

TOPICS FOR TODAY'S LECTURE

1. Discrete-Time Fourier Transform (DTFT)  
Relation to  $X(z)$  and Fourier Transform  $\mathcal{F}$
2. Frequency Response of LTI Systems
3. Notch (line reject) filters

Discrete-Time Fourier Transform (DTFT)

**DEF:**  $DTFT\{x[n]\} = X(e^{j\omega})$  where

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}.$$

1.  $X(e^{j\omega}) = X(z)|_{z=e^{j\omega}}$  (same  $X(\cdot)$ ).
2. **DTFT is periodic with period  $=2\pi$ !**  
This is why I use  $X(e^{j\omega})$ , not  $X(\omega)$ .  
Usually compute/plot for  $-\pi < \omega \leq \pi$ .

DTFT vs. Fourier Transform

**DTFT:**  $X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}.$

$\mathcal{F} : X(j\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt.$

**DTFT:**  $X(e^{j\omega}) = X(z)|_{z=e^{j\omega}}.$

$\mathcal{F} : X(j\omega) = X(s)|_{s=j\omega}.$

**Fact:**  $\mathcal{F}\{\sum x[n]\delta(t-n)\} = DTFT\{x[n]\}.$

Inverse DTFT vs. Fourier Series

**DEF:**  $x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})e^{j\omega n} d\omega.$

**Note:** Can use  $\int_{-\pi}^{\pi}$  or  $\int_0^{2\pi}$  or  $\int_p^{p+2\pi}$

**How:** Period  $= 2\pi \rightarrow$  expand  $X(e^{j\omega})$  as

a **Fourier series** with period  $2\pi$   
**where:**  $x[n]$  = Fourier series coefficients;  
compute using  $DTFT^{-1}$  formula.

DTFT vs.  $\mathcal{Z}$  vs.  $\mathcal{F}$  vs.  $\mathcal{L}$

Continuous	$\mathcal{L}$	$\Leftrightarrow$	$\mathcal{F}$	Discrete xform
$z = e^s$	$\Updownarrow$	$s = j\omega$	$\Updownarrow$	from Continuous
Discrete	$\mathcal{Z}$	$\Leftrightarrow$	DTFT	$\mathcal{F}\{\sum x[n]\delta(t-n)\}$
Time			$z = e^{j\omega}$	$\mathcal{L}\{\sum x[n]\delta(t-n)\}$

DTFT: PROPERTIES

1. **Periodic with period  $= 2\pi$ !**
2. If  $x[n]$  real, have **conjugate symmetry:**
  - a.  $|X(e^{j\omega})|$  &  $\text{real}[X(e^{j\omega})]$  even functions
  - b.  $\arg[X(e^{j\omega})]$  &  $\text{imag}[X(e^{j\omega})]$  odd funcs.
  - c.  $X(e^{-j\omega}) = X(e^{j\omega})^*$
  - d.  $DTFT[\text{real \& even}] = \text{real \& even}$
3.  $DTFT[x[n-D]] = X(e^{j\omega})e^{-j\omega D}$ ;  
Time delay  $\rightarrow$  linear phase shift.
4.  $DTFT[x[n]e^{j\omega_0 n}] = X(e^{j(\omega-\omega_0)})$ ;  
Modulation  $\rightarrow$  frequency shift

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### DTFT: EXAMPLES [1/2]

**Easiest:** Compute  $X(z)$ , then set  $z = e^{j\omega}$ .

**EX #1:**  $x[n] = \{\dots, 0, 0, 3, 1, \underline{4}, 2, 5, 0, 0, \dots\}$

**Soln:**  $X(e^{j\omega}) = 3e^{j2\omega} + 1e^{j\omega} + 4 + 2e^{-j\omega} + 5e^{-j2\omega}$ .

**Answer:**  $X(e^{j\omega}) = [4 + 3 \cos(\omega) + 8 \cos(2\omega)] - j[\sin(\omega) + 2 \sin(2\omega)]$ .

**using:**  $Ae^{j\omega} + Be^{-j\omega} = (A+B)\cos(\omega) + j(A-B)\sin(\omega)$  (Euler)

**Note:** Conjugate symmetry in  $X(e^{j\omega})$ .

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### DTFT: EXAMPLES [2/2]

