begin{bmatrix} N/2 & 0 \\ 0 & N/2 \end{bmatrix}$

exact when
 $f_0 = m/N$
approximate for
large N , otherwise

So $\frac{1}{\sigma^2} \mathbf{H}^T \mathbf{H} + \frac{1}{\tau^2} \mathbf{I}_{2 \times 2} = \begin{pmatrix} \frac{N}{2\sigma^2} + \frac{1}{\tau^2} & 0 \\ 0 & \frac{N}{2\sigma^2} + \frac{1}{\tau^2} \end{pmatrix}$

$\Rightarrow \left(\downarrow \right)^{-1} = \frac{1}{\frac{N}{2\sigma^2} + \frac{1}{\tau^2}} \mathbf{I}_{2 \times 2}$

$$\Rightarrow: \text{Log LRT} =$$

$$\frac{1}{2} \underline{x}^T \left(\frac{1}{\sigma^4} - \frac{1}{\frac{N}{2\sigma^2} + \frac{1}{\tau^2}} H H^T \right) \underline{x} \sum_{H_0}^{H_1} \log \eta$$

or

$$\underline{x}^T (H H^T) \underline{x} \sum_{H_0}^{H_1} \delta$$

$$\text{Now } \underline{x}^T (H H^T) \underline{x} = (H^T \underline{x})^T (H^T \underline{x})$$

$$= \| H^T \underline{x} \|^2$$

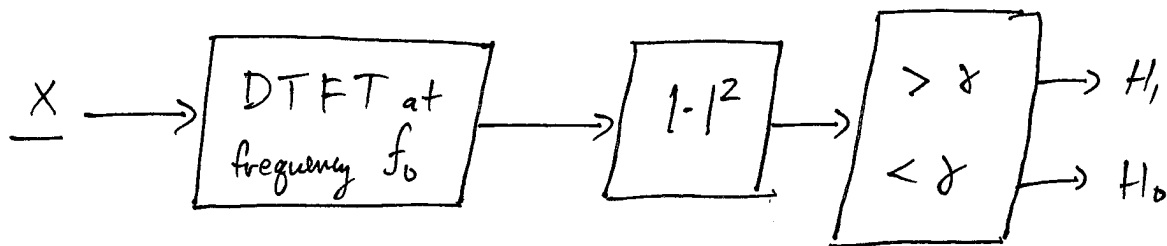
$$= \left\| \begin{bmatrix} \sum x(n) \cos(2\pi f_0 n) \\ \sum x(n) \sin(2\pi f_0 n) \end{bmatrix} \right\|^2$$

$$= \left(\sum x(n) \cos(2\pi n f_0) \right)^2 + \left(\sum x(n) \sin(2\pi n f_0) \right)^2$$

$$= \left| \sum x(n) e^{-i2\pi f_0 n} \right|^2$$

$$\equiv P(\underline{x})$$

(c) Interpretation: Optimal detector given by



Fast implementation possible with FFT.

(d) How should we set δ so that $P_F = \alpha$?

Observe $\sum x(n) \cos(2\pi f_0 n) \sim \mathcal{N}(0, \frac{N\sigma^2}{2})$

under H_0 .

Similarly, $\sum x(n) \sin(2\pi f_0 n) \sim \mathcal{N}(0, \frac{N\sigma^2}{2})$

under H_0 .

$$\Rightarrow \frac{2}{N\sigma^2} \Gamma(\underline{x}) \sim \chi^2_2$$

$$\Rightarrow P_F = \Pr \left\{ \Gamma(\underline{x}) > \delta \right\} = \Pr \left\{ \frac{2}{N\sigma^2} \Gamma(\underline{x}) > \frac{2}{N\sigma^2} \delta \right\}$$

$$= Q_{\chi^2_2} \left(\frac{2}{N\sigma^2} \delta \right) \Rightarrow \delta = \frac{\sigma^2 N}{2} Q_{\chi^2_2}^{-1}(\alpha)$$

Summary

- To detect a sinusoid with unknown phase/amplitude, just look at the magnitude (squared) of the frequency component.
- Test statistic and threshold independent of prior variance τ^2 .