**EX #2:**  $x[n] = a^n u[n] \rightarrow X(e^{j\omega}) = \frac{1}{1 - ae^{-j\omega}}$ .

**EX #3:**  $x[n] = a^n u[n] + b^n u[-n - 1]$  (2-sided).

$$\rightarrow X(e^{j\omega}) = \frac{e^{j\omega}}{e^{j\omega} - a} - \frac{e^{j\omega}}{e^{j\omega} - b} = \frac{b-a}{a+b-e^{j\omega}-abe^{-j\omega}}$$

**Need:**  $|a| < 1 < |b|$  or DTFT does not exist!

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### DTFT: APPLICATIONS

**Q:** So what is DTFT for?

**A:** Same things  $\mathcal{F}$  is for:

1. Signal spectra (next time)
  2. Frequency response (now)
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### FREQUENCY RESPONSE [1/2]

**Recall:**  $z_0^n \rightarrow \boxed{H(z)} \rightarrow H(z_0)z_0^n$ . Eigenfunction of LTI.

**Now:**  $z_0^n = e^{+j\omega_0 n} \rightarrow \boxed{H(z)} \rightarrow H(e^{+j\omega_0})e^{+j\omega_0 n}$ .

**and:**  $z_0^n = e^{-j\omega_0 n} \rightarrow \boxed{H(z)} \rightarrow H(e^{-j\omega_0})e^{-j\omega_0 n}$ .

**using:**  $H(e^{\pm j\omega_0}) = |H(e^{+j\omega_0})| \exp(\pm j \arg(H(e^{+j\omega_0})))$

$\cos(\omega_0 n) \rightarrow \boxed{H(z)} \rightarrow |H(e^{j\omega_0})| \cos(\omega_0 n + \arg[H(e^{j\omega_0})])$ .

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### FREQUENCY RESPONSE [2/2]

**Gain:** Amplitude increases by factor  $|H(e^{j\omega_0})|$ .

**Phase:** Shift by  $\arg[H(e^{j\omega_0})] = \tan^{-1} \frac{\text{Im}[H(e^{j\omega_0})]}{\text{Re}[H(e^{j\omega_0})]}$ .

**DTFT:**  $H(e^{j\omega_0}) = \sum h[n]e^{-j\omega_0 n} = DTFT[h[n]]$ .

**Zero:**  $H(z)$  has zero at  $e^{\pm j\omega_0} \rightarrow y[n] = 0$  (in SS).

**Pole:**  $H(z)$  has pole at  $e^{\pm j\omega_0} \rightarrow y[n] \rightarrow \infty$ .

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### FREQUENCY RESPONSE: EX #1

**System:**  $y[n] = \frac{1}{2}y[n-1] + x[n] \rightarrow h[n] = (\frac{1}{2})^n u[n]$ .

**Input:**  $x[n] = \{\dots, -1, 0, \underline{1}, 0, -1, \dots\} = \cos(\frac{\pi n}{2})$ .

$$\omega = \frac{\pi}{2}: H(e^{j\omega}) = \frac{1}{1 - \frac{1}{2}e^{-j\omega}} = \frac{1}{1 + \frac{1}{2}} = 0.89e^{-j26.6^\circ}$$

**Answer:**  $y[n] = 0.89 \cos(\frac{\pi n}{2} - 26.6^\circ)$   
 $= \{\dots, 0.8, 0.4, -0.8, -0.4, 0.8, 0.4, \dots\}$ .

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**FREQUENCY RESPONSE: EX #2**

**System:**  $y[n] = \frac{1}{2}y[n-1] - x[n] \rightarrow h[n] = (\frac{1}{2})^n u[n]$ .

**Input:**  $x[n] = \{ \dots - 1, \frac{1}{2}, -1, 1, -1, \dots \} = \cos(\pi n)$ .

$$\omega = \pi: H(e^{j\omega}) = \frac{1}{1 - \frac{1}{2}e^{-j\omega}} = \frac{1}{1 + \frac{1}{2}} = \frac{2}{3}.$$

**Answer:**  $y[n] = \frac{2}{3} \cos(\pi n) = \frac{2}{3}(-1)^n$ .

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**FREQUENCY RESPONSE: EX #3**

**System:**  $y[n] = \frac{1}{2}(x[n] + x[n-1]) \rightarrow h[n] = \{\frac{1}{2}, +\frac{1}{2}\}$ .

$$H(e^{j\omega}) = \frac{1}{2}(1 + e^{-j\omega}) = \cos(\frac{\omega}{2})e^{-j\omega/2}. \text{ Low-pass.}$$

**System:**  $y[n] = \frac{1}{2}(x[n] - x[n-1]) \rightarrow h[n] = \{\frac{1}{2}, -\frac{1}{2}\}$ .

$$H(e^{j\omega}) = \frac{1}{2}(1 - e^{-j\omega}) = \sin(\frac{\omega}{2})e^{j(\pi-\omega)/2}. \text{ High-pass.}$$

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**FREQUENCY RESPONSE: EX #4**

**System:**  $y[n] = x[n+1] - 2\cos(\omega_o)x[n] + x[n-1]$ .

$$h[n] = \{1, -2\cos(\omega_o), 1\}.$$

$$H(z) = z - 2\cos(\omega_o) + z^{-1} = (z - e^{j\omega_o})(z - e^{-j\omega_o}) \frac{1}{z}.$$

$$H(e^{j\omega}) = e^{j\omega} - 2\cos(\omega_o) + e^{-j\omega} = 2\cos(\omega) - 2\cos(\omega_o).$$

**Does:** This filter rejects  $\omega = \omega_o$ .

**Name:** *Notch* or line-reject filter.

**Delay:** Make causal: output delayed by one.

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**NOTCH FILTER: EXAMPLE #1**

**Given:** Lab sensors with wire leads

**Given:** DSP system with rate  $360 \frac{\text{SAMPLE}}{\text{SECOND}}$ .

**But:** 60 Hertz interference from walls

**Goal:** Design digital filter to eliminate.

**Soln:** Notch filter with  $\omega_o = 2\pi \frac{60}{360}$ .

**Need:**  $h[1] = -2\cos(2\pi \frac{60}{360}) = -1$

**Answer:**  $y[n] = x[n] - x[n-1] + x[n-2]$ .

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**NOTCH FILTER: EXAMPLE #2 [1/2]**

**Goal:** Filter to reject both 60 Hz and 120 Hz.

**Soln:** Use 2 notch filters in series or cascade.

**Need:**  $-2\cos(2\pi \frac{60}{360}) = -1$  and  $-2\cos(2\pi \frac{120}{360}) = 1$ .

**Soln:**  $h[n] = \{1, -1, 1\} * \{1, 1, 1\} = \{1, 0, 1, 0, 1\}$ .

**Answer:**  $y[n] = x[n] + x[n-2] + x[n-4]$ .

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**NOTCH FILTER: EXAMPLE #2 [2/2]**

Note the above  $H(z) = z^4 + z^2 + 1$  has

Zeros  $e^{\pm j2\pi(60/360)}$  and  $e^{\pm j2\pi(120/360)}$ .

Recall zeros at  $e^{\pm j\omega_o}$  rejects  $A \cos(\omega_o n + \theta)$ .

**Alternative:** Design filter to have these zeros:

$$H(z) = (z - e^{j2\pi \frac{60}{360}})(z - e^{-j2\pi \frac{60}{360}})(z - e^{j2\pi \frac{120}{360}})(z - e^{-j2\pi \frac{120}{360}})$$

$H(z) = z^4 + z^2 + 1$ . Divide by  $z^4 \Leftrightarrow$  delay by 4.

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